

YK500XG

Standard type: Medium type



- Arm length 500mm
- Maximum payload 10kg

Ordering method

YK500XG				RCX340-4								
Model	Z axis stroke 200: 200mm 300: 300mm	Tool flange No entry: None F: With tool flange	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery	

Specify various controller setting items. RCX340 ▶ **P.566**

Specifications

		X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length	200 mm	300 mm	200 mm 300 mm	—
	Rotation angle	+/-130 °	+/-145 °	—	+/-360 °
AC servo motor output		400 W	200 W	200 W	200 W
Deceleration mechanism	Transmission method	Direct-coupled			
	Motor to speed reducer Speed reducer to output	Direct-coupled			
Repeatability <small>Note 1</small>		+/-0.01 mm	+/-0.01 mm	+/-0.004 °	
Maximum speed		7.6 m/sec	2.3 m/sec	1.7 m/sec	1700 °/sec
Maximum payload		10 kg (Standard type), 9 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload <small>Note 2</small>		0.42 sec			
R-axis tolerable moment of inertia <small>Note 3</small>		0.30 kgm ²			
User wiring		0.2 sq × 20 wires			
User tubing (Outer diameter)		φ 6 × 3			
Travel limit		1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length		Standard: 3.5 m Option: 5 m, 10 m			
Weight		30 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
 Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
 Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1700	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
 See our robot manuals (installation manuals) for detailed information.
 Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
<https://global.yamaha-motor.com/business/robot/>

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