

YK900XGS

Wall-mount / inverse type

- Arm length 900mm
- Maximum payload 20kg

Ordering method

YK900XGS

Model	Installation method ^{Note 1}	Z axis stroke	Tool flange	Cable
	W: Wall-mount (same as per external view) I: Inverse wall-mount (upside down)	200: 200mm 400: 400mm	No entry: None F: With tool flange	3L: 3.5m 5L: 5m 10L: 10m

RCX340-4

Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ **P.508**

RCX240

Controller	CE Marking	Regenerative unit	Expansion I/O	Network option	IVY System	Gripper	Battery

Specify various controller setting items. RCX240/RCX240S ▶ **P.495**

Note 1. When installing the robot, always follow the specifications.
Do not install the ceiling-mount robot upside down or do not install the inverse type robot to a ceiling.
Incorrect installation can cause trouble or malfunction.

Specifications

Axis specifications	Arm length	X-axis	Y-axis	Z-axis	R-axis
Rotation angle		500 mm	400 mm	200 mm/400 mm	-
AC servo motor output		+/-130 °	+/-150 °	-	+/-360 °
Deceleration mechanism	Speed reducer	750 W	400 W	400 W	200 W
	Transmission	Harmonic drive	Harmonic drive	Ball screw	Harmonic drive
	Motor to speed reducer	Direct-coupled			
	Speed reducer to output	Direct-coupled			
Repeatability ^{Note 1}		+/-0.02 mm	+/-0.01 mm	+/-0.004 °	
Maximum speed		9.9 m/sec		2.3 m/sec	1.7 m/sec
Maximum payload		920 °/sec (wall-mount) 480 °/sec (inverse wall-mount)			
Standard cycle time: with 2kg payload ^{Note 2}		20 kg (Standard specification), 19 kg (Option specifications)			
R-axis tolerable moment of inertia ^{Note 3}		0.49 sec			
User wiring		1.0 kgm ²			
User tubing (Outer diameter)		0.2 sq × 20 wires			
Travel limit		φ 6 × 3			
Robot cable length		1. Soft limit 2. Mechanical stopper (X,Y,Z axis)			
Weight		Standard: 3.5 m Option: 5 m, 10 m			
		Z axis 200 mm: 54 kg Z axis 400 mm: 56 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. There are limits to acceleration coefficient settings. See P.539.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

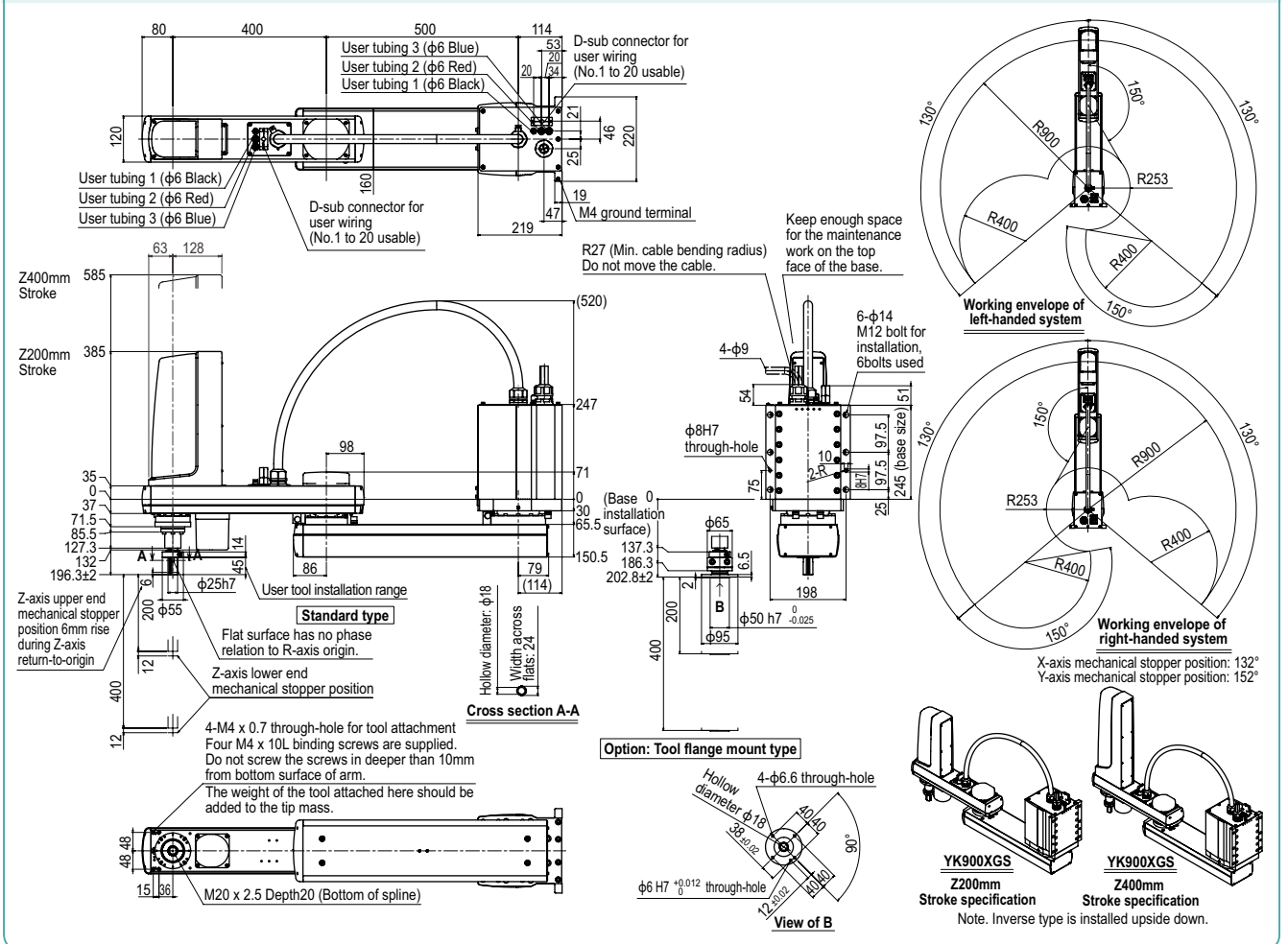
Controller

Controller	Power capacity (VA)	Operation method
RCX340 RCX240-R3	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. "Harmonic" and "Harmonic drive" are the registered trademarks of Harmonic Drive Systems Inc.
Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
<http://global.yamaha-motor.com/business/robot/>

YK900XGS



APPLICATION
Linear conveyor modules
LCM100

TRANSERVO
Compact single-axis robots

FLIP-X
Single-axis robots

PHASER
Linear motor single-axis robots

XY-X
Cartesian robots

YK-X
SCARA robots

YP-X
Pick & place robots

CLEAN
CLEAN CONTROLLER INFORMATION

Orbit / TriV type
Small / Medium type

Large type
Wall-mount / Inverse type

Dust-proof & drip-proof type