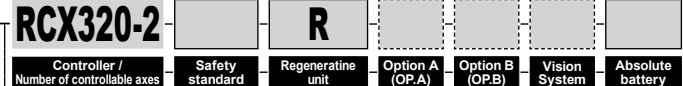
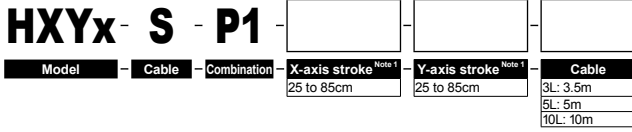


HXYx 2 axes

● Pole type ● Whipover



Ordering method



Specify various controller setting items. RCX320 ▶ **P548**



Specify various controller setting items. RCX222 ▶ **P558**

Note 1. The total of the X and Y strokes should be 1100mm or less.

Specification

	X-axis	Y-axis
Axis construction ^{Note 1}	F20	F20-BK
AC servo motor output (W)	600	600
Repeatability ^{Note 2} (mm)	+/-0.01	+/-0.01
Drive system	Ball screw φ20	Ball screw φ20
Ball screw lead ^{Note 3} (Deceleration ratio) (mm)	20	10
Maximum speed ^{Note 4} (mm/sec)	1200	600
Moving range (mm)	250 to 850	250 to 850
Robot cable length (m)	Standard: 3.5 Option: 5, 10	

Maximum payload (kg)

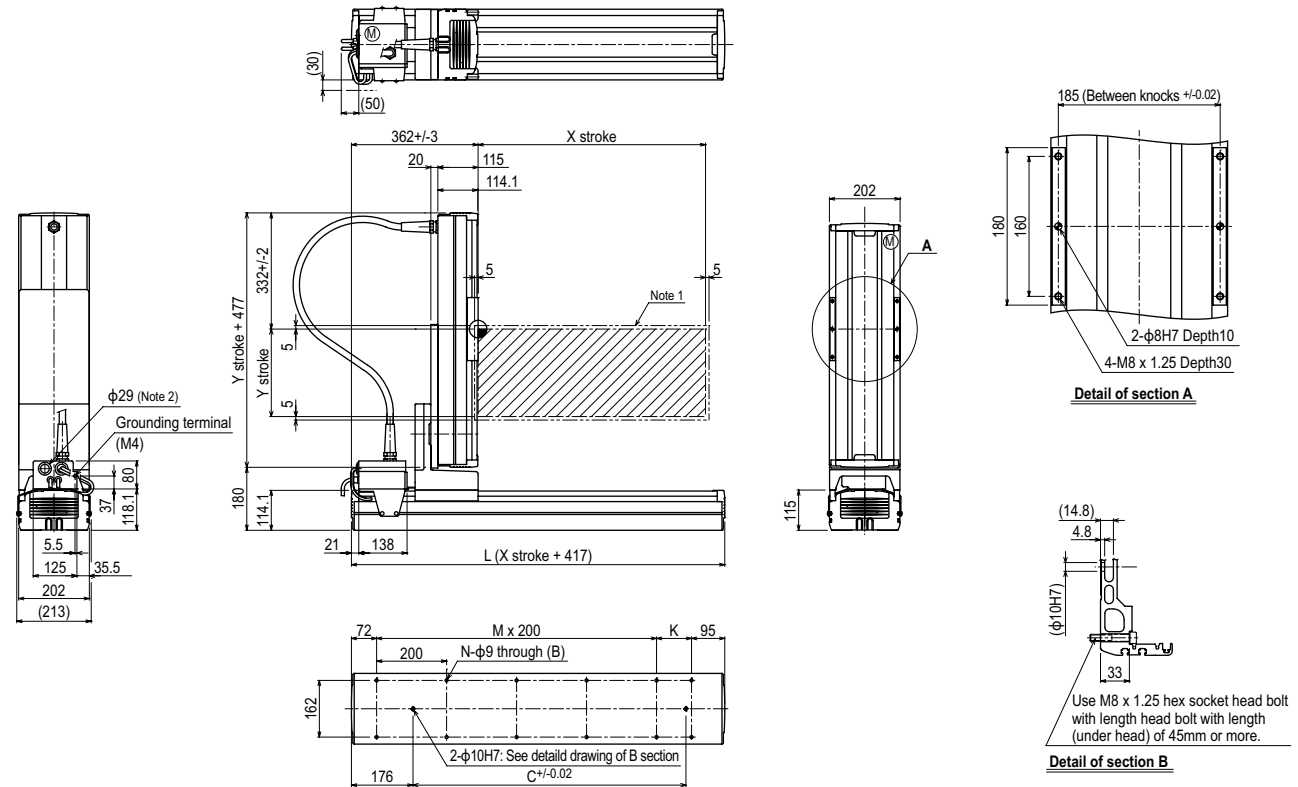
Y stroke (mm)	XY 2 axes
250 to 850	30

Note 1. Use caution that the flange machining (installation holes, tap holes) differs from single-axis robots.
 Note 2. Positioning repeatability in one direction.
 Note 3. Leads not listed in the catalog are also available. Contact us for details.
 Note 4. When the X-axis/Y-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

Controller

Controller	Operation method
RCX320-R RCX222HP-R	Programming / I/O point trace / Remote command / Operation using RS-232C communication

HXYx 2 axes P1



X stroke ^{Note 3}	250	350	450	550	650	750	850
	L	667	767	867	967	1067	1167
K	100	200	100	200	100	200	100
C	420	420	600	600	780	780	960
M	2	2	3	3	4	4	5
N	8	8	10	10	12	12	14

Y stroke ^{Note 3}	250	350	450	550	650	750	850
	Maximum speed for each stroke (mm/sec) ^{Note 4}	X-axis		1200		960	
	Y-axis		600		480		480
Speed setting			-				80%

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.
 Note 2. User cable extraction port.

Note 3. The total of the X and Y strokes should be 1100mm or less.
 Note 4. When the X-axis/Y-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

Articulated robots
YA
Linear conveyor modules
LCM100
Motor-less single axis robot
Robonity
Compact single-axis robots
TRANSEVO
Single-axis robots
FLIP-X
Linear motor single-axis robots
PHASER
Cartesian robots
XY-X
SCARA robots
YK-X
Pick & place robots
YP-X
CLEAN
CONTROLLER INFORMATION
Arm type
Gantry type
Moving arm type
Pole type
XZ type