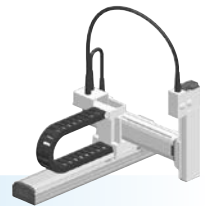


MXYx 3 axes / ZFH

● Moving arm type ● Cable carrier ● Z-axis: clamped table / moving base type (200W)



Ordering method

MXYx - C - [] - [] - [] - **ZFH** - [] - [] - **RCX340-3** - [] - [] - [] - [] - [] - [] - []

Model	Cable	Combination	X-axis stroke	Y-axis stroke	ZR-axis	Z-axis stroke	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
		M1 M3	25 to 125cm	15 to 55cm		15 to 35cm	3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ **P.566**

Specification

	X-axis	Y-axis	Z-axis
Axis construction ^{Note 1}	F17	F14H	F10H-BK
AC servo motor output (W)	400	200	200
Repeatability ^{Note 2} (mm)	+/-0.01	+/-0.01	+/-0.01
Drive system	Ball screw φ20	Ball screw φ15	Ball screw φ15
Ball screw lead ^{Note 3} (Deceleration ratio) (mm)	20	20	10
Maximum speed ^{Note 4} (mm/sec)	1200	1200	600
Moving range (mm)	250 to 1250	150 to 550	150 to 350
Robot cable length (m)	Standard: 3.5 Option: 5,10		

Note. The standard types are ZFH with higher rigidity as compared with ZF types which are conventional standard types. When you need the ZF type, please consult YAMAHA.
 Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots.
 Note 2. Positioning repeatability in one direction.
 Note 3. Leads not listed in the catalog are also available. Contact us for details.
 Note 4. When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

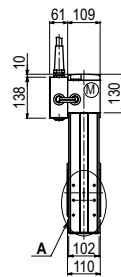
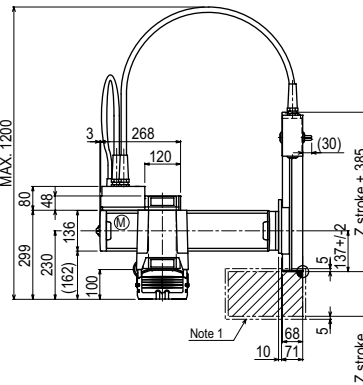
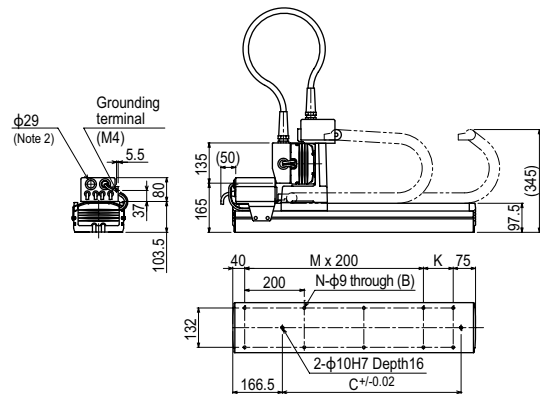
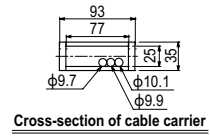
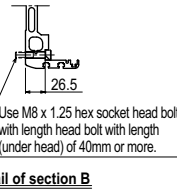
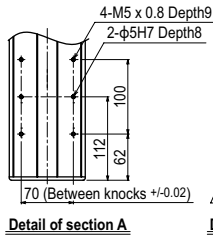
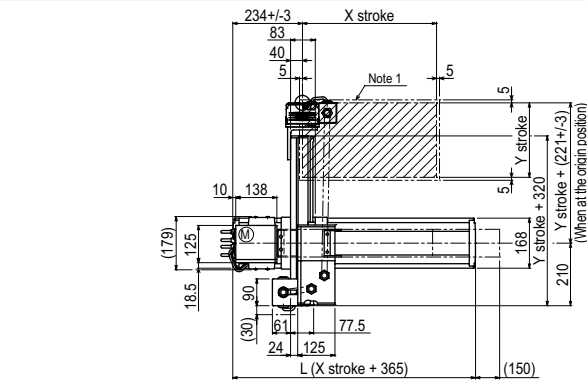
Maximum payload (kg)

	Z stroke (mm)		
Y stroke (mm)	150	250	350
150 to 550	12	11	10

Controller

Controller	Operation method
RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication

MXYx 3 axes / ZFH (M1)



X stroke ^{Note 3}	250	350	450	550	650	750	850	950	1050	1150	1250	
L	615	715	815	915	1015	1115	1215	1315	1415	1515	1615	
K	100	200	100	200	100	200	100	200	100	200	100	
D	240	420	600	600	780	780	960	960	1140	1140	1320	
M	2	2	3	3	4	4	5	5	6	6	7	
N	8	8	10	10	12	12	14	14	16	16	18	
Y stroke ^{Note 3}	150	250	350	450	550							
Z stroke	150	250	350									
Maximum speed for each stroke (mm/sec) ^{Note 4}	X-axis	1200				960	840	720	600	480		
	Speed setting	-				80%	70%	60%	50%	40%		

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.
 Note 2. User cable extraction port.
 Note 3. The total of the Y and Z strokes should be 800mm or less.
 Note 4. When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

Articulated robots
YA
Linear conveyor modules
LCM100
Motorless single-axis actuator
Robonity
Compact single-axis robots
TRANSEVO
Single-axis robots
FLIP-X
Linear motor single-axis robots
PHASER
Cartesian robots
XY-X
SCARA robots
YK-X
Pick & place robots
YP-X
CLEAN
CONTROLLER INFORMATION
Arm type
Gantry type
Moving arm type
Pole type
XZ type