

AGBS14/AGBS14H

Advanced model

Single-axis robots

Timing Belt Drive type

Ordering method

| | | | | | | | | | | | | |
|--------|----------|---|--|---|--------------------------|------------------------------|---|------------------|-------------------------------------|---|--|----------------------------|
| Model | Lead | Shape | Motor specification | OP.1 | Stroke | Cable length | Cable entry location | Robot positioner | Driver Power capacity | Regenerative unit | I/O | Battery |
| AGBS14 | 50: 50mm | R: Motor rightward, horizontal position L: Motor leftward, horizontal position RU: Motor rightward, upper position LU: Motor leftward, upper position RD: Motor rightward, lower position LD: Motor leftward, lower position | S: Standard/With no brake BL: Battery-less absolute/With no brake | No entry; Standard M: Centerized Lubrication | 150 to 4000 (50mm pitch) | R3: 3m R5: 5m R10: 10m | R: From rear of motor F: From front of motor | EP-01 | A10: 200W or less A30: 400W/750W | No entry: None R: With EP-RU C: With RU-1 | EP: EtherNet/IP™ PT: PROFINET ES: EtherCAT NS: NPN CC: CC-Link | B: With battery N: None |

Note 1. The robot cable is flexible and resists bending.

Note 2. [For AGBS14]

When the actuator is used horizontally, ①lead 30 is selected, and the stroke is 2300mm or more, ②lead 50 is selected, and the stroke is 650mm or more, the regenerative unit is needed.

[For AGBS14H]

When the actuator is used horizontally, ①lead 30 is selected, and the stroke is 800mm or more, ②lead 50 is selected, and the stroke is 500mm or more, the regenerative unit is needed. (In this case, please choose the regenerative device "RU1".) ③lead 50 is selected, and the stroke is 1550mm or more

Note 3. When the motor specification is the standard (S, BK), whether to use the battery needs to be selected.

Note 4. The return-to-origin direction can be changed by changing the parameter. (The standard is that the origin is located on the motor side. For details about how to change the return-to-origin direction, see the instruction manual for EP-01.)

AGBS14 (200W)

Specifications

| | | |
|--|--|----------------------------------|
| AC servo motor output | 200 W | |
| Repeatability ^{Note 1} | ±0.04 mm | |
| Stroke | 150 mm to 4000 mm (50 mm pitch) | |
| Maximum Speed ^{Note 2} | 3750 mm/sec | 2250 mm/sec |
| Belt | Equivalent to 50-mm Lead | Equivalent to 30-mm Lead |
| Maximum payload | Horizontal 8 kg | 30 kg |
| Maximum dimensions of cross section of main unit | W 140 mm × H 83 mm | |
| Overall length | L/R Specifications ST + 474.5 mm | Other than the above ST + 405 mm |
| Degree of Cleanliness ^{Note 3} | Equivalent to ISO Class 3 (ISO 14644-1) | |
| Intake air ^{Note 4} | 90 Nℓ/min | |
| Position detector | Absolute Encoder Batteryless Absolute Encoder | |
| Resolution | 23 bits | |
| Using ambient temperature and humidity ^{Note 5} | 0 to 40 °C, 35 to 80 %RH (no condensation) | |

Note 1. Positioning repeatability in one direction.

Note 2. When a moving distance is short and depending on an operation condition, it may not reach the maximum speed.

Note 3. When using in a clean environment, attach a suction air joint. The degree of cleanliness is the cleanliness level achieved when using at 1000 mm/sec or less.

Note 4. The required suction amount will vary according to the operating conditions and operating environment.

Note 5. When operating in low-temperature environments, a deviation error may occur when starting from a stopped state. In such cases, reduce the speed to 50% or less and run the unit for at least one full cycle before setting it to the desired operating speed.

AGBS14H (400W)

Specifications

| | | |
|--|--|----------------------------------|
| AC servo motor output | 400 W | |
| Repeatability ^{Note 1} | ±0.04 mm | |
| Stroke | 150 mm to 4000 mm (50 mm pitch) | |
| Maximum Speed ^{Note 2} | 3750 mm/sec | 2250 mm/sec |
| Belt | Equivalent to 50-mm Lead | Equivalent to 30-mm Lead |
| Maximum payload | Horizontal 30 kg | 60 kg |
| Maximum dimensions of cross section of main unit | W 140 mm × H 83 mm | |
| Overall length | L/R Specifications ST + 474.5 mm | Other than the above ST + 405 mm |
| Degree of Cleanliness ^{Note 3} | Equivalent to ISO Class 3 (ISO 14644-1) | |
| Intake air ^{Note 4} | 90 Nℓ/min | |
| Position detector | Absolute Encoder Batteryless Absolute Encoder | |
| Resolution | 23 bits | |
| Using ambient temperature and humidity ^{Note 5} | 0 to 40 °C, 35 to 80 %RH (no condensation) | |

Note 1. Positioning repeatability in one direction.

Note 2. When a moving distance is short and depending on an operation condition, it may not reach the maximum speed.

Note 3. When using in a clean environment, attach a suction air joint. The degree of cleanliness is the cleanliness level achieved when using at 1000 mm/sec or less.

Note 4. The required suction amount will vary according to the operating conditions and operating environment.

Note 5. When operating in low-temperature environments, a deviation error may occur when starting from a stopped state. In such cases, reduce the speed to 50% or less and run the unit for at least one full cycle before setting it to the desired operating speed.

Motor installation

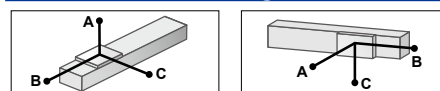
The line-up consisting of six models of different motor installation position as follows.

| | | | | | |
|--|---|--|---|--|---|
| R type Rightward at horizontal position | L type Leftward at horizontal position | RU type Rightward at upper position | LU type Leftward at upper position | RD type Rightward at lower position | LD type Leftward at lower position |
|--|---|--|---|--|---|



▶ The cycle time simulation and service life calculation can be performed easily from our member site.

Allowable overhang ^{Note}



AGBS14-50

| | Horizontal installation (Unit: mm) | | | Wall installation (Unit: mm) | | |
|-----|------------------------------------|------|------|------------------------------|------|------|
| | A | B | C | A | B | C |
| 4kg | 4595 | 3295 | 2628 | 2664 | 3259 | 4554 |
| 6kg | 4027 | 2188 | 2007 | 2051 | 2151 | 3973 |
| 8kg | 3739 | 1634 | 1647 | 1696 | 1598 | 3672 |

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| | Horizontal installation (Unit: mm) | | | Wall installation (Unit: mm) | | |
|------|------------------------------------|------|------|------------------------------|------|------|
| | A | B | C | A | B | C |
| 10kg | 2334 | 1302 | 1236 | 1237 | 1265 | 2289 |
| 20kg | 1641 | 637 | 670 | 675 | 601 | 1565 |
| 30kg | 1601 | 442 | 519 | 517 | 405 | 1495 |

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Note. Service life is calculated for 1000 mm stroke models.

Note. When using it suspended from the ceiling, the overhang will be the same as when used horizontally.

Allowable overhang ^{Note}



AGBS14H-50

| | Horizontal installation (Unit: mm) | | | Wall installation (Unit: mm) | | |
|------|------------------------------------|-----|-----|------------------------------|-----|-----|
| | A | B | C | A | B | C |
| 10kg | 943 | 621 | 429 | 479 | 408 | 627 |
| 20kg | 768 | 302 | 279 | 276 | 182 | 477 |
| 30kg | 746 | 208 | 220 | 198 | 115 | 434 |

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| | Horizontal installation (Unit: mm) | | | Wall installation (Unit: mm) | | |
|------|------------------------------------|-----|-----|------------------------------|-----|------|
| | A | B | C | A | B | C |
| 20kg | 1519 | 637 | 652 | 653 | 601 | 1449 |
| 40kg | 1501 | 344 | 424 | 414 | 308 | 1374 |
| 60kg | 1596 | 250 | 332 | 309 | 213 | 1410 |

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Note. Service life is calculated for 1000 mm stroke models.

Note. When using it suspended from the ceiling, the overhang will be the same as when used horizontally.

