

LGXS16

Advanced model

Motor-less Single Axis Actuator

Slider type



Ordering method

LGXS16

Model	Lead	Motor specification	Stroke
	40: 40 mm 20: 20 mm 10: 10 mm	No entry: Standard P: P specification (see below)	100 to 1450 (50 mm pitch)

[Caution]

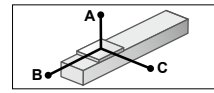
This system is provided as mechanical actuator unit and not including any adapters or electric components. Motor, driver and other components required for installation are the user's responsibility. Refer to user's manual for installation details. Refer to your motor manual for tuning or adjustment. Vibration or resonance from actuator will affect service life of actuator. The product performance may not be satisfied depending on the compatible motor. The bending unit cannot be used for the high agility mode.

Specifications

Applicable motor	750 W		
Repeatability ^{Note 1}	+/-0.005 mm		
Deceleration mechanism	Ground ball screw ϕ 20 (C5 class)		
Stroke	100 mm to 1450 mm (50 mm pitch)		
Maximum speed (or equivalent)	2400 mm/sec	1200 mm/sec	600 mm/sec
Ball screw lead	40 mm	20 mm	10 mm
Maximum payload (or equivalent)	Horizontal	45 kg	95 kg
	Vertical	12 kg	28 kg
Rated thrust (or equivalent)		320 N	640 N
		640 N	1280 N
		1280 N	
Maximum dimensions of cross section of main unit	W 160 mm x H 130 mm		
Overall length	ST + 242.5 mm		
Degree of cleanliness ^{Note 4}	ISO CLASS 3 (ISO14644-1) or equivalent		
Intake air ^{Note 5}	30 Nℓ/min to 90 Nℓ/min		
Using ambient temperature and humidity	0 to 40 °C, 35 to 80 %RH (non-condensing)		

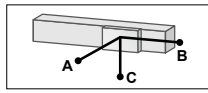
- Note 1. Positioning repeatability in one direction.
 Note 2. When a moving distance is short and depending on an operation condition, it may not reach the maximum speed.
 If the effective stroke exceeds 800 mm, the ball screw may resonate. (Critical speed)
 At this time, make the adjustment to decrease the speed while referring to the maximum speed shown in the table.
 Note 3. The rated thrust and maximum transferable weight are values assuming the attached motor outputs the rated torque.
 Note 4. When using in a clean environment, attach a suction air joint. The degree of cleanliness is the cleanliness level achieved when using at 1000 mm/sec or less.
 Note 5. The required suction amount will vary according to the operating conditions and operating environment.
 Note. See P.130 for acceleration/deceleration and inertia moment.

Allowable overhang ^{Note}



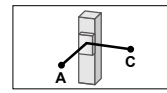
LGXS16-40

Horizontal installation (Unit: mm)	A	B	C
15kg	2876	1866	1253
30kg	2385	997	776
45kg	2339	720	604



Wall installation (Unit: mm)

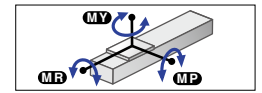
A	B	C
15kg	1273	1802
30kg	782	935
45kg	598	658



Vertical installation (Unit: mm)

A	C
3kg	6605
6kg	3699
12kg	2827

Static loading moment



(Unit: N·m)

MY	MP	MR
706	706	620

Adaptable Servo Motor

Specification	Flange size	<input type="checkbox"/> 80
	Wattage	750 W
Motor specification	Manufacturer	Model
No entry	Yaskawa Electric Corp.	SGMJV-08 SGMJJ-08
	Keyence Corp.	SV-□075 SV2-□075
	Mitsubishi Electric Corp.	SF-KP73 HG-KR73 ^{Note 1} HK-KT7M3 ^{Note 1}
	Omron Electronics	R88M-K75030 R88M-1M75030
P	Panasonic Corp.	M5MD08 M5MF08 MHMF08
	Conversion adapter product model	Shim plate part number
	GX-BEND-80 ^{Note 2}	KEX-M2295-00

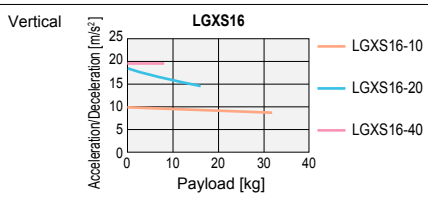
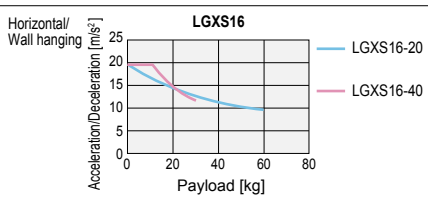
- Note 1. To combine with the conversion adapter <GX-BEND-80>, the shim plate (t1) is necessary.
 Note 2. For the specifications P, the bending unit cannot be used.

When used with high acceleration or deceleration (High agility mode)

Specifications

Stroke	100 mm to 800 mm (50 mm pitch)		
Ball screw lead	40 mm	20 mm	10 mm
Maximum payload	Horizontal	30 kg	60 kg
	Vertical	-	-
Maximum acceleration	Horizontal	19.62 m/s ² (2 G)	19.84 m/s ² (2 G)
	Vertical	8 kg	16 kg
	Vertical	19.62 m/s ² (2 G)	18.43 m/s ² (1.9 G)

Payload - Acceleration / Deceleration Graph (Estimate)



Allowable overhang ^{Note}

LGXS16-40

Horizontal installation (Unit: mm)	A	B	C
10kg	1271	1669	836
20kg	725	803	429
30kg	534	514	287

Wall installation (Unit: mm)

A	B	C
10kg	816	1585
20kg	404	725
30kg	259	441

Vertical installation (Unit: mm)

A	C
3kg	2904
5kg	1710
8kg	1038

LGXS16-10

Vertical installation (Unit: mm)	A	C
10kg	2951	2951
20kg	1438	1438
32kg	870	870

LGXS16-20

Horizontal installation (Unit: mm)	A	B	C
20kg	1722	1123	875
40kg	952	535	428
60kg	682	339	276

Wall installation (Unit: mm)

A	B	C
20kg	842	1056
40kg	388	470
60kg	232	275

Vertical installation (Unit: mm)

A	C
5kg	3473
10kg	1723
16kg	1064

- Note. Distance from center of slider top to center of gravity of object being carried at guide service life of 10,000 km.
 Note. Service life is calculated for 600 mm stroke models.

Effective stroke and maximum speed during high acceleration or deceleration

Effective stroke	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	
Maximum speed (mm/sec)	Lead 40	2400														
	Lead 20	1200														
	Lead 10	600														

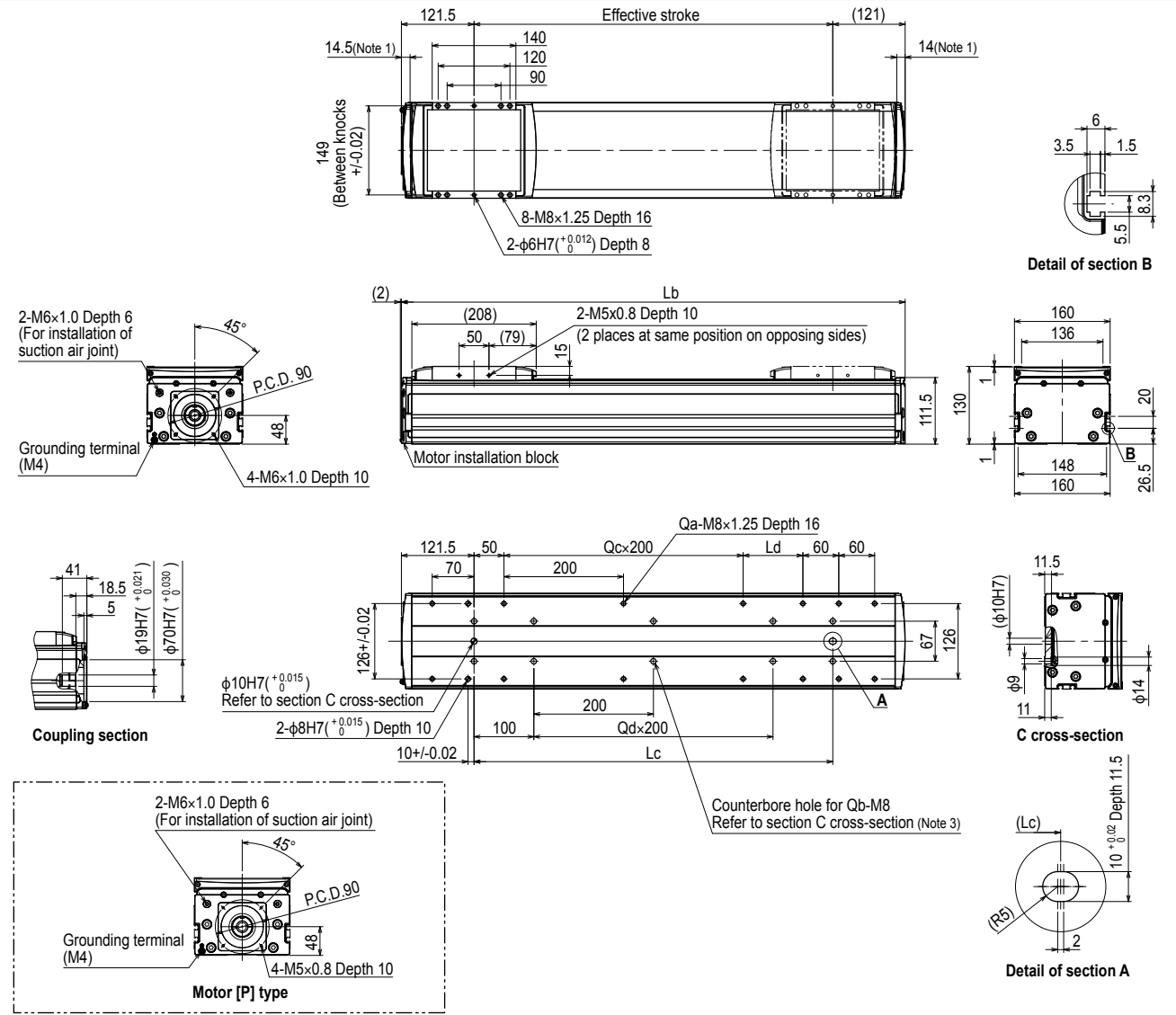
- Note. The bending unit cannot be used for the high agility mode.
 Note. The high agility mode is used in an effective stroke range of 100 to 800 (50 mm pitch).
 Note. There is no critical speed setting. The maximum speed can be set for a selectable stroke.
 The speed may not reach the maximum speed if the movement distance is short or depending on the operating conditions.
 Note. See P.132 for acceleration/deceleration and inertia moment.

Access the website below.



▶ The cycle time simulation and service life calculation can be performed easily from our member site. For details, see P.16.

LGXS16



- Note 1. Stop positions are determined by the mechanical stoppers at both ends.
- Note 2. The length under head of the hex socket head bolts <math>M8 \times 1.25>> used to mount the body with the mounting counterbore holes (section C cross-section) must be <<25 mm or more>>. The recommended length under head of the hex socket head bolts <math>M8 \times 1.25>> used to mount the body with the mounting tap hole specifications is <<frame thickness + 15 mm or less>>.
- Note 3. When using the mounting counterbore holes (section C cross-section) to mount the body, remove the seal, and then fix.
- Note 4. Grease gun nozzle (recommended) (see P.143 for detail)

Effective stroke	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450					
Lb	342.5	392.5	442.5	492.5	542.5	592.5	642.5	692.5	742.5	792.5	842.5	892.5	942.5	992.5	1042.5	1092.5	1142.5	1192.5	1242.5	1292.5	1342.5	1392.5	1442.5	1492.5	1542.5	1592.5	1642.5	1692.5					
Lc	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450					
Ld	0	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150					
Qa	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18	18	20	20	20	20	22	22	22					
Qb	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18					
Qc	0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6					
Qd	0	0	0	0	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6					
Weight (kg)	11.7	12.7	13.7	14.7	15.7	16.6	17.6	18.6	19.6	20.6	21.5	22.5	23.5	24.5	25.5	26.5	27.4	28.4	29.4	30.4	31.4	32.4	33.3	34.3	35.3	36.3	37.3	38.2					
Maximum speed (mm/sec)	Lead 40																2400																
	Lead 20																1200																
	Lead 10																600																
	Speed setting																-																
																	2160	1920	1680	1440	1320	1200	1080	960	840	720	600						
																	1080	960	840	720	660	600	540	480	420	360	300						
																	540	480	420	360	330	300	270	240	210	180	150						
																	90%	80%	70%	60%	55%	50%	45%	40%	35%	30%	25%						

Features

Basic model

Advanced model

Basic model

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Basic model

Advanced model

Acceleration/Deceleration

Inertia Moment

Option

Single axis motion

EP-01