



RCX 3 Series CONTROLLER YAMAHA ROBOT VISION

RCXiVY2+ SYSTEM

Yamaha's own unique solution for integrated robot vision

Integrated Robot Vision System with

Simplicity

Sophistication

Assurance



- Easy Operation
- Wide range of applications
- Shorter startup time
- Comprehensive support of robot and vision by Yamaha

RCXiVY2+ SYSTEM

Camera 400,000 to 5 million pixels	Parts registration 254 types	Search time reduced by Approximately 50 % less	Maximum cable length 20 m	Monitoring Monitor output is provided
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* Time depends on the workpiece.

Solutions RCXiVY2+ can provide:

Reducing teaching process time

Robot teaching work requires a lot of labor and time. The RCXiVY2+ system acts as "robot eye". The final fine positioning can be automated and greatly reduce the teaching time that was required for the conventional models.

Simplified positioning process

Reducing positioning process time in frequent lot change in small lot production. Cost in preparation, control, and switching positioning jigs can be reduced.

Random workpieces need to be handled.

With position detection function of RCXiVY2+, pick & place operation of random shaped parts from parts feeder or pallet can be simplified.

Conveyor tracking

With a feedback from encoder of a conveyor RCXiVY2+ can do pick & place following conveyor or move.

Yamaha's comprehensive support of Robot and Vision

Yamaha's integrated robot vision system. It means Yamaha supports both robot and vision system seamlessly.

Have any questions and don't know if it is robot or vision related? Simply contact Yamaha representative. We have answers.

Advan

RCXiVY2+ features:

- Adjusting parts orientation on the fly
- Conveyor follower
- Searching randomly placed parts
- Top/bottom judgement
- OK/NG judgement





Simplicity

Setup is completed as little as eight minutes after power-on.
Auto-calibration makes setup easy.

Sophistication

With up to five million pixels,
a variety of workpieces can be supported.
Improve throughput to 100 CPM
with conveyor tracking.

Assurance

Comprehensive support covers everything
from camera image acquisition to the operation
of the gripper and robot.
With support that only the robot manufacturer
can provide, you can relax.

Enhanced RCX iVY2+ has been launched.



Increased application features

- Picking of irregular shape workpieces
- Presence inspection
- Multiple piece count

Enhanced performance

- CPU capability is increased to improve the search speed 8 to 45%.
- Number of pixels is increased.
- Frame rate is increased.

Easy operation

- Supports template function of RCX-Studio 2020



Easy op

New features fo

High speed positioning of irregular shaped parts (foods or clothes)

Blob search function

Suitable for pick & place or detection of parts with wide tolerance in shape and size, or high speed counting.
Detection speed is 2 to 10 times faster than edge detection.



Detection time is shortened up to 45%.

CMOS camera

By adopting a high-performance camera and improving the camera frame rate and CPU capability, detection time is reduced 8 to 45% while the resolution is improved.



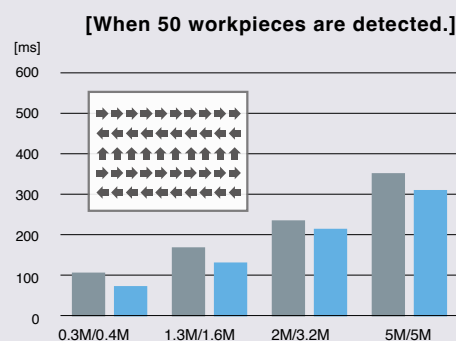
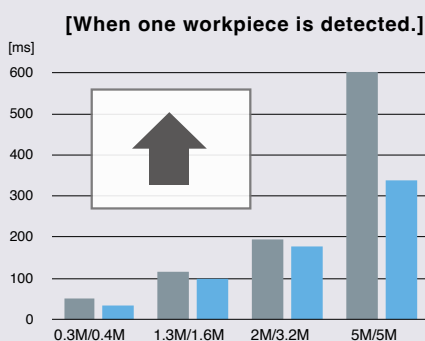
Improved camera pixels

Improved camera frame rate

Improved CPU

Comparison of search time

■ Conventional iVY2 ■ NEW RCXiVY2+



Time
Up to **45** % is shortened.

Operation

for easy operation



Suitable for parts detection and high volume parts count

Application examples

*Subject to application and conditions.

- Detection of electronics components on PC board
- Detection of accessories in package
- Counting of the number of bottles in pallet
- Detection of food labels
- Detection of screws and washers that secure parts
- Checking drilled holes
- Counting of electronics components

Overlap can be eliminated.

Overlapped workpieces are recognized and they can be excluded from the search target.

Detection with Speed

Comparing with edge search, blob search speed is 2 to 10 times faster.

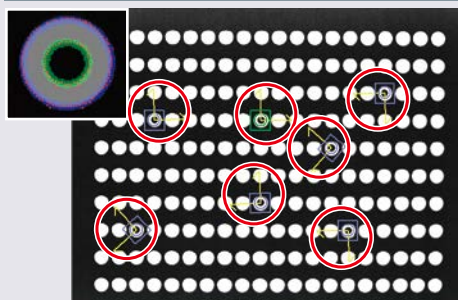
Search speed

Up to **10** times faster

Comparison of edge search and blob search

* Only doughnut shape workpieces are detected.

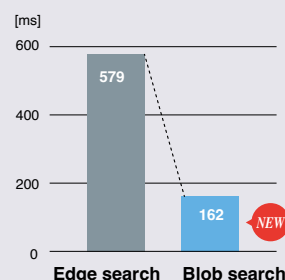
Edge search



Blob search



[Comparison of search speed]



Handling of various types of workpieces is made easier and simpler.

Connection of multiple cameras

By controlling multiple cameras with one controller, multiple processes such as component supply, position correction, and mounting can be performed by one robot and controller.

This makes it possible to dramatically improve the setup man-hours prepared for each component type and contributes to improvement of production efficiency.



[Application using three cameras]

- (1) Workpiece supply position is corrected using the downward camera.
- (2) Workpiece positioning or angle is corrected using the upward camera.
- (3) Place position is corrected using the downward camera.



Suitable for traceability management

Code recognition function

Codes such as QR codes, data matrix codes, and barcodes can be recognized. This code recognition function is optimal for applications that change the operation corresponding to the code contents such as traceability management, workpiece sorting, and tracking change of sealing. It is not necessary to separately purchase a handy terminal or code reader. Troublesome communication control is also not needed.

[Supported codes]

- QR code
- Data matrix code
- Barcode (JAN/EAN-13 JAN/EAN-8 ITF NW7 CODE39 CODE128)

* Up to 255 characters can be read.
Only alphanumeric characters and symbols are supported.
(2-byte characters such as HIRAGANA and KANJI characters cannot be read.)



Automatic image save function

Images are automatically saved to a USB memory when search is executed.

This function is very useful when you want to go back in time to check captured images during operation or debugging or when you want to save images for traceability purposes.

A USB connectable SSD or HDD can also be used.

[Parameters]

Image save mode	All images / NG images / Disabled
Image size	Full size / Reduced size (320 x 240 pix.)
Overwrite save	Disabled/Enabled (The images are deleted from the oldest image when enabled.)

[Number of images that can be saved]

Number of images that can be saved when the memory size is 128 GB.

Number of camera pixels	Image size	Number of images that can be saved
0.4 million pixels	0.4MB	327680
1.6 million pixels	1.6MB	81920
3.2 million pixels	3.2MB	40960
5 million pixels	5.0MB	26214
Reduced.	0.08MB	1638400



Connector for USB memory

A connector that connects a USB memory to save images. This connector is used for the automatic image save function.

USB connector for mouse

A USB connector that connects a mouse to operate an external monitor. This connector is used for the history image function.

Monitor output connector

A connector that outputs images captured by the camera to a monitor.

Number of images that can be saved = Memory size / Image size
81920 images can be saved by 1.6 million pixels camera when 128 GB memory is used.

When the cycle time is 3 seconds, images for 68 hours can be saved.

History image function

Images can be displayed on an external monitor during searching.

The images and search results can be checked retrospectively with a USB mouse connected.

[Number of images that can be saved]

Number of camera pixels	Image size	Number of images that can be saved
0.4 million pixels	0.4MB	1250
1.6 million pixels	1.6MB	312
3.2 million pixels	3.2MB	156
5 million pixels	5.0MB	100

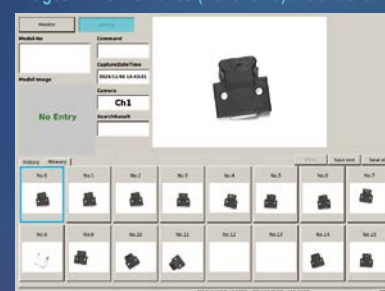
Area for history images 500 MB

Number of images that can be recorded to the history =
500 MB / Image size

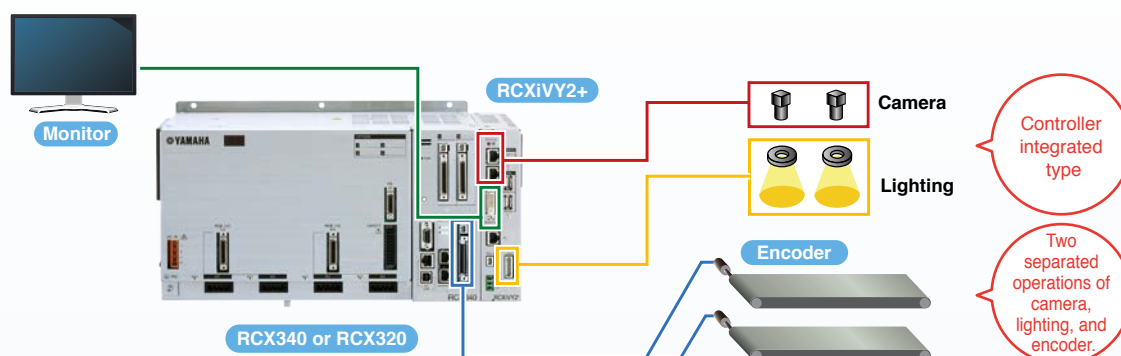
Past search images and results are checked.



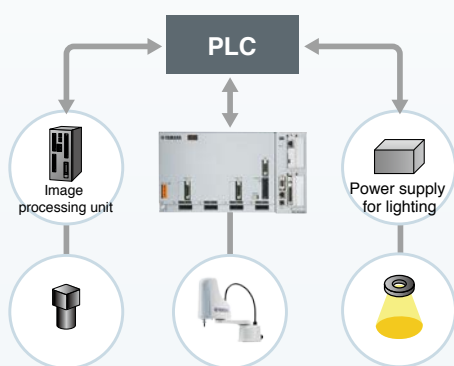
Images in the memories (No. 0 to 15) are checked.



[Robot controller integrated type]



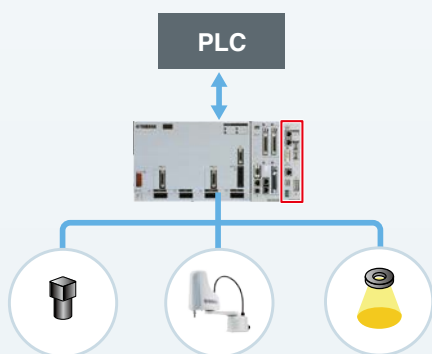
Typical Robot Vision setup



- 1 Time consuming robot coordinates alignment.
- 2 Need to calculate compensation for moving camera setup.
- 3 Operation deviation between the camera and robot due to communication time.
- 4 Adjustment of communication format is needed.

- ✗
- Handling not easy
 - Installation and setup costs are high.
 - Robot issue or vision issue? Who to call?

RCXiVY2+ system



- 1 Simple calibration function is incorporated.
- 2 Coordinates are corrected automatically even when the camera moves.
- 3 High-speed connections through dedicated bus line.
- 4 Controller is incorporated to provide the central operation.
- 5 Applicable to all models of YAMAHA robot lineup.

-
- Easy to use
 - Various applications are supported using easy operation.
 - Cost reduction by reducing work steps.
 - Robot and vision supported by Yamaha

Typical Robot Vision setup

```

MOVE P, P9
OFF LINE
SEND (* *) TO CMU
SEND CMU TO P10
ON LINE
MOVE P, P10
    
```

Communication with image processing unit

↕ RS-232C

Program of image processing unit

Program of host PLC

Camera and robot have separate programs

RCXiVY2+ system

```

MOVE P, P9
VSEARCH 1,2,0
P10=VGETPOS(0)
MOVE P, P10
    
```

Searches for workpiece.
Reads the point.
Moves to this point.

POINT

- No communication time lag
- Needs only few command lines.
- Simple and easy to understand

Centralized control using only the robot program

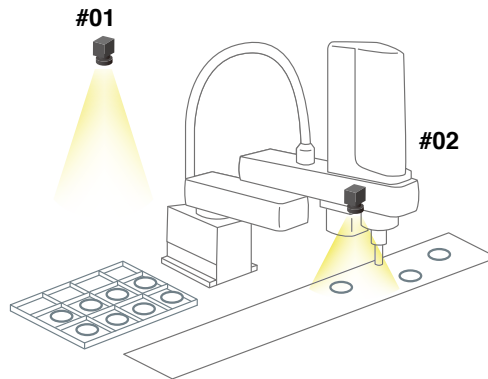
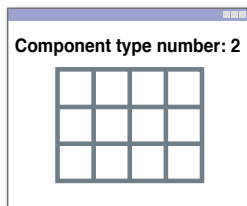
[Examples of program commands]

VSEARCH ... Detect parts with designated camera

Camera and component type to be used for detection and the calibration data to be used can be switched with one command.

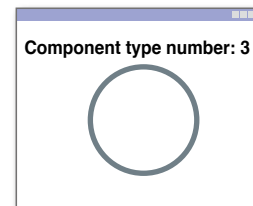
VSEARCH 1, 2, 1

- Camera: 1
- Component type number: 2
- Calibration data: 1



VSEARCH 2, 3, 2

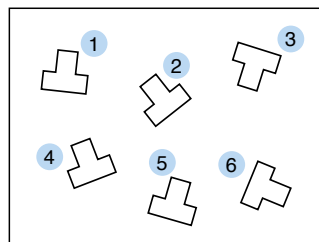
- Camera: 2
- Component type number: 3
- Calibration data: 2



VGETPOS ... Acquires the coordinates of the detected workpieces.

The search results can be substituted into the point coordinates directly.

```
VSEARCH 1, 2, 1    ... Detects the workpieces.
N = VGETCNT        ... Substitutes the number
                    of detected workpieces.
FOR J = 0 TO N-1
  P[ J ] = VGETPOS (J) ... Acquires the workpiece
                    coordinates.
NEXT J
```



VGETPOS (0) → Coordinates of 1
 VGETPOS (1) → Coordinates of 2
 VGETPOS (2) → Coordinates of 3
 VGETPOS (3) → Coordinates of 4
 VGETPOS (4) → Coordinates of 5
 VGETPOS (5) → Coordinates of 6

* The order to substitute into VGETPOS can be selected from the following.
 1) Score order, 2) X coordinate, and 3) Y coordinate

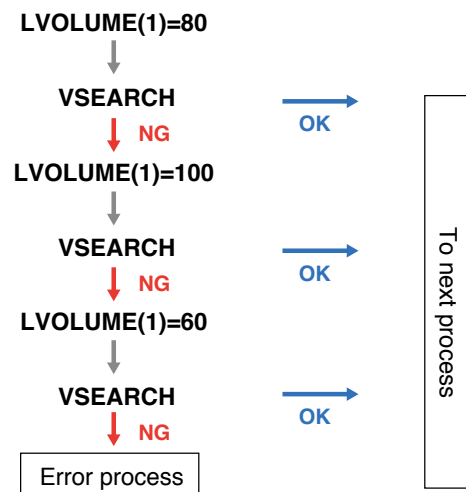
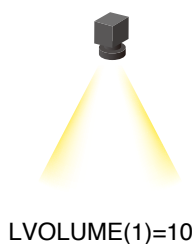
LVOLUME ... Intensity of light is adjustable from 0 to 100% range

In detection mode intensity of light can be adjusted with one command.

Detection can be repeated with adjusted intensity.

With a robot program of RCXiVY2+, retry detection with adjusted light intensity can be easily performed

• Light 1 is set to 10%. • Light 1 is set to 100%.



[3 easy steps for parts registration]

From image acquisition, registration takes just three steps.

Requires as
little as
3 minutes

STEP. 1

Capture images.

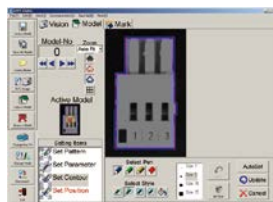
Put the workpiece within the camera field-of-view and specify an image capturing range.



STEP. 2

Set the contour.

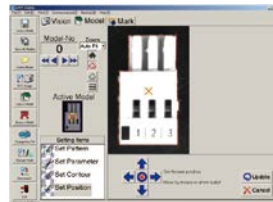
Contour is automatically extracted. Paint the necessary contour with a pen tool.



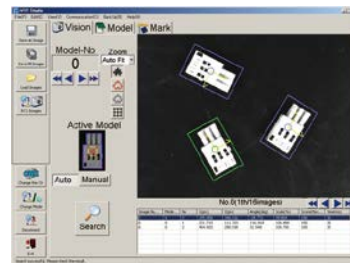
STEP. 3

Register the detection position.

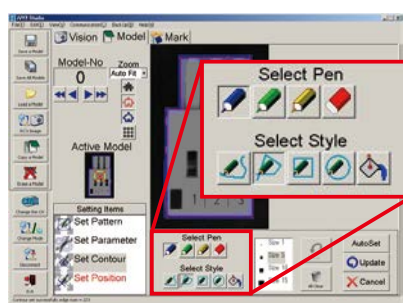
Specify the detection position with the mouse. Desired positions can be set.



Search results



[Simple parts judgement process]



Contour setting pen

Paints the areas to be used from among the automatically detected edges.



Priority area pen

Paints the areas to be used as priority areas during search from among the edges.



Reduction area pen

Paints the areas where there should not be an edge during search.

[Usage example]



· Workpiece top or bottom judgement

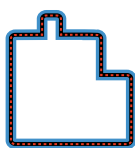


· Simple OK or NG judgement

• Usage example of contour setting pen

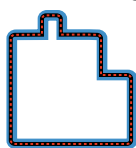
When a workpiece with a partially different shape needs to be distinguished and recognized or when the top or bottom needs to be judged, the detection can be performed by painting the contours in different colors by combining the contour setting pen with the priority area pen and reduction area pen.

Detection results

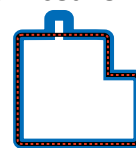


Blue : Normal contour setting

All contours are handled equivalently.

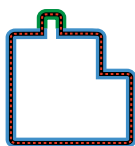


OK



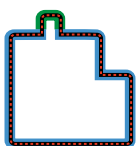
OK

The score may slightly vary depending on the presence status of the protrusion. However, both are detected.

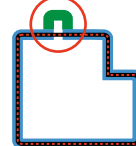


Green : Priority area setting

In addition to the blue area search, areas painted in green are used as priority areas to perform the judgement.

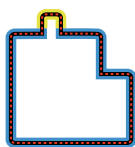


OK



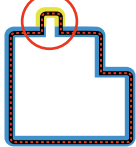
NG

When no edge is detected in the area set as priority area, this is judged as NG and the workpiece is not detected.

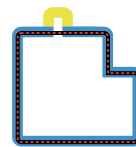


Yellow : Reduction area setting

When there is an edge in the unnecessary area painted in yellow, the score is reduced.



NG



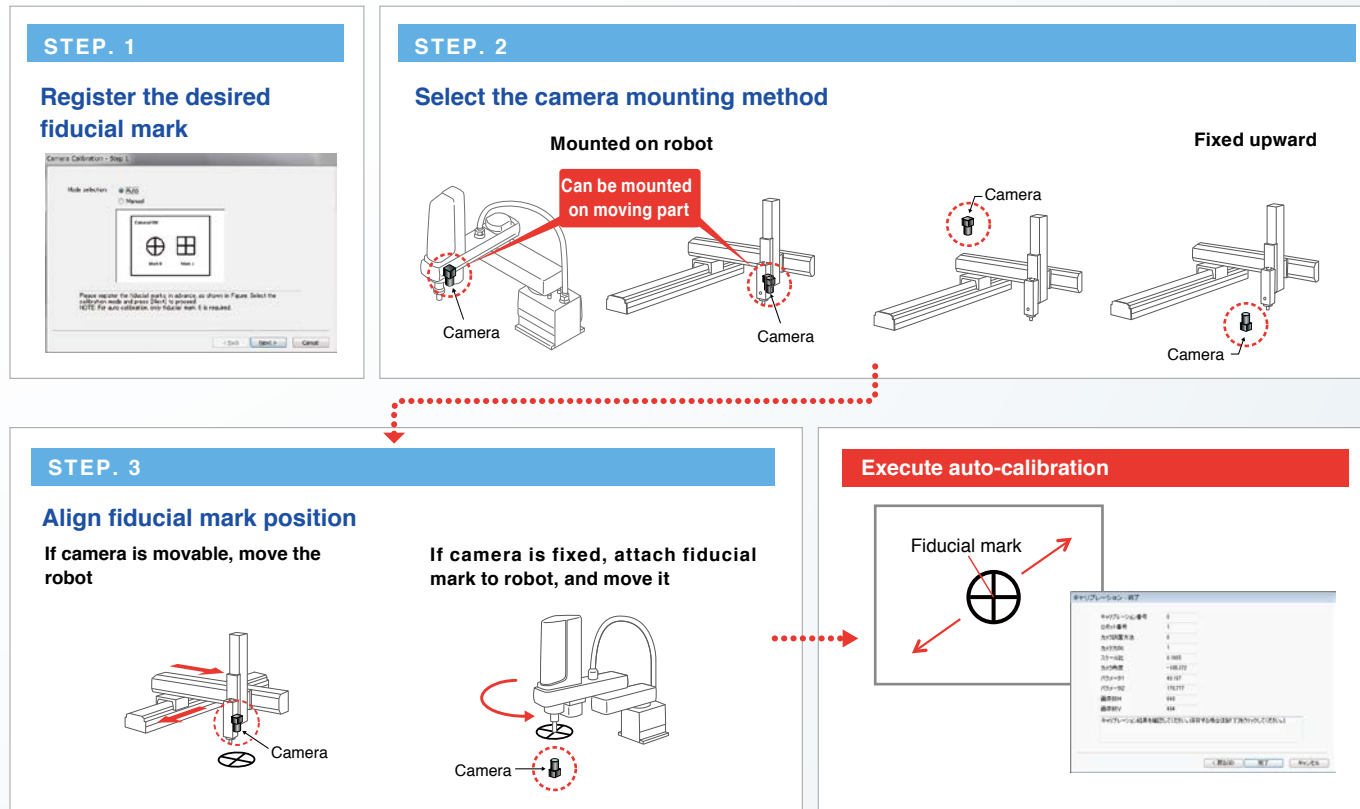
OK

When an edge is detected in the area set as unnecessary area, the score is reduced and the workpiece is not detected.

[Simple calibration]

Conventional equipment combining "image processing unit + robot" requires many steps in "calibration" that aligns the camera coordinates with the robot coordinates. With the RCXiVY2+ system, following the wizard to perform the operation will complete the calibration easily within a short time. In addition, even when the setting position deviates, the calibration is executed and restored immediately.

Requires as little as
5 minutes

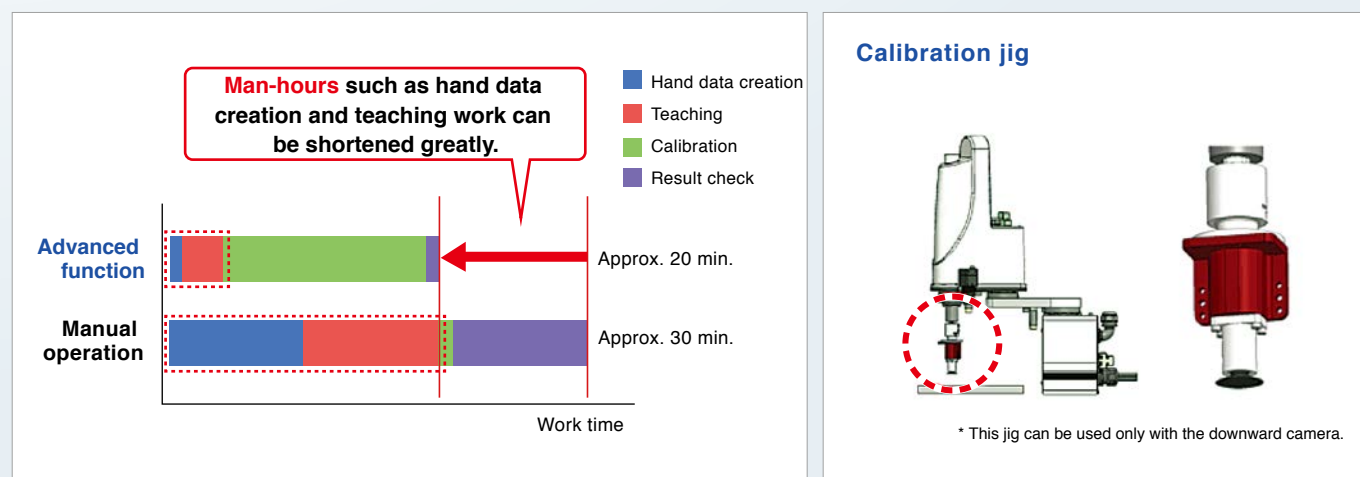


[Calibration is automated with the dedicated jig.]

By automating the calibration using the advanced calibration function, highly accurate calibration can be achieved easily without depending on the operator's skill.

The hand data can also be created automatically and the time necessary for the calibration is reduced greatly.

Since the dedicated jig is the standard part (option part), the jig does not need to be designed and manufactured and can be used immediately.

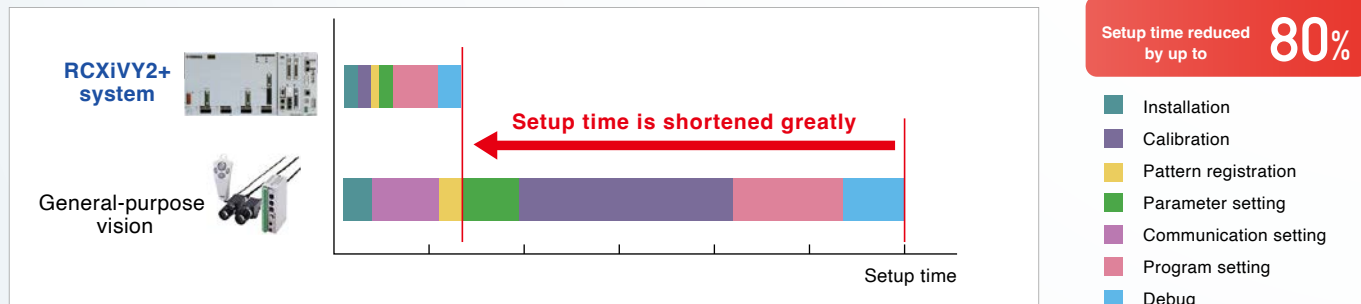


[Setup time reduced greatly]

When using third-party vision, a coordinate conversion program needs to be created in the robot controller since the robot coordinate data differs from the vision format.

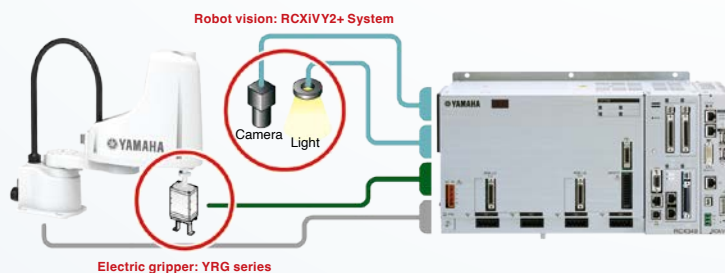
In RCXiVY2+, vision system is incorporated in robot controller the robot coordinate data can be stored into the robot point data using single process. This ensures very simple operation. Additionally, the unified control of the camera control and light control can be performed using the robot program. Start-up process will be greatly simplified.

Comparison of setup time

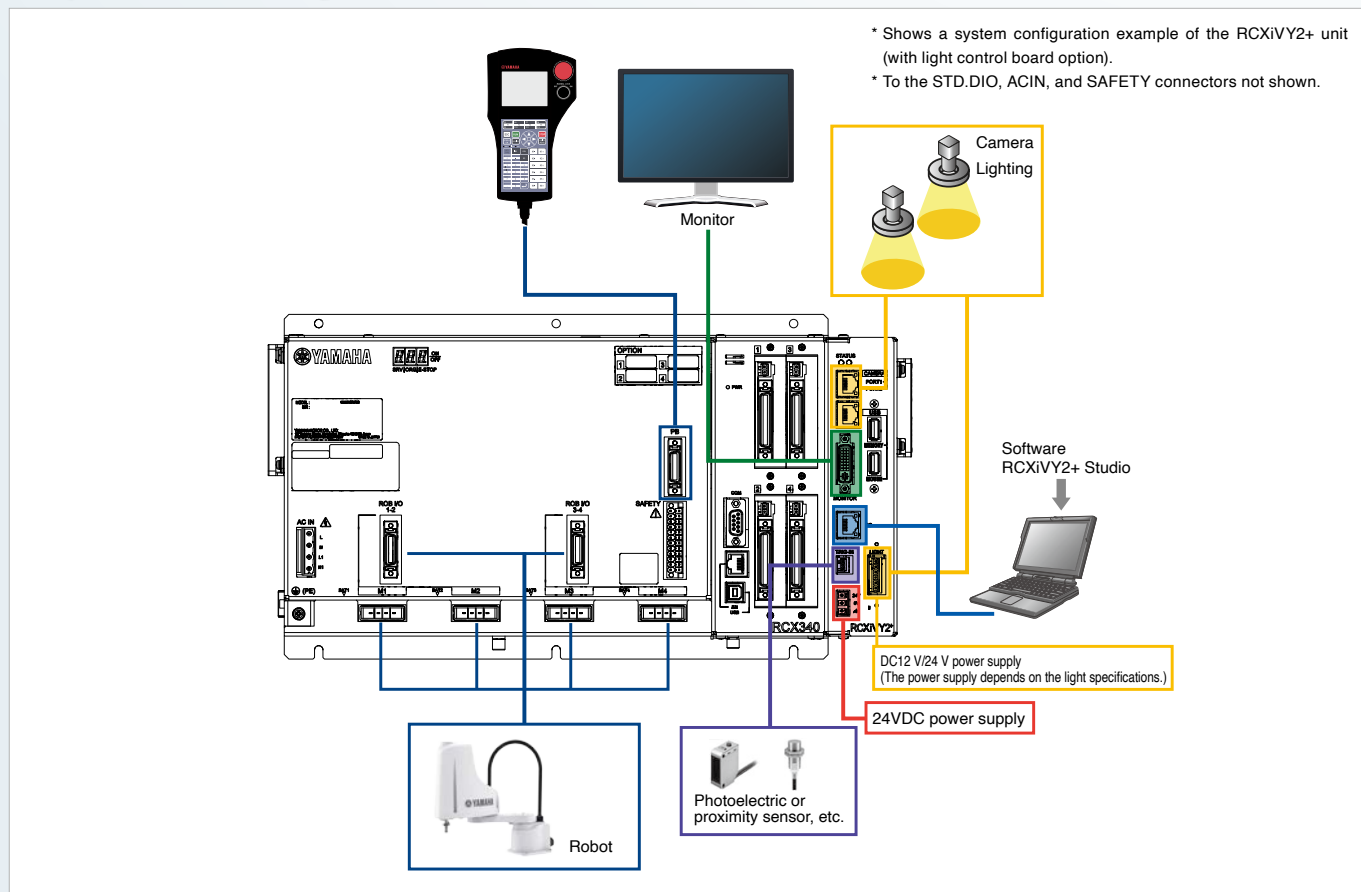


[Easy link with peripheral equipment]

One controller provides unified control of robot, gripper, and lighting.



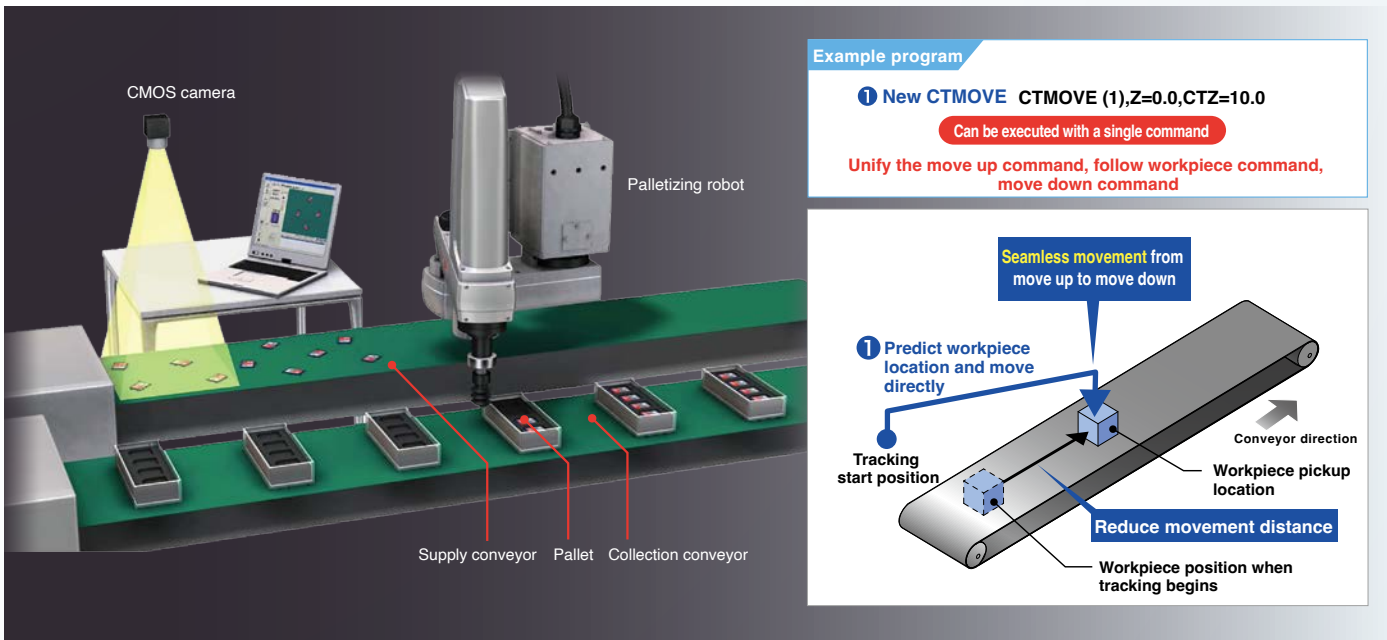
[System configuration illustration]



[Conveyor tracking]

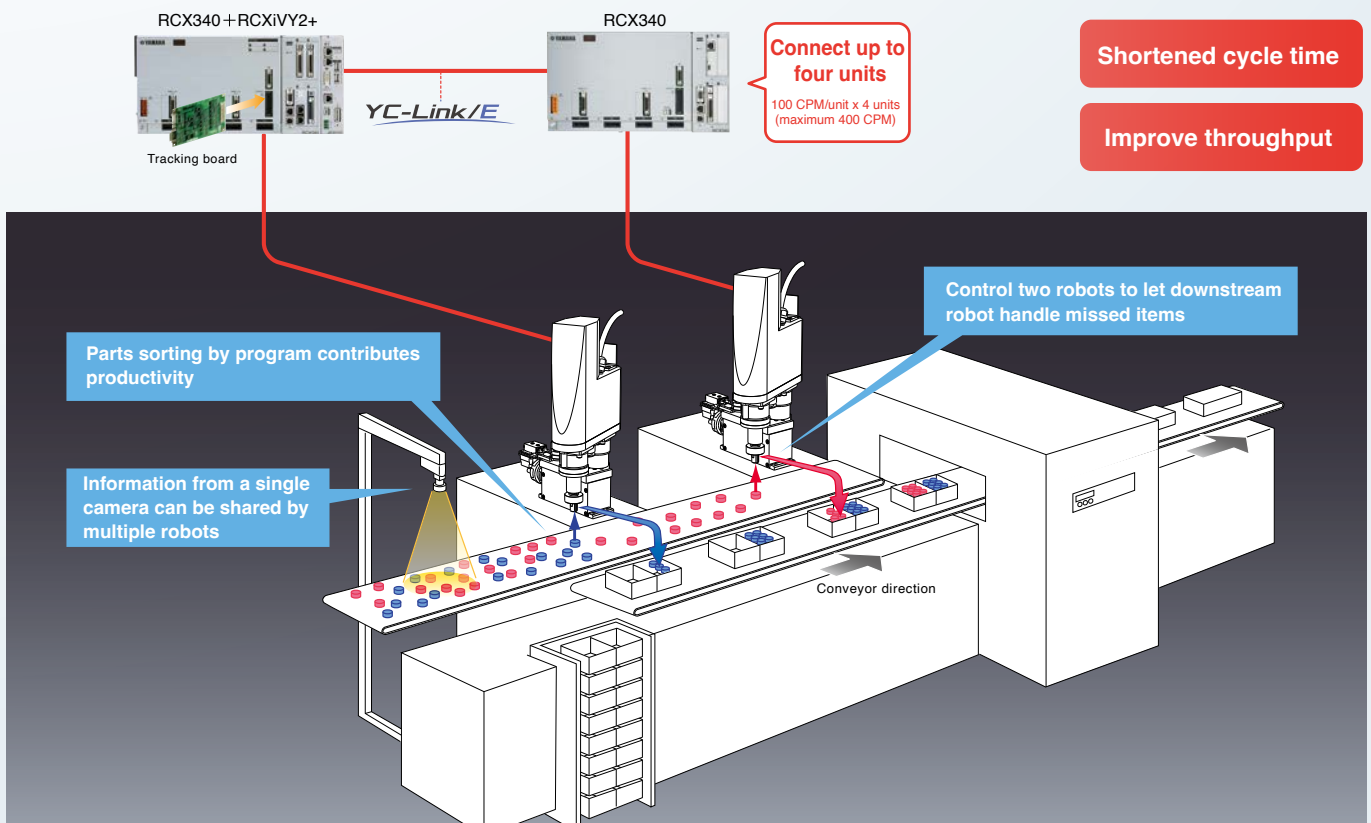
Ideal for high-speed packaging arrangement high-speed transport of multiple types of items such as pharmaceuticals, cosmetics, and food products.

The vision camera detects the position and orientation of parts moving on the conveyor, and the robot picks them up.



Operating conditions: YK500XG / payload 1 kg (total of workpiece and tool) / horizontal movement 250 mm / vertical movement 1 mm / conveyor speed 100 mm/sec

[Improving productivity by controlling multiple robot systems]



[Up to 254 types of parts registration]

Setup changes require only that part numbers be changed. Setup changes are easy.

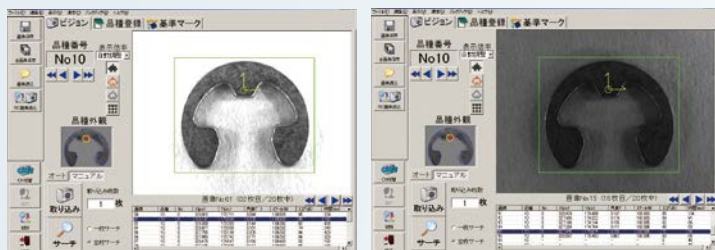
254 types (0-253) can be registered



[High-precision search even under low light]

Edge search engine is built-in

Supports a variety of applications while being minimally affected by the external environment.



When lighting is sufficient

Accurate search even if lighting is insufficient

[Monitor output]

Monitor the operating status

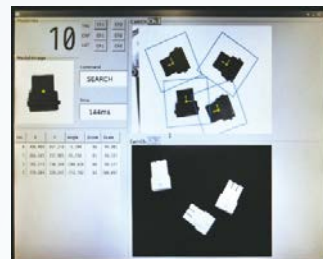
Monitor the search status while making calibration settings or during automatic operation.

Contents of output

- Selected type / Captured image
- Search result (position, score, scale)
- Executed command
- Time required by command

Output method

- DVI-I (supports digital monitor or analog monitor)



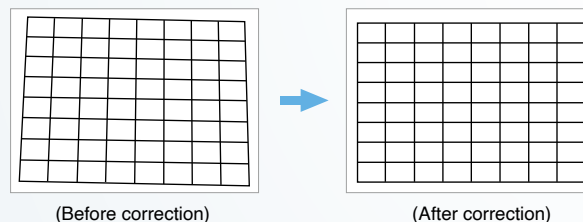
[Lens distortion and camera inclination correction function]

Mounting accuracy is improved. Camera is installed in the inclined status. *

* Up to approx. 15 degrees

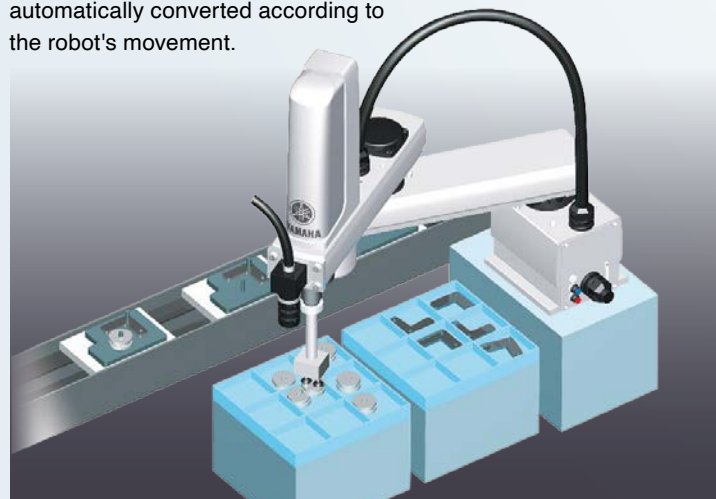
The lens distortion and camera inclination when the angle of visibility is wide or when the camera is installed in the inclined status can be corrected.

When the distortion and inclination correction function is enabled during calibration, the calibration data for the distortion and inclination correction is created. When images are captured using this calibration data, captured images are corrected and output.



[Also supports moving camera]

Even if the camera is mounted on the robot, coordinates are automatically converted according to the robot's movement.



Camera position can be selected in accordance with the application.

Fixed camera

Fixed downward.

Fixed upward.

Movable camera

SCARA robots

Cartesian robots

Even when the camera is moved, the coordinates are corrected automatically.

[Easy-to-use programming software RCXiVY2+ Studio]

With programming software "RCXiVY2+ Studio", all vision related operations such as registration of fiducial marks and workpieces used for calibration (contour settings, various parameter settings, and read range settings), backup, restore operation, and operation monitor can be performed.

- Search trial-run, part type registration
- Reference mark registration (for calibration)
- Up to 254 workpiece types can be registered.
- Workpiece can also be added easily.
- Up to 100 workpieces can be detected at once.
- Data backup
- This software functions as a monitor during program operation.



Download from
website
(member site)

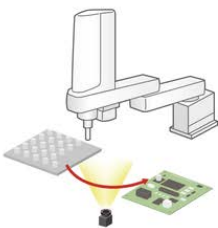
[Easy programming]

Constructing the most suitable robot vision system for an application.

RCX-Studio 2020 program template function

- ◆ Program is created automatically simply following step-by-step operating process

RCX3 series programming software RCX-Studio 2020 also has following five templates for vision system:



- Pallet picking using the vision
- Dispensing work using the vision
- Gripping deviation correction using the vision
- Gripping deviation and mounting position correction using the vision
- Gripping deviation and mounting position correction using the vision (without using any master)



Wide variety of robot system to choose from
most suitable and economical solution for robot vision system



XY-X Cartesian robots

YK-XG/XE SCARA robots

Clean SCARA robots

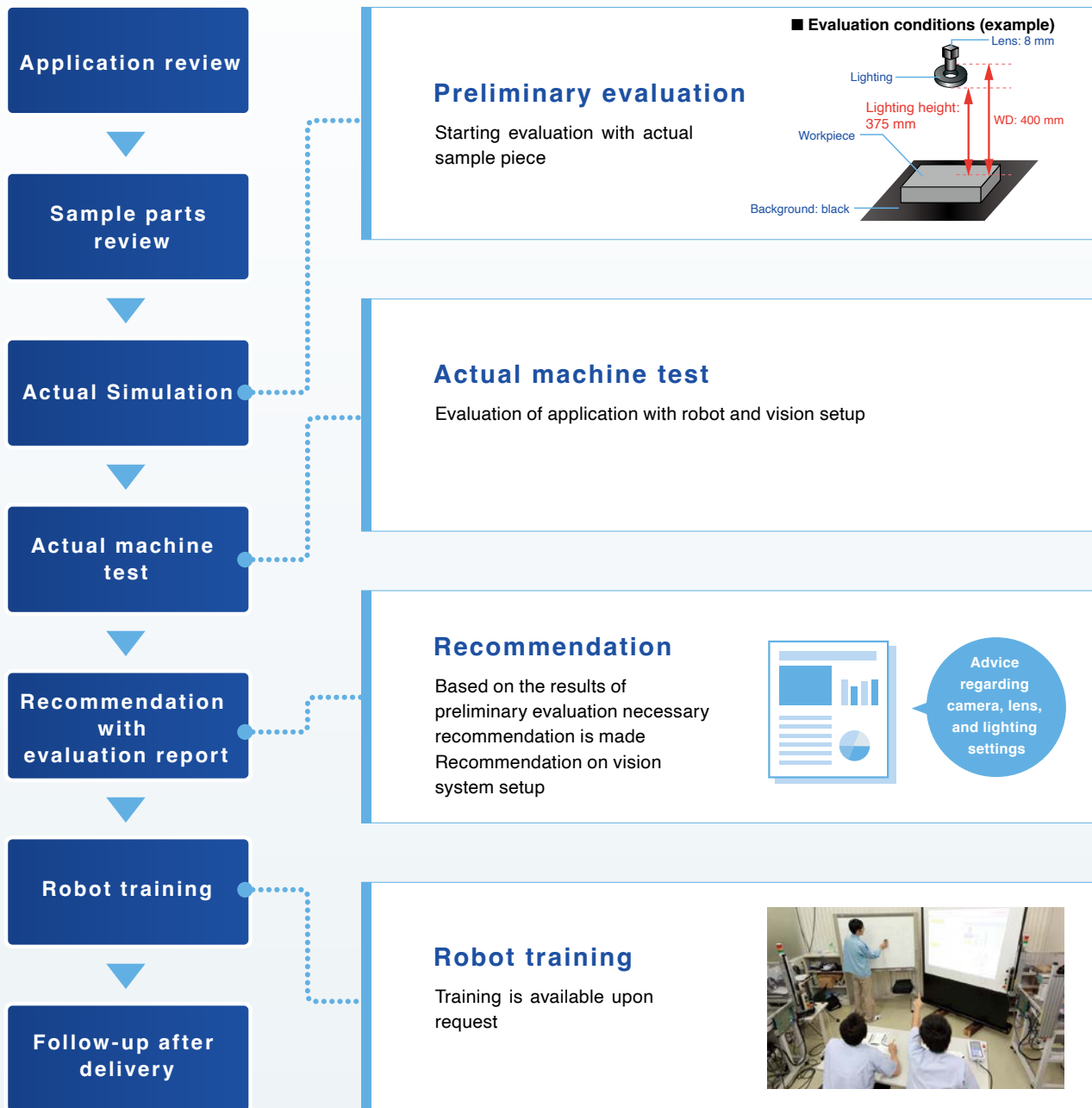
YK-TW orbit type robots

FLIP-X single-axis robots

[Verifying application prior to purchase]

User's application is verified using actual sample parts before making a purchase decision.

Based on the evaluation result, recommendation will be made for most suitable and economical solution.



*Sales of "iVY2" ended at the end of December 2020.

► For customers who consider to replace "iVY2" with "RCXiVY2+"

Workpieces that have been able to be recognized by the iVY2 system can also be detected by the RCXiVY2+ system under the same conditions without changing the installation position.

Therefore, it is not necessary to evaluate the workpieces again.

However, the exposure time and aperture may need to be adjusted.

In addition, since the installation hole positions of the camera are changed, the plate of the installation section needs to be changed.

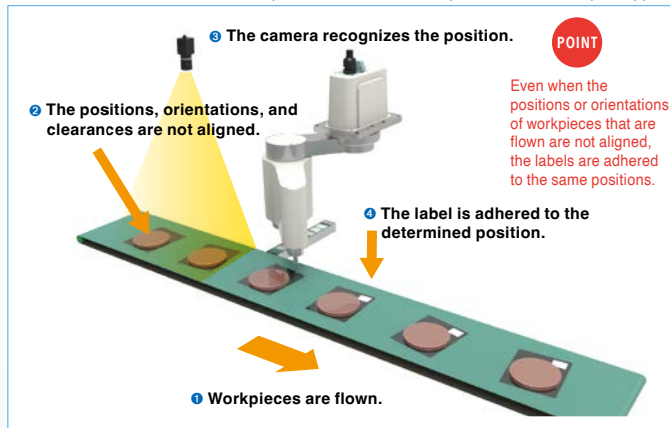
[Lot application examples]

Application

1

Random flow of parts on conveyor

The workpiece positions are recognized by the camera and the labels are adhered to the determined positions on workpieces. The adhesion position can also be specified for each part type.

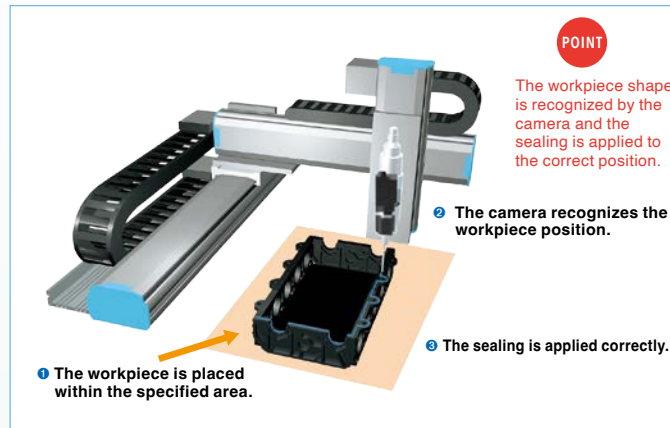


Application

2

Automatically adjusting sealing points

Position of workpiece is correctly recognized by its shape. Changing setup or jig between production lot can be eliminated.

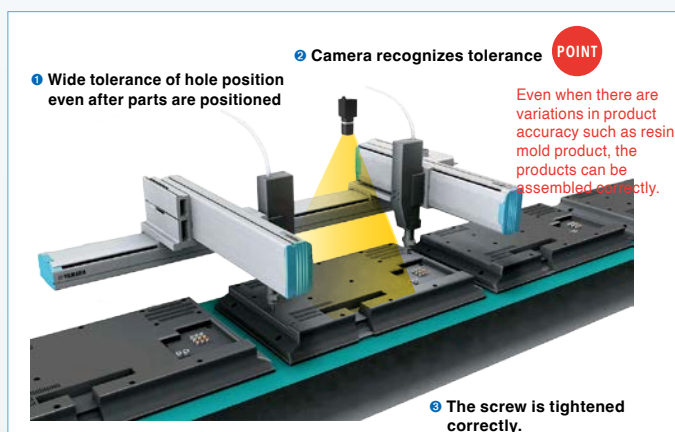


Application

3

Adjusting screw fastening position

Vision camera recognizes actual hole position with wide tolerance and adjust fastening position.

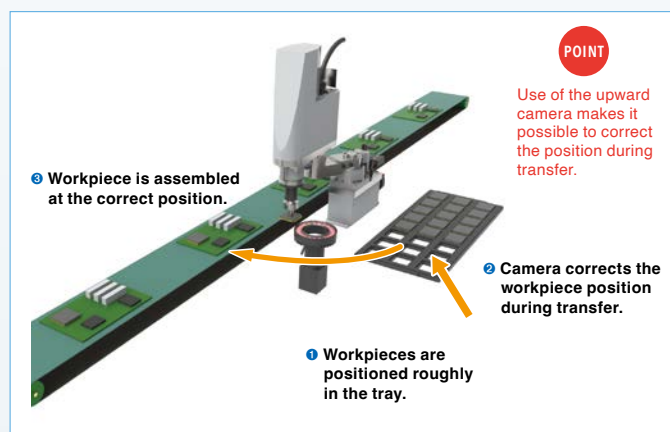


Application

4

“Pick-and-Assemble” in one motion

Pick up parts from a tray, adjust position on the fly and install directly.

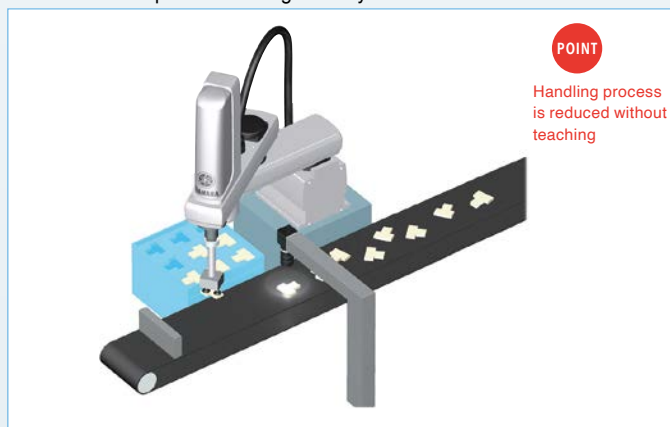


Application

5

Conveyor tracking

Pick-and-place operation of randomly positioned parts on conveyor by SCARA robot. Position and orientation of parts are recognized by vision camera.

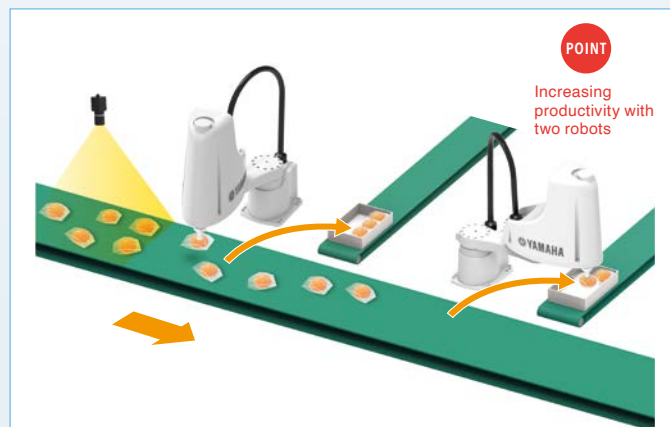


Application

6

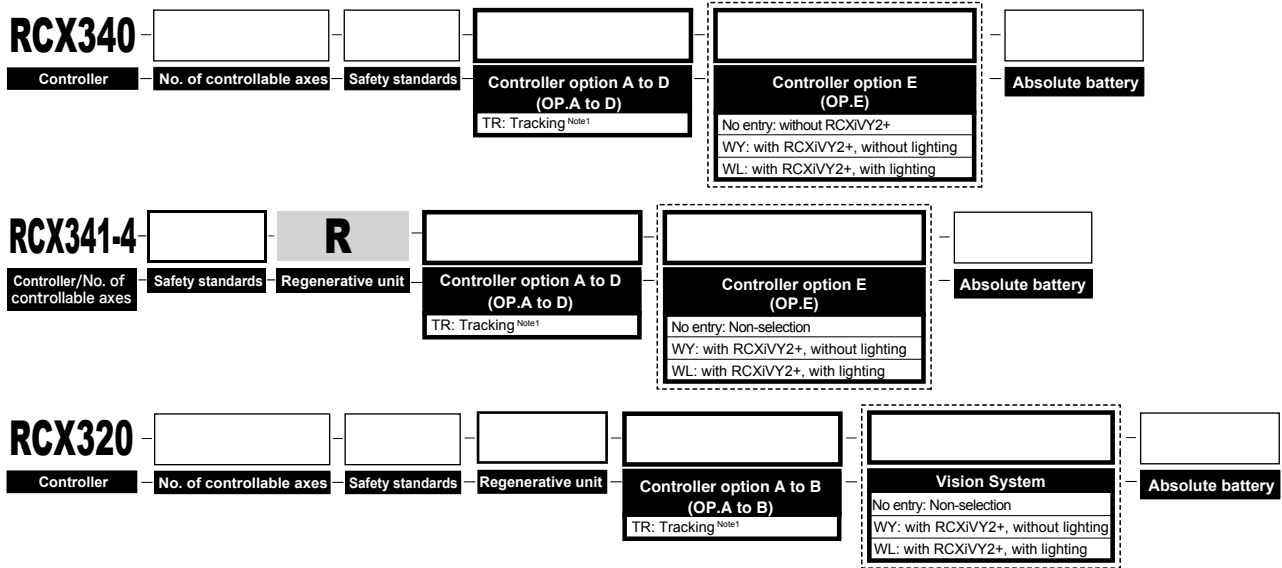
Irregular shape workpieces such as foods and clothes

Pick-and-place with conveyor tracking for parts with wide tolerance like foods and clothes.



Ordering method / Basic specifications

● Ordering method



Note1. Only one tracking board can be selected.

● Refer to the comprehensive catalog for details on the order format.

● Robot vision basic specifications

Item		RCXiVY2+ unit
Basic specifications	Applicable controllers	RCX340/RCX341/RCX320
	Number of screen pixels	720(H) × 540(V) (400,000 pixels) 1440(H) × 1080(V) (1,600,000 pixels) 2048(H) × 1536(V) (3,200,000 pixels) 2592(H) × 1944(V) (5,000,000 pixels) ^{Note1}
	Model setting capacity	254 models
	Number of connectable cameras	2 cameras (8 units when the HUB is used.)
	Connectable camera	GigE camera PoE: IEEE802.3af 1 ch up to 7W
	External interface	Ethernet (1000BASE-T) ^{Note2} USB 2.0 2Ch (Up to 5V 2.5W / ch)
	External monitor output	DVI-I ^{Note4} Monitor resolution: 1024 × 768 Vertical periodic frequency: 60 Hz Horizontal periodic frequency: 48.4 kHz
	Power supply	24 VDC +/-10%, Maximum 1.5 A
	Dimensions	W45 × H195 × D130 (RCXiVY2+ unit only)
	Weight	0.8kg (RCXiVY2+ unit only, when the lighting control board option is selected)
	Operating environment	Compliant with the RCX340/RCX341/RCX320 controller.
	Storage environment	Compliant with the RCX340/RCX341/RCX320 controller.
Search method		Edge search, Measuring search, Blob search, Code search
Image capturing	Trigger mode	S/W trigger, H/W trigger
	External trigger input	2 points
Function		Position detection, coordinate conversion, automatic point data generation, distortion and inclination correction
Camera installation position		Fixed to the fixed camera (up, down) or robot (Y-axis, Z-axis). Vertical direction to the image capturing target workpiece is recommended.
Setting support function		Calibration, image save function, model registration ^{Note4} , fiducial mark registration ^{Note4} , measuring registration ^{Note4} , blob registration ^{Note4} , code registration ^{Note4} , monitor function ^{Note4}
Lighting control options	Number of connectable lighting units	Maximum 2
	Modulated light format	PWM modulated light control (0 to 100%), PWM frequency switchable 62.5 kHz/ 125 kHz Continuous light, strobe light (follows camera exposure)
	Lighting power input	12VDC or 24VDC (external supply shared by both channels)
	Lighting output	For 12VDC supply: Total of less than 40W for both channels. For 24VDC supply: Total of less than 80W for both channels.

Note1. Since the rolling shutter is used, the tracking is not supported.

Note2. For setting and monitor operations

Note3. Also usable with an analog monitor by using a conversion adaptor.

Note4. RCXiVY2+ Studio function (requires a Windows PC)

● Tracking board basic Specifications

Item		Tracking board
Basic specifications	Applicable controllers	RCX340/RCX341/RCX320
	Number of connected encoders	Up to 2 units.
	Encoder power supply	5VDC (2 counters total 500 mA or less) (Supplied from controller)
	Applicable encoder	26LS31/26C31 or equivalent line driver (RS-422 compliance).
	Input phase	A, \bar{A} , B, \bar{B} , Z, \bar{Z}
	Max. response frequency	2MHz or less
	Counter	0 to 65535
	Multiplier	4x
	Other	With disconnection detection function

Accessories and part options

Standard accessories

● RCiVY2+ unit

The RCiVY2+ unit adds robot vision to the RCX340/RCX320 robot controller.



Model	No lighting	KFR-M4400-V0
	With lighting	KFR-M4400-L0

• RCiVY2+ unit accessories

Name	Model
Trigger input cable connector set	KX0-M657K-00
24V power supply connector	KCF-M5382-00

● Support software for PC RCiVY2+ Studio

RCiVY2+ Studio is programming software for the RCiVY2+ system that allows registering part types and reference marks as well as monitoring the work search status during automatic robot operation by connecting to the robot controller.

[Download from website \(member site\)](#)



■ Environment

OS	Microsoft Windows XP / Vista (32 bit / 64 bit) / 7 (32 bit / 64 bit) / 8, 8.1 (32 bit / 64 bit) / 10 (32 bit / 64 bit) 11 (Compatible version V3.2.5~)
CPU	Processor that meets or exceeds the suggested requirements for the OS being used.
Memory	Suggested amount of memory or more for the OS being used.
Hard disk capacity	30MB of available space required on installation drive. * Additional vacant space is required for saving images and data.
Display	800 x 600 dot, or higher, 32768 colors (16bit High Color) or higher (recommended)
Communication Port	Ethernet Port of TCP/IP

* Microsoft, Windows XP, Windows Vista, Windows 7, Windows 8, 8.1, Windows 10 and Windows 11 are registered trademarks of the Microsoft Corporation, USA.

* Ethernet is a registered trademark of the XEROX Corporation, USA.

Options

● CMOS camera



Model	400,000 pixel	720(H) × 540(V)	KFR-M6541-01
	1,600,000 pixel	1440(H) × 1080(V)	KFR-M6541-11
	3,200,000 pixel	2048(H) × 1536(V)	KFR-M6541-21
	5,000,000 pixel	2592(H) × 1944(V)	KFR-M6541-32

● Lens



Model	8mm	KCX-M7214-00
	12mm	KCX-M7214-10
	16mm	KCX-M7214-20
	25mm	KCX-M7214-30
	8mm (megapixel support)	KCX-M7214-40
	12mm (megapixel support)	KCX-M7214-50
	16mm (megapixel support)	KCX-M7214-60
	25mm (megapixel support)	KCX-M7214-70

* Common to iVY2.

● Close-up ring



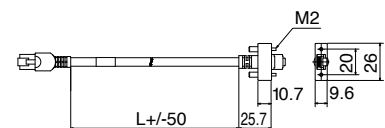
Model	0.5mm	KX0-M7215-00
	1.0mm	KX0-M7215-10
	2.0mm	KX0-M7215-20
	5.0mm	KX0-M7215-40

● Camera cable

Cable for connecting the camera to the RCiVY2+ unit.

Cable length (L)	Model
5m	KCX-M66F0-00
10m	KCX-M66F0-10
15m	KCX-M66F0-20

External diagram of camera cable



* Common to iVY2.

● Lighting control board

This board adds lighting control functionality to the RCiVY2+ system. (Installed in the RCiVY2+ unit when shipped)

Name	Model
Lighting control board	KCX-M4403-L0

• Lighting control board accessories

Name	Model
Lighting power cable connector set	KX0-M657K-10

● Tracking board

This board adds conveyor tracking functionality to the RCX340/RCX320 controller.

Name	Model
Tracking board	KCX-M4400-T0

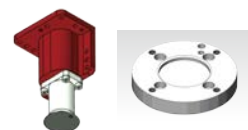
• Tracking board accessories

Name	Model
Tracking encoder connector	KX0-M657K-20

● Calibration jig

(Large and small attachments are provided.)

Model	KCX-M7200-00
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● LAN cable with shield cloth (5 m)

Model	KX0-M55G0-00
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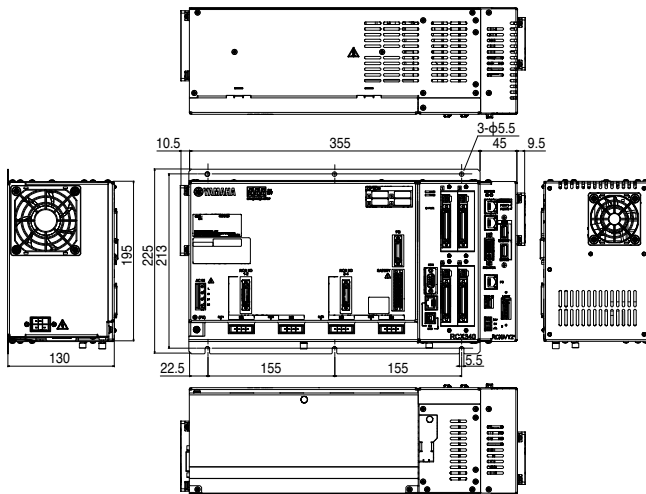
● Tracking encoder cable (10 m)

Model	When one encoder is connected.	KX0-M66AF-00
	When two encoders are connected.	KCX-M66AF-10



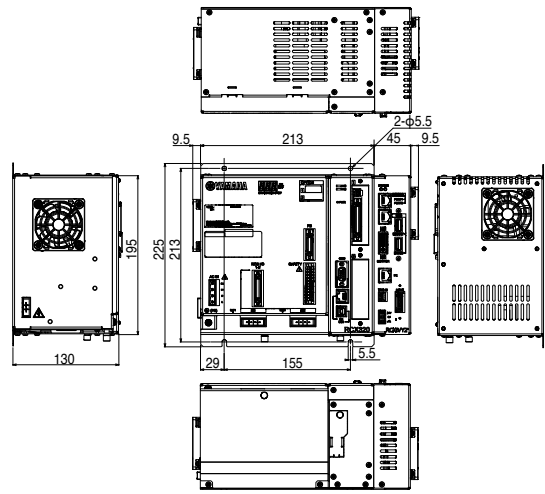
Dimensional outlines

RCX340/RCX341 + RCXiVY2+



Note. RCX341 comes with an external regenerative unit.

RCX320 + RCXiVY2+

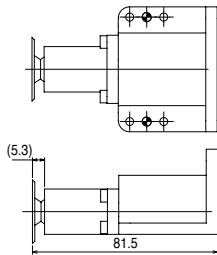


Calibration jig

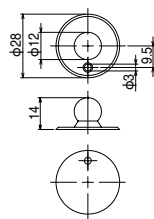
Calibration jig

Model: KCX-M7200-00

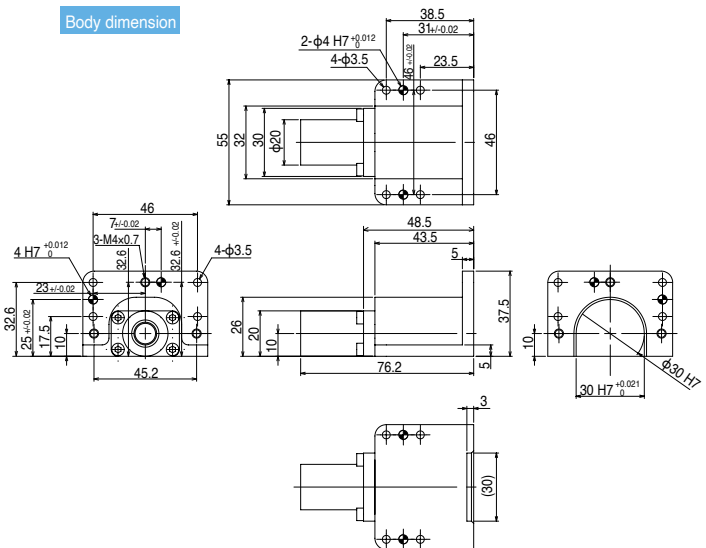
Mark gripper dimension



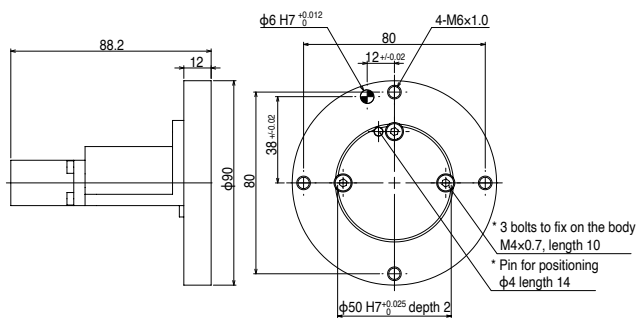
Mark dimension



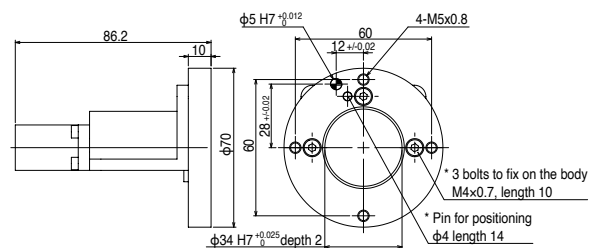
Body dimension



When using attachment (large)



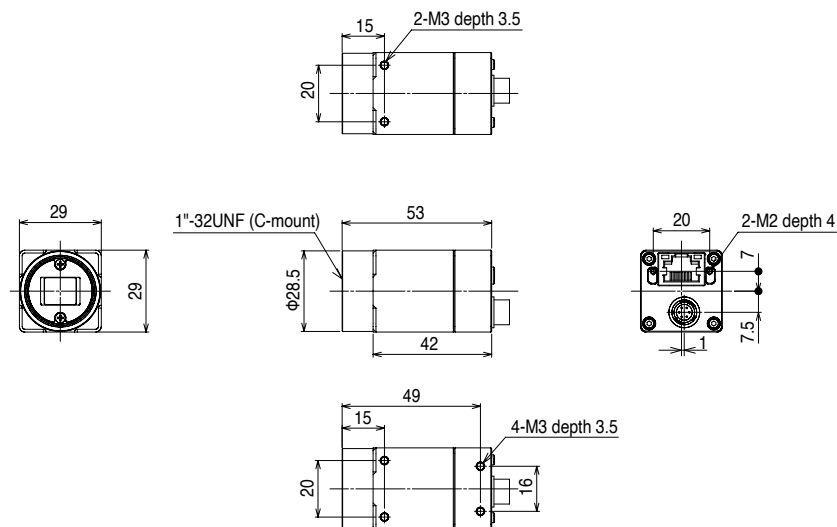
When using attachment (small)



Dimensional outlines

Camera

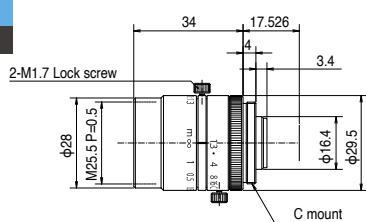
- **CMOS camera** (400,000 pixel / 1,600,000 pixel / 3,200,000 pixel / 5,000,000 pixel)



Lenses

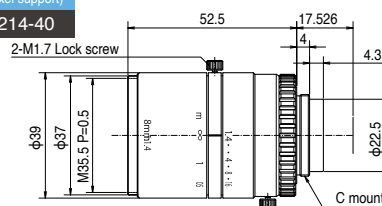
8 mm lens

Model: KCX-M7214-00



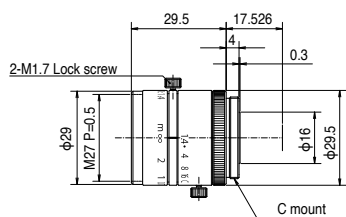
8 mm lens (megapixel support)

Model: KCX-M7214-40



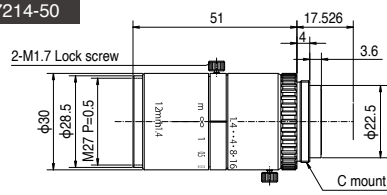
12 mm lens

Model: KCX-M7214-10



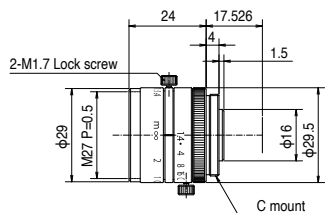
12 mm lens (megapixel support)

Model: KCX-M7214-50



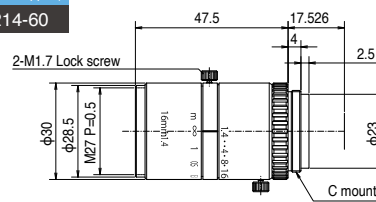
16 mm lens

Model: KCX-M7214-20



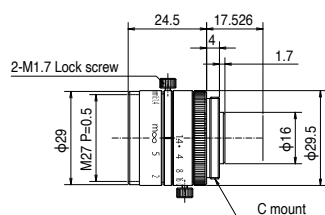
16 mm lens (megapixel support)

Model: KCX-M7214-60



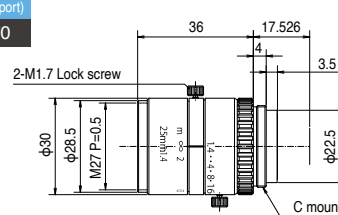
25 mm lens

Model: KCX-M7214-30



25 mm lens (megapixel support)

Model: KCX-M7214-70



Lens characteristics/Contact angle ⇔ WD (workpiece distance) table

● Lens characteristics

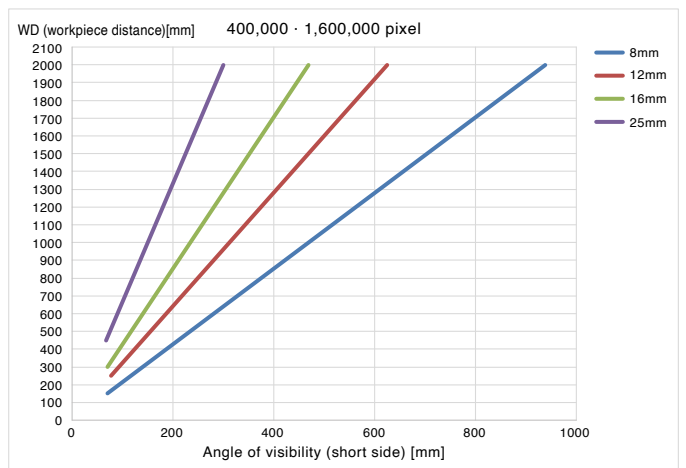
Lens	Model	Focal length [mm]	Aperture value [F No.]	Angle-of-view (degrees)								Closest approach distance [m]
				KFR-M6541-01 (400,000 pixel camera)		KFR-M6541-11 (1,600,000 pixel camera)		KFR-M6541-21 (3,200,000 pixel camera)		KFR-M6541-32 (5,000,000 pixel camera)		
				Vertical	Horizontal	Vertical	Horizontal	Vertical	Horizontal	Vertical	Horizontal	
8mm	KCX-M7214-00	8	F1.3-CLOSE	27.13	36.09	26.85	35.69	37.57	49.23	30.72	40.60	0.2
12mm	KCX-M7214-10	12	F1.4-CLOSE	17.23	23.01	17.05	22.74	24.11	31.95	19.57	26.03	0.3
16mm	KCX-M7214-20	16	F1.4-CLOSE	13.17	17.50	13.03	17.30	18.48	24.44	14.97	19.83	0.4
25mm	KCX-M7214-30	25	F1.4-CLOSE	8.57	11.42	8.47	11.29	12.05	16.01	9.74	12.95	0.5
8mm (megapixel support)	KCX-M7214-40	8	F1.4-F16	26.47	34.83	26.20	34.44	36.68	47.61	29.97	39.21	0.1
12mm (megapixel support)	KCX-M7214-50	12	F1.4-F16	17.49	23.19	17.31	22.92	24.47	32.19	19.86	26.23	0.1
16mm (megapixel support)	KCX-M7214-60	16	F1.4-F16	13.28	17.69	13.14	17.48	18.64	24.69	15.09	20.04	0.1
25mm (megapixel support)	KCX-M7214-70	25	F1.4-F16	8.62	11.48	8.52	11.34	12.12	16.09	9.80	13.02	0.15

Note. This table shows the angle-of-view for Yamaha's standard lenses. If the angle-of-view is greater, there might be more distortion at the edge of the image.

● Contact angle ⇔ WD (workpiece distance) table

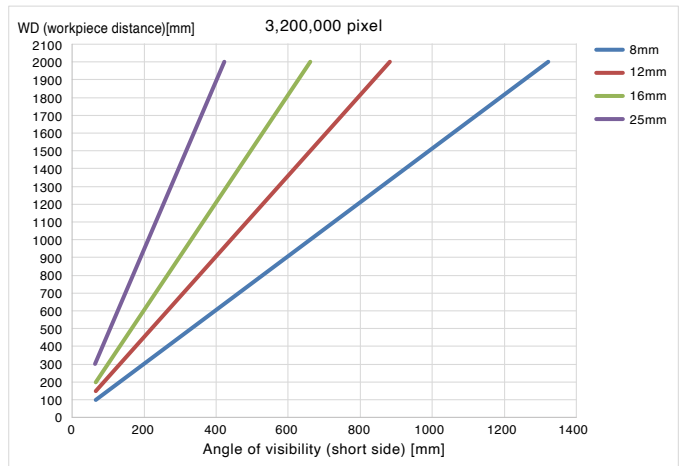
400,000 pixel (KFR-M6541-01) · 1,600,000 pixel (KFR-M6541-11)

WD (workpiece distance)	Lens							
	8mm KCX-M7214-40		12mm KCX-M7214-50		16mm KCX-M7214-60		25mm KCX-M7214-70	
	Horizontal	Vertical	Horizontal	Vertical	Horizontal	Vertical	Horizontal	Vertical
100	63	47	42	31	31	23	30	23
150	94	70	63	47	47	35	40	30
200	126	94	84	63	63	47	50	38
250	157	117	105	78	78	59	60	45
300	188	141	126	94	94	70	70	53
350	220	164	146	109	110	82	82	60
400	251	188	167	125	126	94	80	68
450	282	211	188	141	141	105	90	75
500	314	234	209	156	157	117	100	83
550	345	258	230	172	173	129	110	90
600	377	281	251	188	188	141	120	98
650	408	305	272	203	204	152	131	105
700	439	328	293	219	220	164	141	113
750	471	352	314	234	235	176	151	120
800	502	375	335	250	251	188	161	128
850	533	398	356	266	267	199	171	135
900	565	422	377	281	282	211	181	143
950	596	445	397	297	298	223	191	150
1000	628	469	418	313	314	234	201	157
1500	941	703	628	469	471	352	301	225
2000	1255	938	837	625	628	469	402	300



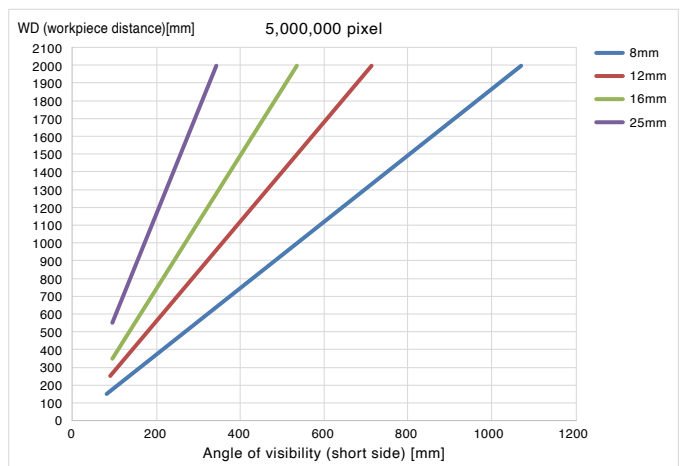
3,200,000 pixel (KFR-M6541-21)

WD (workpiece distance)	Lens							
	8mm KCX-M7214-40		12mm KCX-M7214-50		16mm KCX-M7214-60		25mm KCX-M7214-70	
	Horizontal	Vertical	Horizontal	Vertical	Horizontal	Vertical	Horizontal	Vertical
100	88	66	59	44	44	33	42	32
150	132	99	88	66	66	50	56	42
200	177	132	118	88	88	66	71	53
250	221	165	147	110	110	83	85	63
300	265	198	177	132	132	99	99	74
350	309	231	206	154	154	116	113	85
400	353	265	235	176	177	132	127	95
450	397	298	265	198	199	149	141	106
500	441	331	294	220	221	165	155	116
550	485	364	324	242	243	182	169	127
600	530	397	353	265	265	198	184	138
650	574	430	382	287	287	215	198	148
700	618	463	412	309	309	231	212	159
750	662	496	441	331	331	248	226	169
800	706	529	471	353	353	265	240	180
850	750	562	500	375	375	281	254	190
900	794	595	530	397	397	298	268	201
950	838	628	559	419	419	314	282	212
1000	883	661	588	441	441	331	296	222
1500	1324	992	883	661	662	496	424	317
2000	1765	1323	1177	882	883	661	565	423



5,000,000 pixel (KFR-M6541-32)

WD (workpiece distance)	Lens							
	8mm KCX-M7214-40		12mm KCX-M7214-50		16mm KCX-M7214-60		25mm KCX-M7214-70	
	Horizontal	Vertical	Horizontal	Vertical	Horizontal	Vertical	Horizontal	Vertical
100	71	54	48	36	36	27	34	26
150	107	80	71	54	53	40	46	34
200	143	107	95	71	71	54	57	43
250	178	134	119	89	89	67	68	51
300	214	161	143	107	107	80	80	60
350	249	187	166	125	125	94	91	68
400	285	214	190	143	143	107	103	77
450	321	241	214	161	160	120	114	86
500	356	268	238	178	178	134	125	94
550	392	294	261	196	196	147	137	103
600	428	321	285	214	214	161	148	111
650	463	348	309	232	232	174	160	120
700	499	375	333	250	249	187	171	128
750	534	401	356	268	267	201	182	137
800	570	428	380	285	285	214	194	146
850	606	455	404	303	303	227	205	154
900	641	482	428	321	321	241	217	163
950	677	508	451	339	338	254	228	171
1000	713	535	475	357	356	268	242	180
1500	1069	803	713	535	534	401	342	257
2000	1425	1070	950	713	713	535	456	342

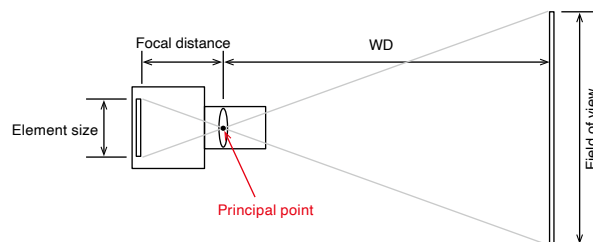


Minimum WD (workpiece distance) when close-up ring is used.

● Minimum WD (workpiece distance) when close-up ring is used.

Close-up ring [mm]	Lens							
	8mm KCX-M7 214-40		12mm KCX-M7 214-50		16mm KCX-M7 214-60		25mm KCX-M7 214-70	
	Minimum	Maximum	Minimum	Maximum	Minimum	Maximum	Minimum	Maximum
None	100	∞	100	∞	100	∞	150	∞
0.5	46	114	67	284	78	506	131	1233
1.0			48	132	63	243	115	608
1.5			36	82	52	116	102	399
2.0					43	112	92	295
5.0							54	108

* The values in this table are for reference only and are not absolute indexes.

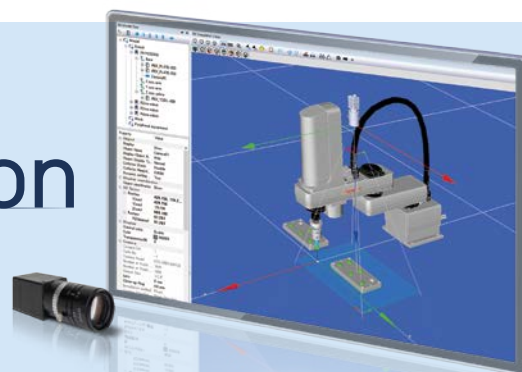


* All values in the table are based on the principal point.

PC-based Machine Vision

RCXiVY2+ PCVision

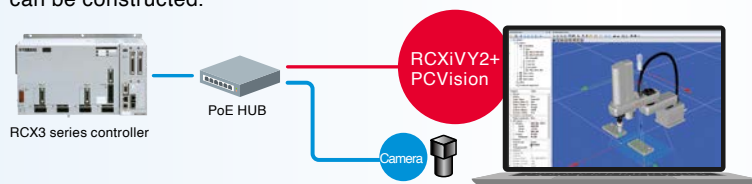
PCVision provides the same ease of use and affinity with robots as the RCXiVY2+ system.



What is "RCXiVY2+ PCVision"?

Apps working as RCXiVY2+ on Windows.

By connecting the PC into which this software has been installed to the RCX controller, a PC vision system that is equivalent to the "RCXiVY2+ System" can be constructed.



"Robot+ vision" allows you to perform the simulation.

If you have a PC and camera, you can perform the recognition test of workpieces.

High-pixel camera up to 25 megapixels is supported.

For details, scan the QR code shown on the right.



Safety Precautions

Read the instruction manual thoroughly to operate the robot in a correct manner.



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URL <https://global.yamaha-motor.com/business/robot/>