

T4LH

● Origin on the non-motor side is selectable

● Controller: 100V / 200V



Ordering method

T4LH

Model	Lead designation	Brake	Origin position change	Grease type	Stroke	Cable length ^{Note 1}
	12: 12mm 6: 6mm 2: 2mm	No entry: No brakes BK: Brakes provided	None: Standard Z: Non-motor side	None: Standard GC: Clean	50 to 400 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX

Positioner ^{Note 2}	Driver: Power-supply voltage / Power capacity	LCD monitor	I/O selection	Battery
TS-X	105: 100V/100W or less 205: 200V/100W or less	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board ^{Note 3}	B: With battery (Absolute) N: None (Incremental)

SR1-X

Controller	Driver: Power capacity	Usable for CE	I/O selection	Battery
05	05: 100W or less	No entry: Standard E: CE marking	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X

Driver	Power-supply voltage	Driver: Power capacity
2	2: AC200V	05: 100W or less

Note 1. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.614 for details on robot cable.

Note 2. See P.522 for DIN rail mounting bracket.

Note 3. Select this selection when using the gateway function. For details, see P.66.

Specifications

AC servo motor output (W)	30
Repeatability ^{Note 1} (mm)	+/-0.02
Deceleration mechanism	Ball screw φ8
Ball screw lead (mm)	12 6 2
Maximum speed (mm/sec)	720 360 120
Maximum payload (kg)	Horizontal: 4.5, 6, 6 Vertical: 1.2, 2.4, 7.2
Rated thrust (N)	32 64 153
Stroke (mm)	50 to 400 (50mm pitch)
Overall length (mm)	Horizontal: Stroke+198 Vertical: Stroke+236
Maximum dimensions of cross section of main unit (mm)	W45 × H53
Cable length (m)	Standard: 3.5 / Option: 5,10
Linear guide type	2 rows of gothic arch grooves × 1 rail
Position detector	Resolvers ^{Note 2}
Resolution (Pulse/rotation)	16384

Note 1. Positioning repeatability in one direction.

Note 2. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang^{Note}

Horizontal installation (Unit: mm)				Wall installation (Unit: mm)				Vertical installation (Unit: mm)		
	A	B	C		A	B	C		A	C
Lead 12	2kg	341	90	174	2kg	140	73	300		
	4.5kg	172	37	72		4.5kg	47	22	119	
Lead 6	3kg	355	58	134	3kg	105	42	260		
	6kg	235	27	62		6kg	31	11	135	
Lead 2	3kg	1105	59	142	3kg	113	42	810		
	6kg	520	27	66		6kg	32	11	305	

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Note. Service life is calculated for 300mm stroke models.

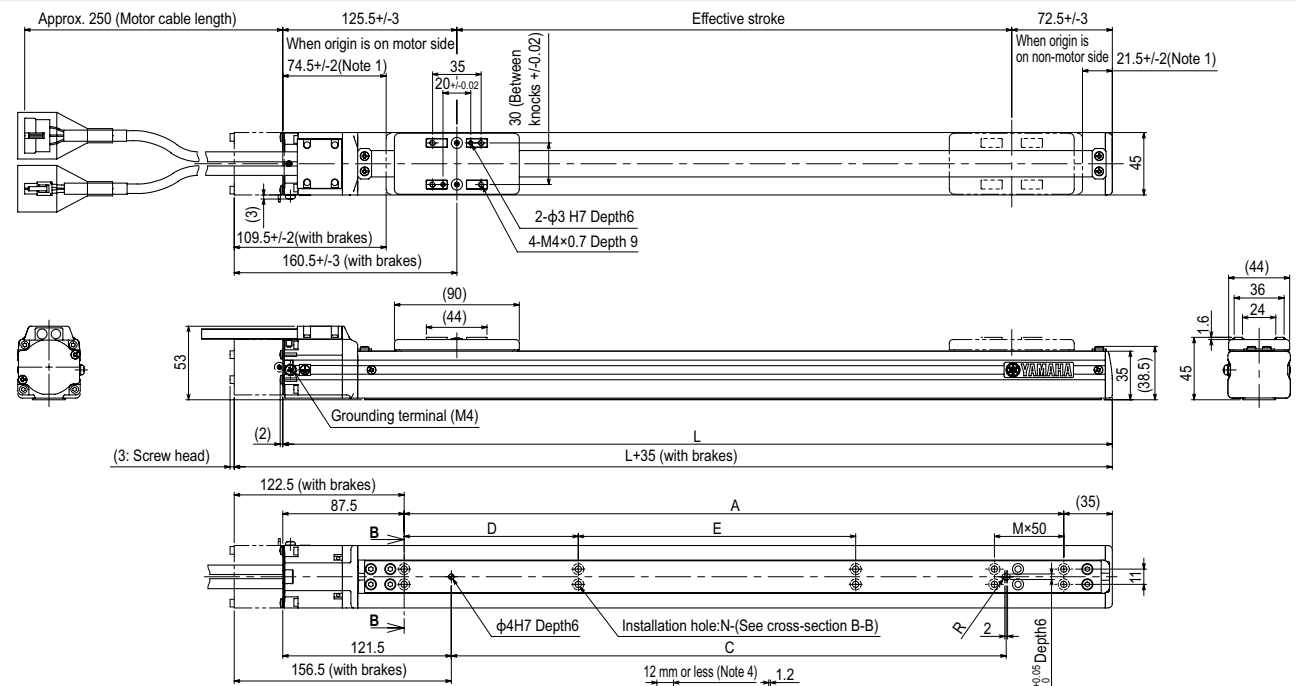
Static loading moment

(Unit: N·m)		
MY	MP	MR
15	19	18

Controller

Controller	Operation method
SR1-X05	Programming / I/O point trace / Remote command / Operation using RS-232C communication
RCX320	
RCX221/222	
RCX340	
TS-X105	I/O point trace / Remote command
TS-X205	
RDV-X205	Pulse train control

T4LH



Effective stroke	50	100	150	200	250	300	350	400
L	248	298	348	398	448	498	548	598
A	125.5	175.5	225.5	275.5	325.5	375.5	425.5	475.5
C	50	100	150	200	250	300	350	400
D	-	-	-	-	125.5	125.5	125.5	125.5
E	-	-	-	-	-	200	200	200
M	0	1	2	3	0	1	0	1
N	4	6	8	10	6	8	8	10
Weight (kg) ^{Note 3}	1.1	1.2	1.4	1.5	1.6	1.7	1.8	1.9
Maximum speed for each stroke (mm/sec)	Lead 12	720						
	Lead 6	360						
	Lead 2	120						

Note 1. Stop positions are determined by the mechanical stoppers at both ends.

Note 2. Minimum bend radius of motor cable is R30.

Note 3. Weight of models with no brake. The weight of brake-attached models is 0.2 kg heavier than the models with no brake shown in the table.

Note 4. The under-head length of the hex socket-head bolt (M4×0.7) to be used for the installation work is 12mm or less.

Note 5. External view of T4LH is identical to T4L.