F8

- High lead: Lead 20
- Origin on the non-motor side is selectable

Ordering method

F8 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Lead designation	Brake Note 1	Origin position change	Grease type	Stroke	Cable length Note 2
	20: 20mm 12: 12mm 6: 6mm	No entry: No brakes BK: Brakes provided	None: Standard Z: Non-motor side	None: Standard GC: Clean	150 to 800 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX - [ ] - [ ] - [ ] - [ ]

Positioner Note 3	Driver: Power-supply voltage / Power capacity	LCD monitor	I/O selection	Battery
TSX: TS-X	105: 100V/100W or less 205: 200V/100W or less	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 4	B: With battery (Absolute) N: None (Incremental)

SR1-X - **05** - [ ] - [ ] - [ ]

Controller	Driver: Power capacity	Usable for CE	I/O selection	Battery
	05: 100W or less	No entry: Standard E: CE marking	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X - **2** - **05** - **RBR1**

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
	2: AC200V	05: 100W or less	

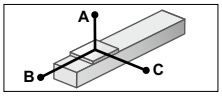
Note 1. The model with a lead of 20mm cannot select specifications with brake (vertical specifications).
Note 2. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.692 for details on robot cable.
Note 3. See P.600 for DIN rail mounting bracket.
Note 4. Select this selection when using the gateway function.

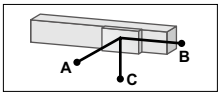
Specifications

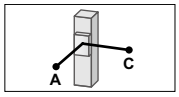
AC servo motor output (W)		100		
Repeatability Note 1 (mm)		+/-0.02		
Deceleration mechanism		Ball screw ϕ12		
Ball screw lead (mm)		20	12	6
Maximum speed Note 2 (mm/sec)		1200	720	360
Maximum payload (kg)	Horizontal	12	20	40
	Vertical	–	4	8
Rated thrust (N)		84	141	283
Stroke (mm)		150 to 800 (50mm pitch)		
Overall length (mm)	Horizontal	Stroke+286		
	Vertical	Stroke+316		
Maximum dimensions of cross section of main unit (mm)		W80 × H65		
Cable length (m)		Standard: 3.5 / Option: 5,10		
Linear guide type		4 rows of circular arc grooves × 1 rail		
Position detector		Resolvers Note 3		
Resolution (Pulse/rotation)		16384		

Note 1. Positioning repeatability in one direction.
Note 2. When the stroke is longer than 550mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
Note 3. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note







Horizontal installation (Unit: mm)

		A	B	C
Lead 20	5kg	197	76	120
	10kg	100	32	54
	12kg	85	25	43
Lead 12	5kg	364	89	188
	10kg	203	39	87
	15kg	139	22	51
	20kg	103	14	33
Lead 6	10kg	403	43	113
	20kg	214	16	43
	30kg	140	6	20
	40kg	113	0	8

Wall installation (Unit: mm)

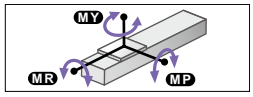
		A	B	C
Lead 20	5kg	104	67	174
	10kg	37	23	72
	12kg	27	15	55
Lead 12	5kg	171	81	340
	10kg	69	32	172
	15kg	33	15	100
	20kg	15	6	55
Lead 6	10kg	94	36	369
	20kg	25	9	157
	30kg	0	0	14
	40kg	0	0	0

Vertical installation (Unit: mm)

		A	C
Lead 12	1kg	447	448
	2kg	214	216
	3kg	137	138
	4kg	98	99
Lead 6	2kg	244	245
	4kg	113	113
	6kg	69	69
	8kg	46	46

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



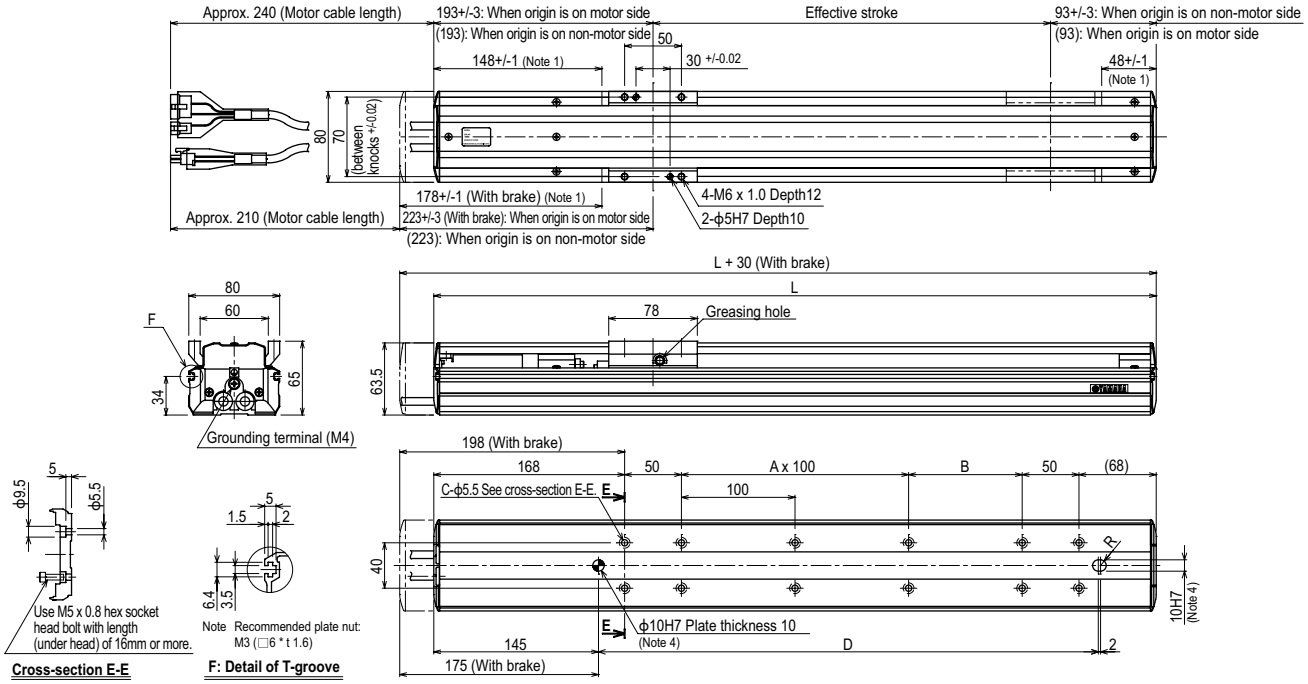
(Unit: N·m)

MY	MP	MR
70	95	110

Controller

Controller	Operation method
SR1-X05 RCX320 RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X105 TS-X205	I/O point trace / Remote command
RDV-X205-RBR1	Pulse train control

F8



Effective stroke		150	200	250	300	350	400	450	500	550	600	650	700	750	800
L		436	486	536	586	636	686	736	786	836	886	936	986	1036	1086
A		0	0	1	1	2	2	3	3	4	4	5	5	6	6
B		100	150	100	150	100	150	100	150	100	150	100	150	100	150
C		8	8	10	10	12	12	14	14	16	16	18	18	20	20
D		240	290	340	390	440	490	540	590	640	690	740	790	840	890
Weight (kg) Note 5		3.6	3.9	4.2	4.4	4.7	5.0	5.3	5.6	5.9	6.2	6.4	6.7	7.0	7.3
Maximum speed Note 6 (mm/sec)	Lead 20	1200									1080	900	780	720	600
	Lead 12	720									648	540	468	432	360
	Lead 6	360									324	270	234	216	180
	Speed setting	–									90%	75%	65%	60%	50%

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. When installing the robot, do not use washers inside the robot body.
Note 3. Minimum bend radius of motor cable is R50.
Note 4. When using this ϕ10 knock-pin hole to position the robot body, the knockpin must not protrude more than 10mm inside the robot body.
Note 5. Weight of models with no brake. The weight of brake-attached models is 0.3 kg heavier than the models with no brake shown in the table.
Note 6. When the stroke is longer than 550mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

F8L

- High lead: Lead 30
- Origin on the non-motor side is selectable

Ordering method

F8L - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Lead designation	Brake Note 1	Origin position change	Grease type	Stroke	Cable length Note 2
	30: 30mm 20: 20mm 10: 10mm 5: 5mm	No entry:No brakes BK:Brakes provided	None: Standard Z: Non-motor side	None: Standard GC: Clean	150 to 1050 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX [ ] - [ ] - [ ] - [ ]

Positioner Note 3	Driver: Power-supply voltage / Power capacity	LCD monitor	I/O selection	Battery
TSX: TS-X	105: 100V/100W or less 205: 200V/100W or less	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 4	B: With battery (Absolute) N: None (Incremental)

SR1-X **05** - [ ] - [ ] - [ ]

Controller	Driver: Power capacity	Usable for CE	I/O selection	Battery
	05: 100W or less	No entry: Standard E: CE marking	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X **2** **05** - **RBR1**

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
	2: AC200V	05: 100W or less	

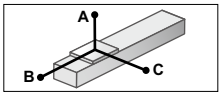
Note 1. The model with a lead of 30mm cannot select specifications with brake (vertical specifications).
Note 2. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.692 for details on robot cable.
Note 3. See P.600 for DIN rail mounting bracket.
Note 4. Select this selection when using the gateway function.

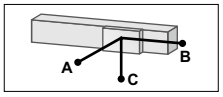
Specifications

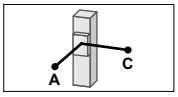
AC servo motor output (W)		100			
Repeatability Note 1 (mm)		+/-0.01			
Deceleration mechanism		Ball screw ϕ15			
Ball screw lead (mm)		30	20	10	5
Maximum speed Note 2 (mm/sec)		1800	1200	600	300
Maximum payload (kg)	Horizontal	7	20	40	50
	Vertical	–	4	8	16
Rated thrust (N)		56	84	169	339
Stroke (mm)		150 to 1050 (50mm pitch)			
Overall length (mm)	Horizontal	Stroke +300	Stroke+292		
	Vertical	–	Stroke+322		
Maximum dimensions of cross section of main unit (mm)		W80 × H65			
Cable length (m)		Standard: 3.5 / Option: 5,10			
Linear guide type		4 rows of circular arc grooves × 1 rail			
Position detector		Resolvers Note 3			
Resolution (Pulse/rotation)		16384			

Note 1. Positioning repeatability in one direction.
Note 2. When the stroke is longer than 650mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
Note 3. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note







Horizontal installation (Unit: mm)

		A	B	C
Lead 30	5kg	112	80	80
	7kg	78	43	49
Lead 20	5kg	211	108	147
	10kg	116	45	69
	15kg	76	24	39
	20kg	58	14	26
Lead 10	10kg	251	56	122
	20kg	121	20	46
	30kg	74	8	20
	40kg	35	0	6
Lead 5	20kg	249	23	62
	30kg	170	10	29
	40kg	138	4	12
	50kg	51	0	0

Wall installation (Unit: mm)

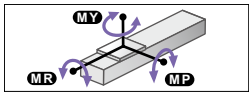
		A	B	C
Lead 30	5kg	55	57	77
	7kg	21	19	34
Lead 20	5kg	119	89	176
	10kg	38	26	69
	15kg	7	0	16
	20kg	0	0	0
Lead 10	10kg	85	39	202
	20kg	7	0	30
	30kg	0	0	0
	40kg	0	0	0
Lead 5	20kg	19	7	140
	30kg	0	0	0
	40kg	0	0	0
	50kg	0	0	0

Vertical installation (Unit: mm)

		A	C
Lead 20	2kg	236	240
	4kg	106	110
Lead 10	2kg	310	311
	4kg	141	143
	6kg	85	86
	8kg	57	58
Lead 5	5kg	123	124
	10kg	47	48
	15kg	22	22
	16kg	19	19

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



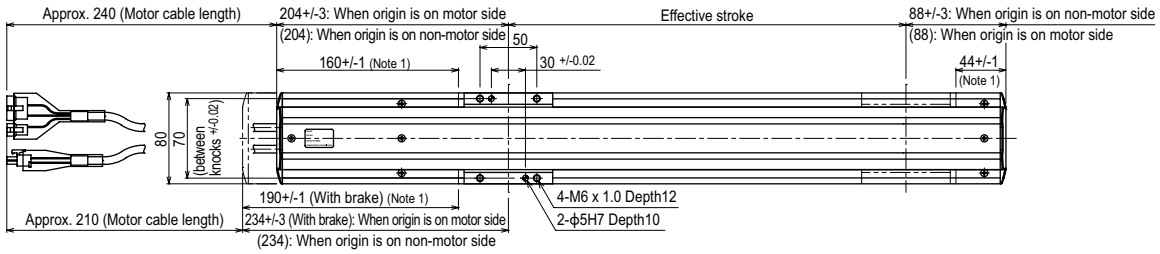
(Unit: N·m)

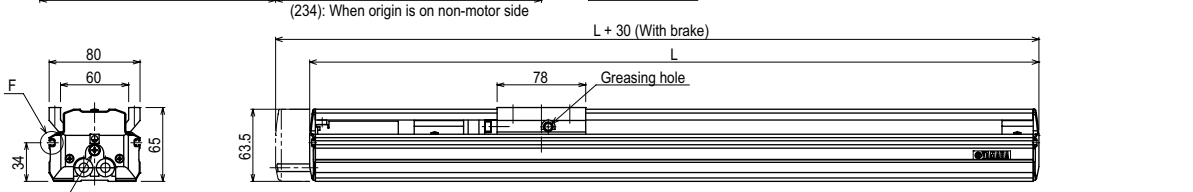
MY	MP	MR
70	95	110

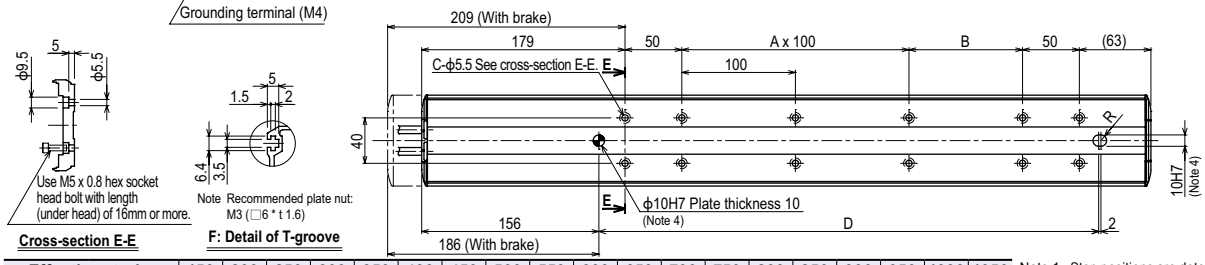
Controller

Controller	Operation method
SR1-X05 RCX320 RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X105 TS-X205	I/O point trace / Remote command
RDV-X205-RBR1	Pulse train control

F8L



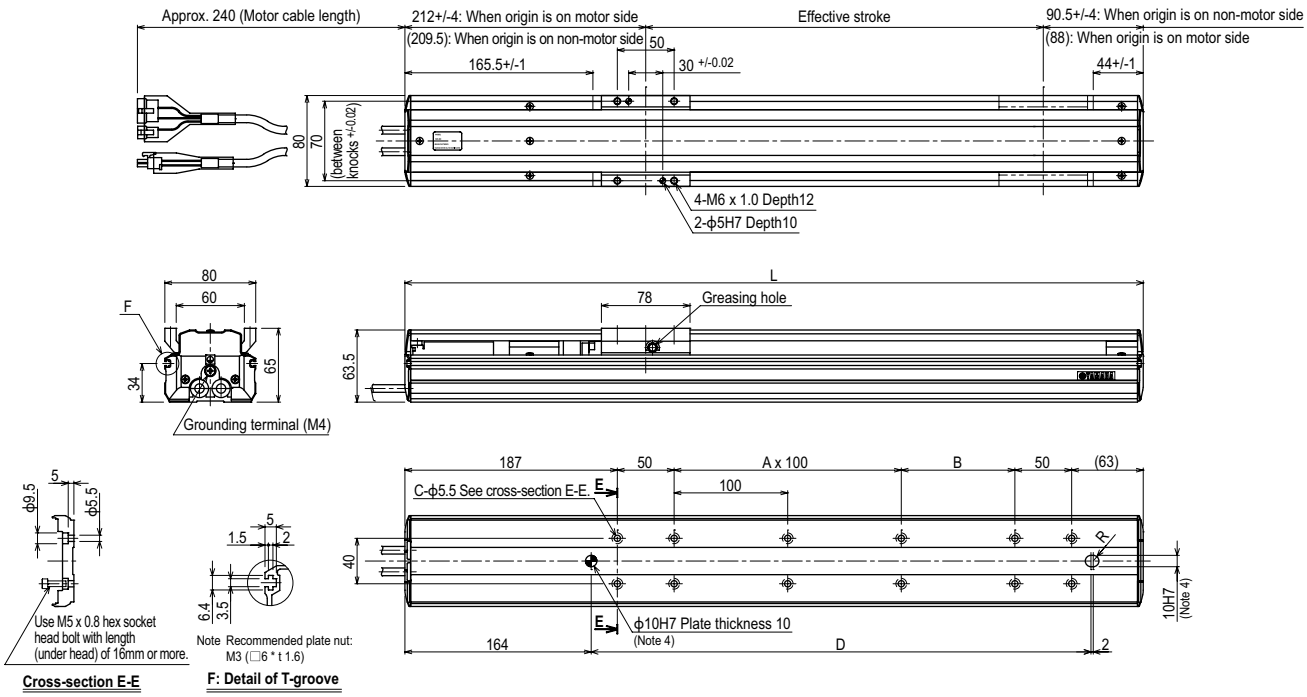




Effective stroke		150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050
L		442	492	542	592	642	692	742	792	842	892	942	992	1042	1092	1142	1192	1242	1292	1342
A		0	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	8	9
B		100	150	100	150	100	150	100	150	100	150	100	150	100	150	100	150	100	150	100
C		8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24	26
D		240	290	340	390	440	490	540	590	640	690	740	790	840	890	940	990	1040	1090	1140
Weight (kg) Note 5		3.9	4.2	4.5	4.8	5.1	5.4	5.7	6.1	6.4	6.7	7.0	7.3	7.6	7.9	8.2	8.5	8.8	9.2	9.5
Maximum speed Note 6 (mm/sec)	Lead 20	1200											1020	900	780	720	660	600	540	480
	Lead 10	600											510	450	390	360	330	300	270	240
	Lead 5	300											255	225	195	180	165	150	135	120
	Speed setting	–											85%	75%	65%	60%	55%	50%	45%	40%

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. When installing the robot, do not use washers inside the robot body.
Note 3. Minimum bend radius of motor cable is R50.
Note 4. When using this ϕ10 knock-pin hole to position the robot body, the knockpin must not protrude more than 10mm inside the robot body.
Note 5. Weight of models with no brake. The weight of brake-attached models is 0.3 kg heavier than the models with no brake shown in the table.
Note 6. When the stroke is longer than 650mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.

F8L High lead type: Lead 30



Effective stroke		150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050
L		450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350
A		0	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	8	9
B		100	150	100	150	100	150	100	150	100	150	100	150	100	150	100	150	100	150	100
C		8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24	26
D		240	290	340	390	440	490	540	590	640	690	740	790	840	890	940	990	1040	1090	1140
Weight (kg)		3.9	4.2	4.5	4.8	5.1	5.4	5.7	6.1	6.4	6.7	7.0	7.3	7.6	7.9	8.2	8.5	8.8	9.2	9.5
Maximum speed Note 5 (mm/sec)	Lead 30	1800											1530	1350	1170	1080	990	900	810	720
	Speed setting	–											85%	75%	65%	60%	55%	50%	45%	40%

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. When installing the robot, do not use washers inside the robot body.
Note 3. Minimum bend radius of motor cable is R50.
Note 4. When using this ϕ10 knock-pin hole to position the robot body, the knockpin must not protrude more than 10mm inside the robot body.

Note 5. When the stroke is longer than 650mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.

F8LH

Origin on the non-motor side is selectable

Ordering method

F8LH - [ ] - [ ] - [ ] - [ ] - [ ] - **TSX** [ ] - [ ] - [ ] - [ ]

Model	Lead designation	Origin position change	Grease type	Stroke	Cable length Note 1
	20: 20mm 10: 10mm 5: 5mm	None: Standard Z: Non-motor side	None: Standard GC: Clean	150 to 1050 (50mm pitch)	3L:3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

Positioner Note 2	Driver: Power-supply voltage / Power capacity	LCD monitor	I/O selection	Battery
TSX: TS-X	105: 100V/100W or less 205: 200V/100W or less	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 3	B: With battery (Absolute) N: None (Incremental)

SR1-X - **05** - [ ] - [ ] - [ ]

Controller	Driver: Power capacity	Usable for CE	I/O selection	Battery
	05: 100W or less	No entry: Standard E: CE marking	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X - **2** - **05** - **RBR1**

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
	2: AC200V	05: 100W or less	

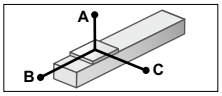
Note 1. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable.
See P.692 for details on robot cable.
Note 2. See P.600 for DIN rail mounting bracket.
Note 3. Select this selection when using the gateway function.

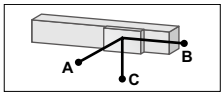
Specifications

AC servo motor output (W)		100		
Repeatability Note 1 (mm)		+/-0.01		
Deceleration mechanism		Ball screw ϕ15		
Ball screw lead (mm)		20	10	5
Maximum speed Note 2 (mm/sec)		1200	600	300
Maximum payload (kg)	Horizontal	30	60	80
Rated thrust (N)		84	169	339
Stroke (mm)		150 to 1050 (50mm pitch)		
Overall length (mm)	Horizontal	Stroke+368		
Maximum dimensions of cross section of main unit (mm)		W80 × H65		
Cable length (m)		Standard: 3.5 / Option: 5,10		
Linear guide type		4 rows of circular arc grooves × 1 rail		
Position detector		Resolvers Note 3		
Resolution (Pulse/rotation)		16384		

Note 1. Positioning repeatability in one direction.
Note 2. When the stroke is longer than 600mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
Note 3. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note





Horizontal installation (Unit: mm)

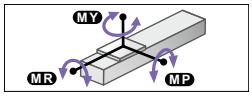
		A	B	C
Lead 20	10kg	573	256	176
	20kg	334	116	81
	30kg	279	70	50
Lead 10	20kg	629	137	111
	20kg	479	57	47
	60kg	382	30	25
Lead 5	20kg	1094	148	127
	40kg	851	63	54
	60kg	714	34	29
	80kg	601	20	17

Wall installation (Unit: mm)

		A	B	C
Lead 20	10kg	147	215	515
	20kg	53	75	255
	30kg	20	29	160
Lead 10	20kg	80	99	545
	40kg	15	19	270
	60kg	-	-	-
Lead 5	20kg	96	112	1005
	40kg	22	26	604
	60kg	-	-	-
	80kg	-	-	-

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



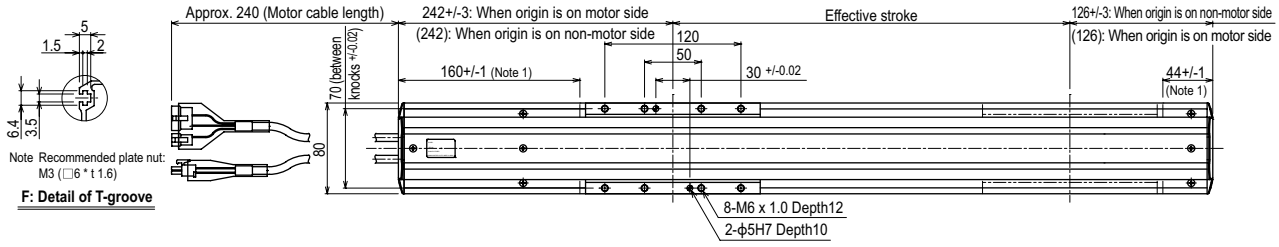
(Unit: N·m)

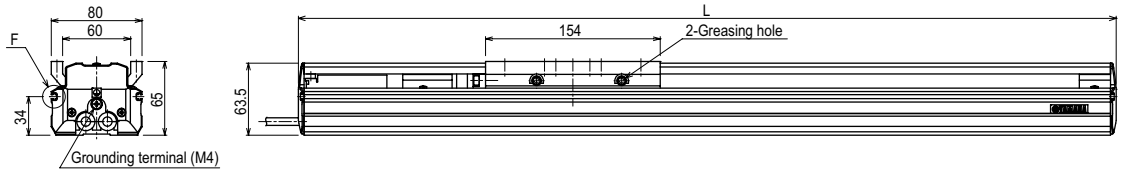
MY	MP	MR
128	163	143

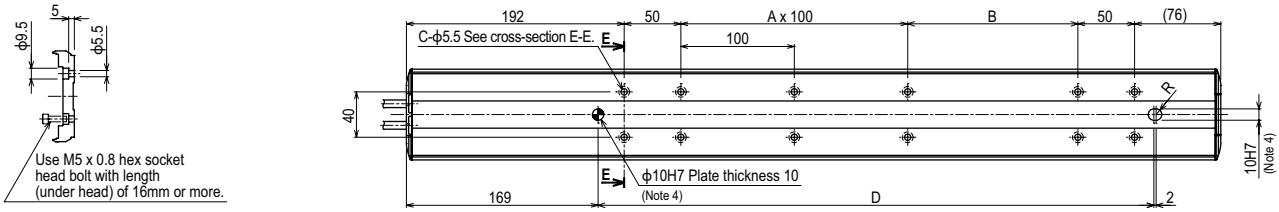
Controller

Controller	Operation method
SR1-X05 RCX320 RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X105 TS-X205	I/O point trace / Remote command
RDV-X205-RBR1	Pulse train control

F8LH







Effective stroke		150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050
L		518	568	618	668	718	768	818	868	918	968	1018	1068	1118	1168	1218	1268	1318	1368	1418
A		0	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	8	9	9
B		150	100	150	100	150	100	150	100	150	100	150	100	150	100	150	100	150	100	150
C		8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24	26	26
D		290	340	390	440	490	540	590	640	690	740	790	840	890	940	990	1040	1090	1140	1190
Weight (kg)		4.7	5.0	5.3	5.6	5.9	6.2	6.6	6.9	7.2	7.5	7.8	8.1	8.4	8.7	9.0	9.3	9.7	10.0	10.3
Maximum speed Note 5 (mm/sec)	Lead 20	1200										1020	900	780	720	660	600	540	480	420
	Lead 10	600										510	450	390	360	330	300	270	240	210
	Lead 5	300										255	225	195	180	165	150	135	120	105
	Speed setting	–										85%	75%	65%	60%	55%	50%	45%	40%	35%

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. When installing the robot, do not use washers inside the robot body.
Note 3. Minimum bend radius of motor cable is R50.
Note 4. When using this ϕ10 knock-pin hole to position the robot body, the knockpin must not protrude more than 10mm inside the robot body.

Note 5. When the stroke is longer than 600mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.

F10

- High lead: Lead 30
- Origin on the non-motor side is selectable: Lead 10·20·30

Note. Strokes longer than 1050mm are special order items. Please consult us for delivery time.

Ordering method

F10 – [ ] – [ ] – [ ] – [ ] – [ ] – [ ] – [ ]

Model	Lead designation	Brake Note 1	Cable entry location	Origin position change	Grease type	Stroke	Cable length Note 3
	30: 30mm 20: 20mm 10: 10mm 5: 5mm	No entry: No brakes BK: Brakes provided	No entry: Standard (S) U:From the top	None: Standard Z: Non-motor side Note 2	None: Standard GC: Clean	Lead 20·10·5: 150 to 1050 (50mm pitch) Lead 30: 150 to 1250 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX – [ ] – [ ] – [ ] – [ ] – [ ] – [ ]

Positioner Note 4	Driver: Power-supply voltage / Power capacity	Regenerative unit	LCD monitor	I/O selection	Battery
TSX: TS-X	105: 100V/100W or less 205: 200V/100W or less	No entry: None R: With RGT	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 5	B: With battery (Absolute) N: None (Incremental)

SR1-X – **05** – [ ] – [ ] – [ ] – [ ]

Controller	Driver: Power capacity	Usable for CE	Regenerative unit	I/O selection	Battery
	05: 100W or less	No entry: Standard E: CE marking	No entry: None R: With RG1	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X – **2** – **05** – **RBR1**

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
	2: AC200V	05: 100W or less	

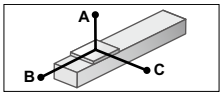
Note 1. The model with a lead of 30mm cannot select specifications with brake (vertical specifications).
Note 2. If selecting 5mm lead specifications then the origin point cannot be changed to the non-motor side.
Note 3. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.692 for details on robot cable.
Note 4. See P.600 for DIN rail mounting bracket.
Note 5. Select this selection when using the gateway function.

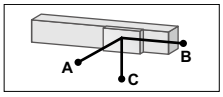
Specifications

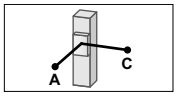
AC servo motor output (W)		100			
Repeatability Note 1 (mm)		+/-0.01			
Deceleration mechanism		Ball screw ϕ15			
Ball screw lead (mm)		30	20	10	5
Maximum speed Note 2 (mm/sec)		1800	1200	600	300
Maximum payload (kg)	Horizontal	15	20	40	60
	Vertical	–	4	10	20
Rated thrust (N)		56	84	169	339
Stroke (mm)		150 to 1250 Note 3 (50mm pitch)			
Overall length (mm)	Horizontal	Stroke+260			
	Vertical	Stroke+290			
Maximum dimensions of cross section of main unit (mm)		W110 × H71			
Cable length (m)		Standard: 3.5 / Option: 5,10			
Linear guide type		4 rows of circular arc grooves × 1 rail			
Position detector		Resolvers Note 4			
Resolution (Pulse/rotation)		16384			

Note 1. Positioning repeatability in one direction.
Note 2. When the stroke is longer than 700mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
Note 3. Strokes longer than 1050mm are available only for high lead (Lead 30). (Special order item)
Note 4. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note







Horizontal installation (Unit: mm)

		A	B	C
Lead 30	5kg	491	273	215
	15kg	223	61	63
Lead 20	5kg	937	282	259
	10kg	487	121	116
	20kg	236	40	44
Lead 10	15kg	389	71	74
	30kg	179	17	20
	40kg	106	0	0
Lead 5	30kg	419	19	20
	50kg	0	0	0
	60kg	0	0	0

Wall installation (Unit: mm)

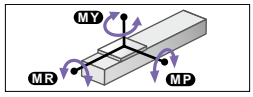
		A	B	C
Lead 30	5kg	206	209	480
	15kg	45	0	177
Lead 20	5kg	250	213	905
	10kg	99	51	438
	20kg	21	0	149
Lead 10	10kg	105	53	550
	20kg	22	0	230
	30kg	0	0	0
Lead 5	10kg	107	54	1410
	20kg	22	0	540
	30kg	0	0	0

Vertical installation (Unit: mm)

		A	C
Lead 20	1kg	600	600
	2kg	649	691
	4kg	306	347
Lead 10	4kg	338	380
	8kg	142	183
	10kg	102	144
Lead 5	10kg	105	146
	15kg	51	93
	20kg	25	66

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



(Unit: N·m)

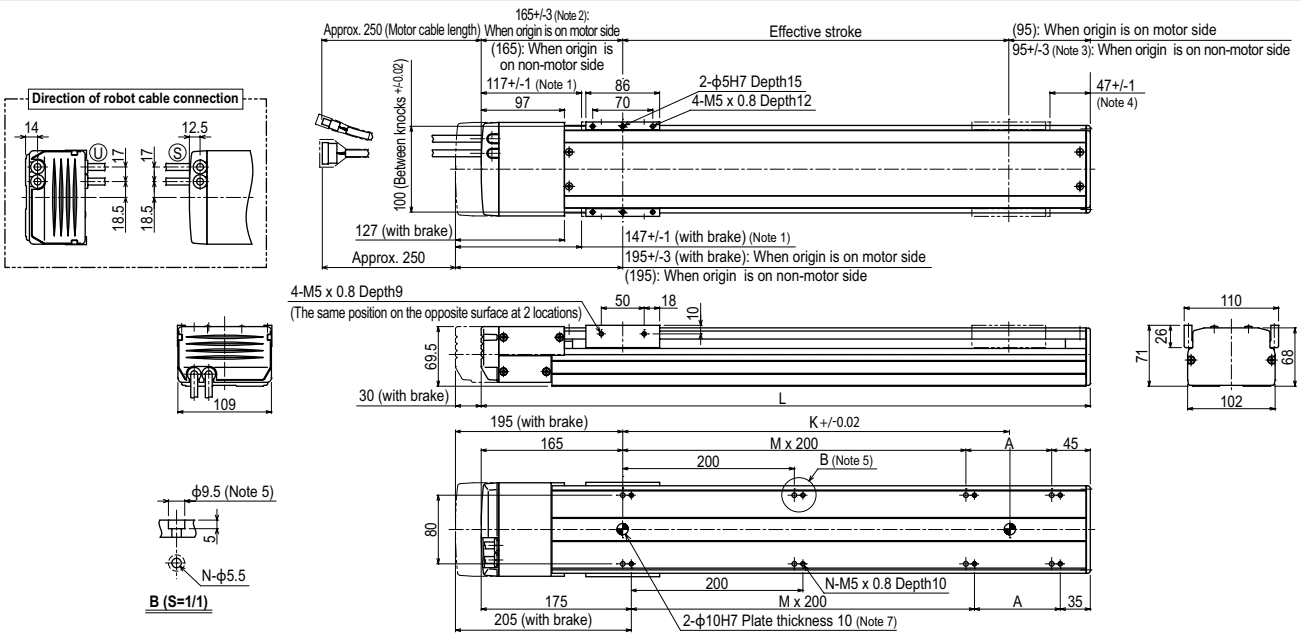
MY	MP	MR
131	131	115

Controller

Controller	Operation method
SR1-X05 Note RCX320 RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X105 Note TS-X205 Note	I/O point trace / Remote command
RDV-X205-RBR1	Pulse train control

Note. Regenerative unit is required when the models used vertically and with 700mm or larger stroke.

F10



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. 167.5+/-4 when the high lead specification (Lead 30) is used.
Note 3. 95+/-4 when the high lead specification (Lead 30) is used.
Note 4. 44.5+/-1 when the high lead specification (Lead 30) is used.
Note 5. When installing the unit, washers, etc., cannot be used in the ϕ9.5 counter bore hole.
Note 6. Minimum bend radius of motor cable is R50.
Note 7. When using this ϕ10 knock-pin hole to position the robot body, the knockpin must not protrude more than 10mm inside the robot body.
Note 8. Weight of models with no brake. The weight of brake-attached models is 0.6 kg heavier than the models with no brake shown in the table.

Effective stroke		150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100 Note 10	1150 Note 10	1200 Note 10	1250 Note 10
L		410	460	510	560	610	660	710	760	810	860	910	960	1010	1060	1110	1160	1210	1260	1310	1360	1410	1460	1510
A		200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100
M		0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6
N		4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16
K		150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250
Weight (kg) Note 8		5.5	5.7	5.8	6.2	6.5	6.9	7.3	7.7	8.1	8.5	8.8	9.2	9.6	10.0	10.4	10.8	11.1	11.5	11.9	12.3	12.7	13.1	13.5
Maximum speed Note 9 (mm/sec)	Lead 30	1800												1440		1170		900		810				
	Lead 20	1200												960		780		600		540				
	Lead 10	600												480		390		300		270				
	Lead 5	300												240		195		150		135				
	Speed setting	–												80%		65%		50%		45%				

Note 9. When the stroke is longer than 700mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.
Note 10.Strokes longer than 1050mm are special order items. Please contact us for speed setting.

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

F10H

- High lead: Lead 30
- Origin on the non-motor side is selectable: Lead 10·20·30

Ordering method

F10H - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Lead designation	Brake Note 1	Cable entry location	Origin position change	Grease type	Stroke	Cable length Note 3
	30: 30mm 20: 20mm 10: 10mm 5: 5mm	No entry: No brakes BK: Brakes provided	No entry: Standard (S) U:From the top	None: Standard Z: Non-motor side Note 2	None: Standard GC: Clean	Lead 20·10·5: 150 to 1000 (50mm pitch) Lead 30: 150 to 1000 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Positioner Note 4	Driver: Power-supply voltage / Power capacity	Regenerative unit	LCD monitor	I/O selection	Battery
TSX: TS-X	110: 100V/200W 210: 200V/200W	No entry: None R: With RGT	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 5	B: With battery (Absolute) N: None (Incremental)

SR1-X - **10** - [ ] - [ ] - [ ] - [ ]

Controller	Driver: Power capacity	Usable for CE	Regenerative unit	I/O selection	Battery
	10: 200W	No entry: Standard E: CE marking	No entry: None R: With RG1	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: Profibus	B: With battery (Absolute) N: None (Incremental)

RDV-X - **2** - **10** - **RBR1**

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
	2: AC200V	10: 200W or less	

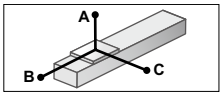
Note 1. The model with a lead of 30mm cannot select specifications with brake (vertical specifications).
Note 2. If selecting 5mm lead specifications then the origin point cannot be changed to the non-motor side.
Note 3. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.692 for details on robot cable.
Note 4. See P.600 for DIN rail mounting bracket.
Note 5. Select this selection when using the gateway function.

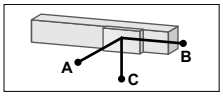
Specifications

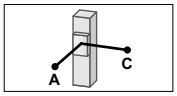
AC servo motor output (W)		200			
Repeatability Note 1 (mm)		+/- 0.01			
Deceleration mechanism		Ball screw ϕ15			
Ball screw lead (mm)		30	20	10	5
Maximum speed Note 2 (mm/sec)		1800	1200	600	300
Maximum payload (kg)	Horizontal	25	40	80	100
	Vertical	–	8	20	30
Rated thrust (N)		113	170	341	683
Stroke (mm)		150 to 1000			
Overall length (mm)	Horizontal	Stroke+355			
	Vertical	Stroke+385			
Maximum dimensions of cross section of main unit (mm)		W110 × H71			
Cable length (m)		Standard: 3.5 / Option: 5,10			
Linear guide type		4 rows of circular arc grooves × 1 rail			
Position detector		Resolvers Note 3			
Resolution (Pulse/rotation)		16384			

Note 1. Positioning repeatability in one direction.
Note 2. When the stroke is longer than 600mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below. When the movement distance is short, the speed may not reach the maximum speed according to the payload.
Note 3. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note







Horizontal installation (Unit: mm)

		A	B	C
Lead 30	10kg	1181	681	219
	20kg	772	298	99
Lead 20	10kg	1961	685	232
	20kg	949	301	103
	40kg	432	109	38
Lead 10	30kg	1615	239	84
	50kg	1131	112	39
	80kg	812	40	14
Lead 5	60kg	3091	112	39
	80kg	2330	64	23
	100kg	1733	36	12

Wall installation (Unit: mm)

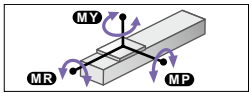
		A	B	C
Lead 30	10kg	193	570	1062
	20kg	65	187	549
Lead 20	10kg	198	570	1786
	20kg	65	187	732
	40kg	0	0	0
Lead 10	20kg	100	283	1981
	25kg	66	187	1546
	30kg	43	123	1223
Lead 5	20kg	134	379	7629
	25kg	93	264	5987
	30kg	66	187	4841

Vertical installation (Unit: mm)

		A	C
Lead 20	4kg	1650	1650
	6kg	1104	1104
	8kg	832	832
Lead 10	10kg	927	927
	15kg	614	614
	20kg	458	458
Lead 5	15kg	752	752
	20kg	560	560
	30kg	369	369

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.
Note. Service life is calculated for 600mm stroke models.

Static loading moment



(Unit: N·m)

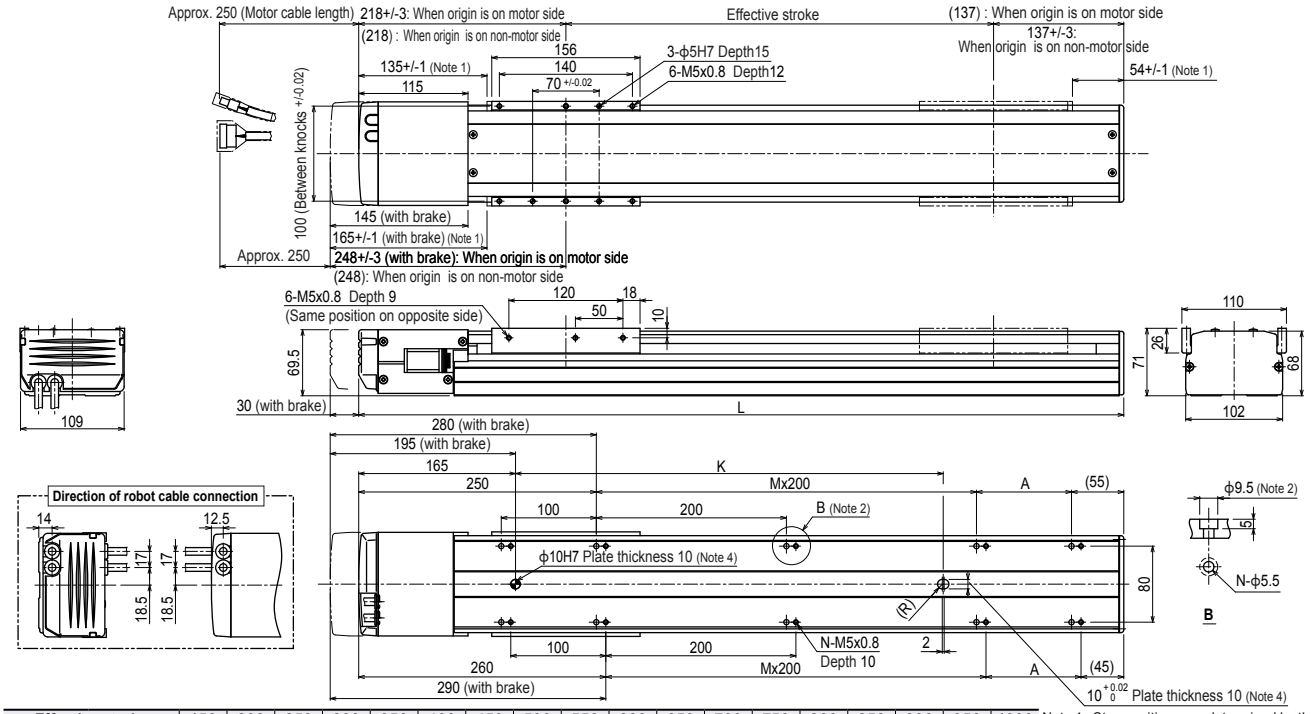
MY	MP	MR
348	348	160

Controller

Controller	Operation method
SR1-X10 Note RCX320 RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X110 Note TS-X210 Note	I/O point trace / Remote command
RDV-X210-RBR1	Pulse train control

Note. When using the unit vertically, a regeneration unit is required.

F10H



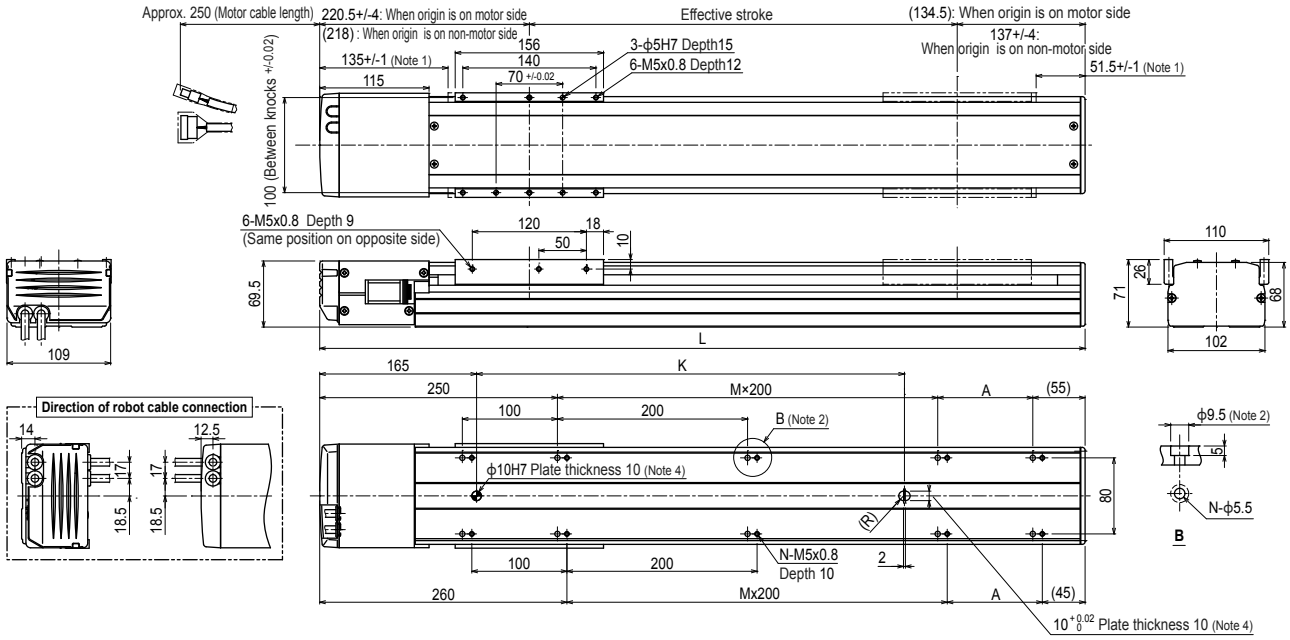
Effective stroke		150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
L		505	555	605	655	705	755	805	855	905	955	1005	1055	1105	1155	1205	1255	1305	1355
A		200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50
M		0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5
N		6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16
K		250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100
Weight (kg) Note 5		6.9	7.3	7.7	8.1	8.4	8.8	9.2	9.6	10.0	10.3	10.7	11.1	11.5	11.9	12.2	12.6	13.0	13.4
Maximum speed Note 6 (mm/sec)	Lead 30	1800										1440	1260	1080	900		720		630
	Lead 20	1200										960	840	720	600		480		420
	Lead 10	600										480	420	360	300		240		210
	Lead 5	300										240	210	180	150		120		105
	Speed setting	–										80%	70%	60%	50%		40%		35%

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. When installing the unit, washers, etc., cannot be used in the ϕ9.5 counter bore hole.
Note 3. Minimum bend radius of motor cable is R50.
Note 4. When using this ϕ10 knock-pin hole to position the robot body, the knockpin must not protrude more than 10mm inside the robot body.
Note 5. Weight of models with no brake. The weight of brake-attached models is 0.5 kg heavier than the models with no brake shown in the table.

Note 6. When the stroke is longer than 600mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

F10H High lead type: Lead 30



Effective stroke		150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
L		505	555	605	655	705	755	805	855	905	955	1005	1055	1105	1155	1205	1255	1305	1355
A		200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50
M		0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5
N		6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16
K		250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100
Weight (kg)		6.9	7.3	7.7	8.1	8.4	8.8	9.2	9.6	10.0	10.3	10.7	11.1	11.5	11.9	12.2	12.6	13.0	13.4
Maximum speed Note 5 (mm/sec)	Lead 30	1800										1440	1260	1080	900		720		630
	Lead 20	1200										960	840	720	600		480		420
	Lead 10	600										480	420	360	300		240		210
	Lead 5	300										240	210	180	150		120		105
	Speed setting	–										80%	70%	60%	50%		40%		35%

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. When installing the unit, washers, etc., cannot be used in the ϕ9.5 counter bore hole.
Note 3. Minimum bend radius of motor cable is R50.
Note 4. When using this ϕ10 knock-pin hole to position the robot body, the knockpin must not protrude more than 10mm inside the robot body.

Note 5. When the stroke is longer than 600mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

F14

High lead: Lead 30

Origin on the non-motor side is selectable

Note. Strokes longer than 1050mm are special order items. Please consult us for delivery time.

Ordering method

F14 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Lead designation	Brake Note 1	Cable entry location	Origin position change	Grease type	Stroke	Cable length Note 2
	30: 30mm 20: 20mm 10: 10mm 5: 5mm	No entry: No brakes BK: Brakes provided	No entry: Standard (S) U: From the top R: From the right L: From the left	None: Standard Z: Non-motor side	None: Standard GC: Clean	Lead 20·10·5: 150 to 1050 (50mm pitch) Lead 30: 150 to 1250 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Positioner Note 3	Driver: Power-supply voltage / Power capacity	Regenerative unit	LCD monitor	I/O selection	Battery
TSX: TS-X	105: 100V/100W or less 205: 200V/100W or less	No entry: None R: With RGT	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 4	B: With battery (Absolute) N: None (Incremental)

SR1-X - **05** - [ ] - [ ] - [ ] - [ ]

Controller	Driver: Power capacity	Usable for CE	Regenerative unit	I/O selection	Battery
	05: 100W or less	No entry: Standard E: CE marking	No entry: None R: With RG1	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X - **2** - **05** - **RBR1**

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
	2: AC200V	05: 100W or less	

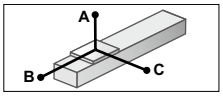
Note 1. The model with a lead of 30mm cannot select specifications with brake (vertical specifications).
Note 2. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.692 for details on robot cable.
Note 3. See P.600 for DIN rail mounting bracket.
Note 4. Select this selection when using the gateway function.

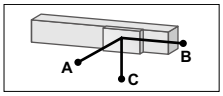
Specifications

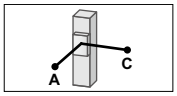
AC servo motor output (W)		100			
Repeatability Note 1 (mm)		+/-0.01			
Deceleration mechanism		Ball screw ϕ15			
Ball screw lead (mm)		30	20	10	5
Maximum speed Note 2 (mm/sec)		1800	1200	600	300
Maximum payload (kg)	**Horizontal**	15	30	55	80
	Vertical	–	4	10	20
Rated thrust (N)		56	84	169	339
Stroke (mm)		150 to 1250 Note 3 (50mm pitch)			
Overall length (mm)	**Horizontal**	Stroke+255			
	Vertical	Stroke+285			
Maximum dimensions of cross section of main unit (mm)		W136 × H83			
Cable length (m)		Standard: 3.5 / Option: 5,10			
Linear guide type		4 rows of circular arc grooves × 2 rail			
Position detector		Resolvers Note 4			
Resolution (Pulse/rotation)		16384			

Note 1. Positioning repeatability in one direction.
Note 2. When the stroke is longer than 700mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
Note 3. Strokes longer than 1050mm are available only for high lead (Lead 30). (Special order item)
Note 4. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note







Horizontal installation (Unit: mm)

		A	B	C
Lead 30	5kg	1756	1364	863
	15kg	1236	467	438
Lead 20	5kg	2153	1366	980
	15kg	1193	465	430
	30kg	1266	245	294
Lead 10	20kg	1132	353	361
	40kg	872	183	218
	55kg	946	140	184
Lead 5	50kg	1575	158	222
	60kg	1493	135	194
	80kg	1466	107	159

Wall installation (Unit: mm)

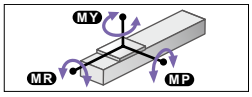
		A	B	C
Lead 30	5kg	951	969	1286
	15kg	408	277	803
Lead 20	5kg	1066	974	1578
	15kg	402	276	775
	30kg	219	105	678
Lead 10	20kg	312	189	690
	40kg	140	57	402
	55kg	92	0	345
Lead 5	30kg	246	107	1095
	40kg	167	64	798
	60kg	88	20	508

Vertical installation (Unit: mm)

		A	C
Lead 20	1kg	600	600
	2kg	1200	1200
	4kg	1154	895
Lead 10	4kg	1232	956
	8kg	634	492
	10kg	499	387
Lead 5	10kg	587	456
	15kg	383	297
	20kg	281	218

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



(Unit: N·m)

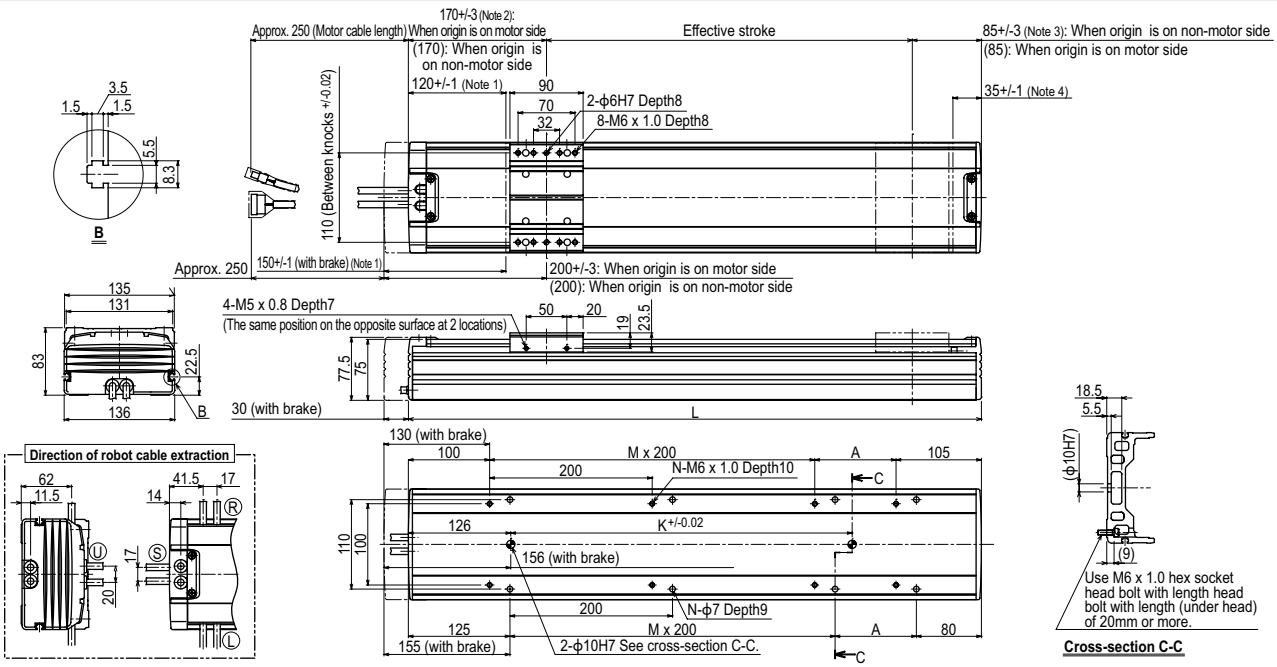
MY	MP	MR
232	233	204

Controller

Controller	Operation method
SR1-X05 Note RCX320 RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X105 Note TS-X205 Note	I/O point trace / Remote command
RDV-X205-RBR1	Pulse train control

Note. Regenerative unit is required when the models used vertically and with 700mm or larger stroke.

F14



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. 172.5+/-4 when the high lead specification (Lead 30) is used.
Note 3. 85+/-4 when the high lead specification (Lead 30) is used.
Note 4. 32.5+/-1 when the high lead specification (Lead 30) is used.
Note 5. Minimum bend radius of motor cable is R50.
Note 6. Weight of models with no brake. The weight of brake-attached models is 0.7 kg heavier than the models with no brake shown in the table.

Effective stroke		150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100 Note 8	1150 Note 8	1200 Note 8	1250 Note 8
L		405	455	505	555	605	655	705	755	805	855	905	955	1005	1055	1105	1155	1205	1255	1305	1355	1405	1455	1505
A		200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100
M		0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6
N		4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16
K		240	240	240	240	420	420	420	420	600	600	600	600	780	780	780	780	960	960	960	960	1140	1140	1140
Weight (kg) Note 6		6.2	6.9	7.5	8.2	8.8	9.5	10.1	10.8	11.4	12.1	12.6	13.4	13.9	14.6	15.2	15.9	16.5	17.2	17.8	18.5	19.1	19.8	20.4
Maximum speed Note 7 (mm/sec)	**Lead 30**	1800												1440		1170		900		810				
	Lead 20	1200												960		780		600		540				
	Lead 10	600												480		390		300		270				
	Lead 5	300												240		195		150		135				
	Speed setting	–												80%		65%		50%		45%				

Note 7. When the stroke is longer than 700mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.
Note 8. Strokes longer than 1050mm are special order items. Please contact us for speed setting.

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

F14H

High lead: Lead 30

Origin on the non-motor side is selectable: Lead 10·20·30

Note. Strokes longer than 1050mm are special order items. Please consult us for delivery time.

Ordering method

F14H - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Lead designation	Brake Note 1	Cable entry location	Origin position change	Grease type	Stroke	Cable length Note 3
	30: 30mm 20: 20mm 10: 10mm 5: 5mm	No entry: No brakes BK: Brakes provided	No entry: Standard (S) U: From the top R: From the right L: From the left	None: Standard Z: Non-motor side Note 2	None: Standard GC: Clean	Lead 20·10·5: 150 to 1050 (50mm pitch) Lead 30: 150 to 1250 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Positioner Note 4	Driver: Power-supply voltage / Power capacity	Regenerative unit	LCD monitor	I/O selection	Battery
TSX: TS-X	110: 100V/200W 210: 200V/200W	No entry: None R: With RGT	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 5	B: With battery (Absolute) N: None (Incremental)

SR1-X - **10** - [ ] - [ ] - [ ] - [ ]

Controller	Driver: Power capacity	Usable for CE	Regenerative unit	I/O selection	Battery
	10: 200W	No entry: Standard E: CE marking	No entry: None R: With RG1	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X - **2** - **10** - **RBR1**

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
	2: AC200V	10: 200W or less	

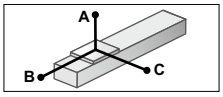
Note 1. The model with a lead of 30mm cannot select specifications with brake (vertical specifications).
Note 2. If selecting 5mm lead specifications then the origin point cannot be changed to the non-motor side.
Note 3. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.692 for details on robot cable.
Note 4. See P.600 for DIN rail mounting bracket.
Note 5. Select this selection when using the gateway function.

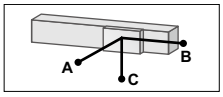
Specifications

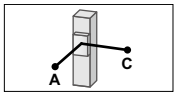
AC servo motor output (W)		200			
Repeatability Note 1 (mm)		+/-0.01			
Deceleration mechanism		Ball screw ϕ15			
Ball screw lead (mm)		30	20	10	5
Maximum speed Note 2 (mm/sec)		1800	1200	600	300
Maximum payload (kg)	Horizontal	25	40	80	100
	Vertical	–	8	20	30
Rated thrust (N)		113	170	341	683
Stroke (mm)		150 to 1250 Note 3 (50mm pitch)			
Overall length (mm)	Horizontal	Stroke+320			
	Vertical	Stroke+350			
Maximum dimensions of cross section of main unit (mm)		W136 × H83			
Cable length (m)		Standard: 3.5 / Option: 5,10			
Linear guide type		4 rows of circular arc grooves × 2 rail			
Position detector		Resolvers Note 4			
Resolution (Pulse/rotation)		16384			

Note 1. Positioning repeatability in one direction.
Note 2. When the stroke is longer than 700mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
Note 3. Strokes longer than 1050mm are available only for high lead (Lead 30). (Special order item)
Note 4. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note







Horizontal installation (Unit: mm)

		A	B	C
Lead 30	10kg	2152	1673	934
	25kg	1847	691	533
Lead 20	10kg	2265	1674	961
	20kg	1402	855	537
	40kg	1047	445	324
Lead 10	30kg	1953	583	485
	50kg	1655	365	328
	80kg	1720	242	238
Lead 5	60kg	2443	311	317
	80kg	2193	242	253
	100kg	2000	202	214

Wall installation (Unit: mm)

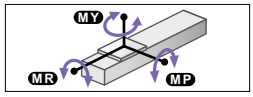
		A	B	C
Lead 30	10kg	975	1219	1625
	25kg	482	426	1257
Lead 20	10kg	999	1220	1711
	20kg	515	558	987
	40kg	263	227	635
Lead 10	30kg	419	338	1282
	50kg	240	162	934
	80kg	134	62	756
Lead 5	60kg	209	117	1398
	80kg	135	62	1120
	100kg	90	29	900

Vertical installation (Unit: mm)

		A	C
Lead 20	4kg	2400	2016
	6kg	1699	1364
	8kg	1301	1051
Lead 10	10kg	1370	1106
	15kg	906	732
	20kg	678	548
Lead 5	20kg	767	619
	25kg	612	494
	30kg	503	407

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



(Unit: N·m)

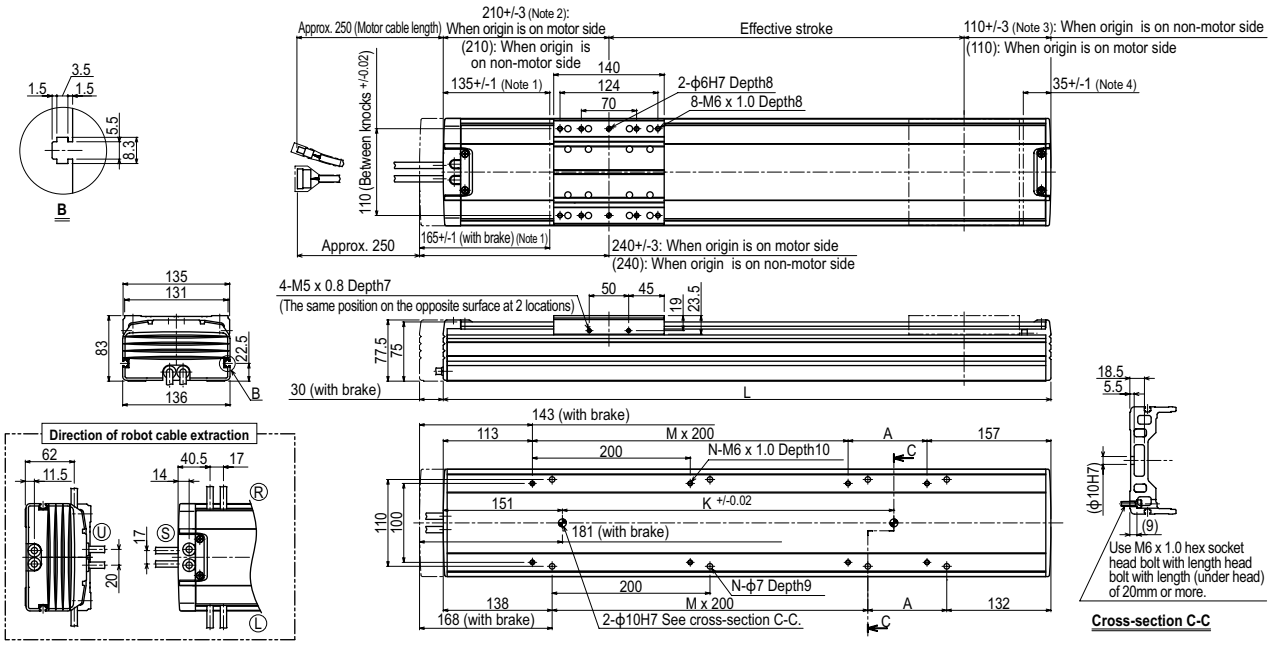
MY	MP	MR
551	552	485

Controller

Controller	Operation method
SR1-X10 Note RCX320 RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X110 Note	I/O point trace /
TS-X210 Note	Remote command
RDV-X210-RBR1	Pulse train control

Note. When using the unit vertically, a regeneration unit is required.

F14H



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. 212.5+/-4 when the high lead specification (Lead 30) is used.
Note 3. 110+/-4 when the high lead specification (Lead 30) is used.
Note 4. 32.5+/-1 when the high lead specification (Lead 30) is used.
Note 5. Minimum bend radius of motor cable is R50.
Note 6. Weight of models with no brake. The weight of brake-attached models is 0.7 kg heavier than the models with no brake shown in the table.

Effective stroke		150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100 Note 8	1150 Note 8	1200 Note 8	1250 Note 8
L		470	520	570	620	670	720	770	820	870	920	970	1020	1070	1120	1170	1220	1270	1320	1370	1420	1470	1520	1570
A		200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100
M		0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6
N		4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16
K		240	240	240	420	420	420	420	600	600	600	600	780	780	780	960	960	960	960	1140	1140	1140	1140	1320
Weight (kg) Note 6		7.5	8.2	8.8	9.5	10.1	10.8	11.4	12.1	12.7	13.4	13.9	14.6	15.2	15.9	16.5	17.2	17.8	18.5	19.1	19.8	20.4	21.1	21.7
Maximum speed Note 7 (mm/sec)	Lead 30	1800												1440		1170		900		810				
	Lead 20	1200												960		780		600		540				
	Lead 10	600												480		390		300		270				
	Lead 5	300												240		195		150		135				
	Speed setting	–												80%		65%		50%		45%				

Note 7. When the stroke is longer than 700mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.
Note 8. Strokes longer than 1050mm are special order items. Please contact us for speed setting.

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

GF14XL

Origin on the non-motor side is selectable

Note. If you need an installation posture other than the horizontal installation, please contact us.

Ordering method

GF14XL - S H - 20 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Model	Installation direction	Lead designation	Cable entry location	Origin position change	Frame	Grease type	Stroke	Cable length Note 1
	S: Straight model	H: Horizontal installation		No entry: Standard (S) U: From the top R: From the right L: From the left	None: Standard Z: Non-motor side	No entry: Standard (Spot facing) T: Tapping	None: Standard GC: Clean	750 to 2000 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX - [ ] - [ ] - [ ] - [ ] - [ ]

Positioner Note 2	Driver: Power-supply voltage / Power capacity	LCD monitor	I/O selection	Battery
TSX: TS-X	110: 100V/200W 210: 200V/200W	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 3	B: With battery (Absolute) N: None (Incremental)

SR1-X - 10 - [ ] - [ ] - [ ]

Controller	Driver: Power capacity	Usable for CE	I/O selection	Battery
	10: 200W	No entry: Standard E: CE marking	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X - 2 - 20 - RBR1

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
	2: AC200V	20: 600W or less	

Note 1. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.692 for details on robot cable.
Note 2. See P.600 for DIN rail mounting bracket.
Note 3. Select this selection when using the gateway function.

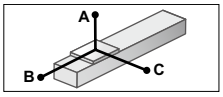
[Cautions after purchase]
- When changing the origin position, contact us since the adjustment is needed.
- When changing the cable entry location, contact us since necessary parts may vary depending on the cable entry location.
- Do not install the robot with the horizontal installation specifications in a direction other than the horizontal direction.

Specifications

AC servo motor output (W)	200
Repeatability Note 1 (mm)	+/-0.01
Deceleration mechanism	Ball screw ϕ15
Ball screw lead (mm)	20
Maximum speed (mm/sec)	1200
Maximum payload (kg)	45
Rated thrust (N)	170
Stroke (mm)	750 to 2000 (50mm pitch)
Overall length (mm)	Stroke+561
Maximum dimensions of cross section of main unit (mm)	W140×H91.5
Cable length (m)	Standard: 3.5 / Option: 5,10
Linear guide type	4 rows of circular arc grooves × 2 rail
Position detector	Resolvers Note 2
Resolution (Pulse/rotation)	20480

Note 1. Positioning repeatability in one direction.
Note 2. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note

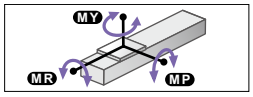


Horizontal installation (Unit: mm)

		A	B	C
Lead 20	10kg	3550	1340	1210
	20kg	2075	685	633
	45kg	1280	326	308

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.
Note. Service life is calculated for 1000mm stroke models.

Static loading moment



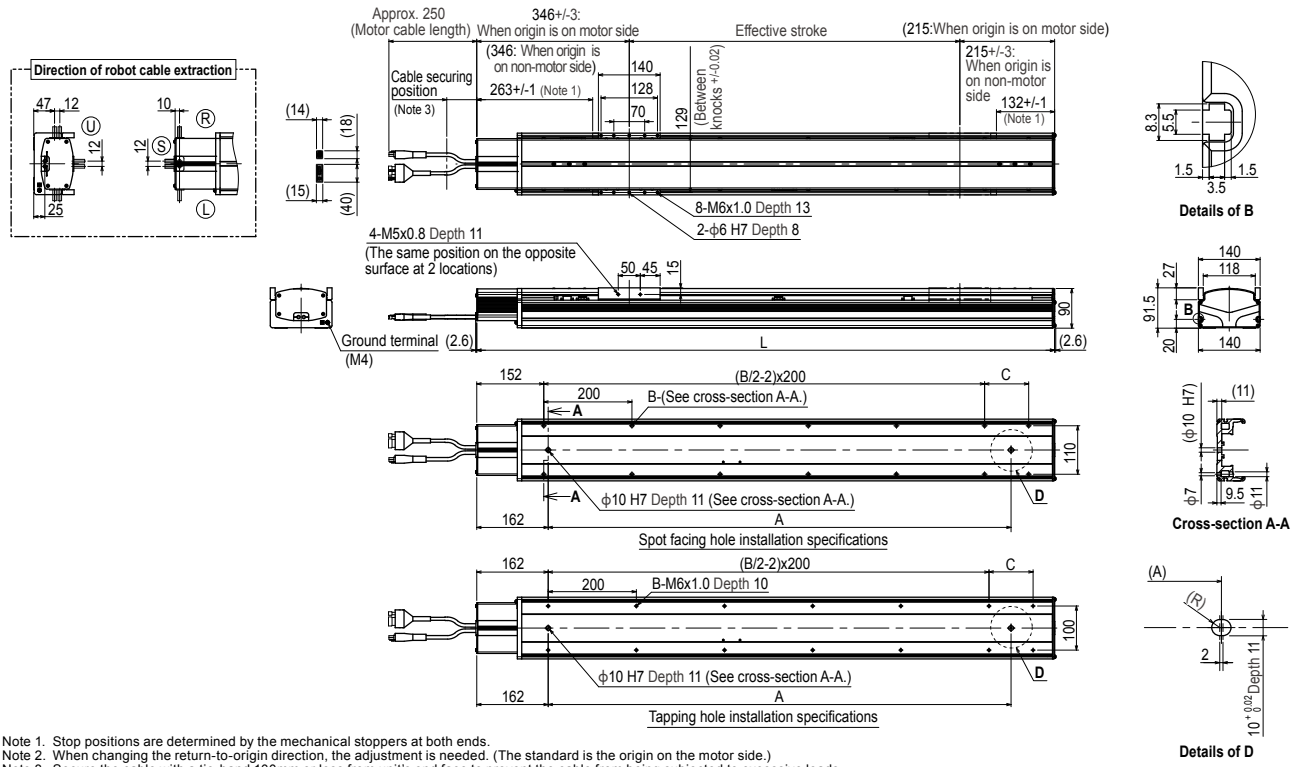
(Unit: N·m)

MY	MP	MR
551	552	485

Controller

Controller	Operation method
SR1-X10 RCX320 RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X110 TS-X210	I/O point trace/ Remote command
RDV-X220-RBR1	Pulse train control

GF14XL



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. When changing the return-to-origin direction, the adjustment is needed. (The standard is the origin on the motor side.)
Note 3. Secure the cable with a tie-band 100mm or less from unit's end face to prevent the cable from being subjected to excessive loads.
Note 4. The cable's minimum bend radius is R30.
Note 5. The length under head of the hexagonal socket head bolts (M6 x 1.0) that are used to install the main body with the spot facing hole installation specifications is 20mm or more. It is recommended that the length under head of the hexagonal socket head bolts (M6 x 1.0) that are used to install the main body with the tapping hole installation specifications is the thickness of the installation base + 10mm or less.

Effective stroke	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450	1500	1550	1600	1650	1700	1750	1800	1850	1900	1950	2000
L	1311	1361	1411	1461	1511	1561	1611	1661	1711	1761	1811	1861	1911	1961	2011	2061	2111	2161	2211	2261	2311	2361	2411	2461	2511	2561
A	1050	1100	1150	1200	1250	1300	1350	1400	1450	1500	1550	1600	1650	1700	1750	1800	1850	1900	1950	2000	2050	2100	2150	2200	2250	2300
B	14	14	14	16	16	16	16	18	18	18	18	20	20	20	20	22	22	22	22	24	24	24	24	26	26	26
C	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150
Weight (kg)	22.5	23.2	23.8	24.5	25.2	25.9	26.5	27.2	27.9	28.6	29.2	29.9	30.6	31.3	31.9	32.6	33.3	33.9	34.6	35.3	36.0	36.6	37.3	38.0	38.7	39.3

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

F17

High lead: Lead 40

Origin on the non-motor side is selectable

Note. Upper robot cable (U) on models with brakes is a special order item, so please consult our sales office or sales representative for assistance.
(External dimensions: overall length + 20 mm)

Ordering method

F17 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Lead designation	Brake Note 1	Cable entry location	Origin position change	Grease type	Stroke	Cable length Note 3
	40: 40mm 20: 20mm 10: 10mm	No entry: No brakes BK: Brakes provided	No entry: Standard (S) U: From the top Note 2 R: From the right L: From the left	None: Standard Z: Non-motor side	None: Standard GC: Clean	Lead 20·10: 200 to 1250 (50mm pitch) Lead 40: 200 to 1450 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX - **220** - [ ] - [ ] - [ ] - [ ]

Positioner Note 4	Driver: Power-supply voltage / Power capacity	Regenerative unit Note 5	LCD monitor	I/O selection	Battery
TSX: TS-X	220: 200V/400 to 600W	No entry: None R: With RGT	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 6	B: With battery (Absolute) N: None (Incremental)

SR1-X - **20** - [ ] - [ ] - [ ] - [ ]

Controller	Driver: Power capacity	Usable for CE	Regenerative unit Note 5	I/O selection	Battery
	20: 400 to 600W	No entry: Standard E: CE marking	No entry: None R: With RG1	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X - **2** - **20** - [ ]

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit Note 5
	2: AC200V	20: 600W or less	RBR1 (Horizontal) RBR2 (Vertical)

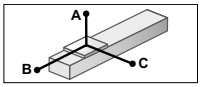
Note 1. The model with a lead of 40mm cannot select specifications with brake (vertical specifications).
Note 2. Upper robot cable (U) on models equipped with brake is a special-order item.
Note 3. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.692 for details on robot cable.
Note 4. See P.600 for DIN rail mounting bracket.
Note 5. The robot with the high lead specifications (lead 40) needs a regenerative unit.
Note 6. Select this selection when using the gateway function.

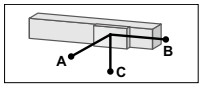
Specifications

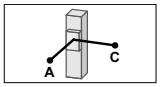
AC servo motor output (W)		400		
Repeatability Note 1 (mm)		+/-0.01		
Deceleration mechanism		Ball screw ϕ20		
Ball screw lead (mm)		40	20	10
Maximum speed Note 2 (mm/sec)		2400	1000 (1200 Note 3)	600
Maximum payload (kg)	**Horizontal**	40	80	120
	Vertical	–	15	35
Rated thrust (N)		169	339	678
Stroke (mm)		200 to 1450 Note 4 (50mm pitch)		
Overall length (mm)	**Horizontal**	Stroke+375	Stroke+365	
	Vertical	–	Stroke+395	
Maximum dimensions of cross section of main unit (mm)		W168 × H100		
Cable length (m)		Standard: 3.5 / Option: 5,10		
Linear guide type		4 rows of circular arc grooves × 2 rail		
Position detector		Resolvers Note 5		
Resolution (Pulse/rotation)		16384		

Note 1. Repeatability for single oscillation.
Note 2. When the stroke exceeds 800mm, although depending on the moving range, the ball screw may resonate (critical speed). In that case, make adjustment to lower the speed on the program using the maximum speed given in the below table as a guide.
Note 3. To operate the unit at a speed exceeding 1,000mm/sec. (Max. speed), a regeneration unit RG1 is required.
Note 4. Longer than 1250mm stroke can be handled by the high lead specification (Lead 40) only.
Note 5. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note







Horizontal installation (Unit: mm)

		A	B	C
Lead 40	**10kg**	3540	2753	1999
Lead 20	**20kg**	2541	1357	1181
	40kg	2639	661	736
	30kg	2647	894	989
	50kg	1770	521	588
	80kg	1391	312	362
Lead 10	**60kg**	2443	430	572
	100kg	2000	243	326
	120kg	1841	197	264

Wall installation (Unit: mm)

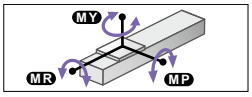
		A	B	C
Lead 40	**10kg**	2022	2670	3501
	20kg	1202	1283	2483
	40kg	752	587	2516
Lead 20	**30kg**	987	820	2578
	50kg	574	447	1685
	80kg	342	237	1263
Lead 10	**60kg**	535	355	2443
	100kg	283	169	2000
	120kg	220	123	1841

Vertical installation (Unit: mm)

		A	C
Lead 20	**5kg**	3000	3000
	10kg	2447	2447
	15kg	1650	1650
Lead 10	**15kg**	1782	1782
	25kg	1054	1054
	35kg	742	742

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



(Unit: N·m)

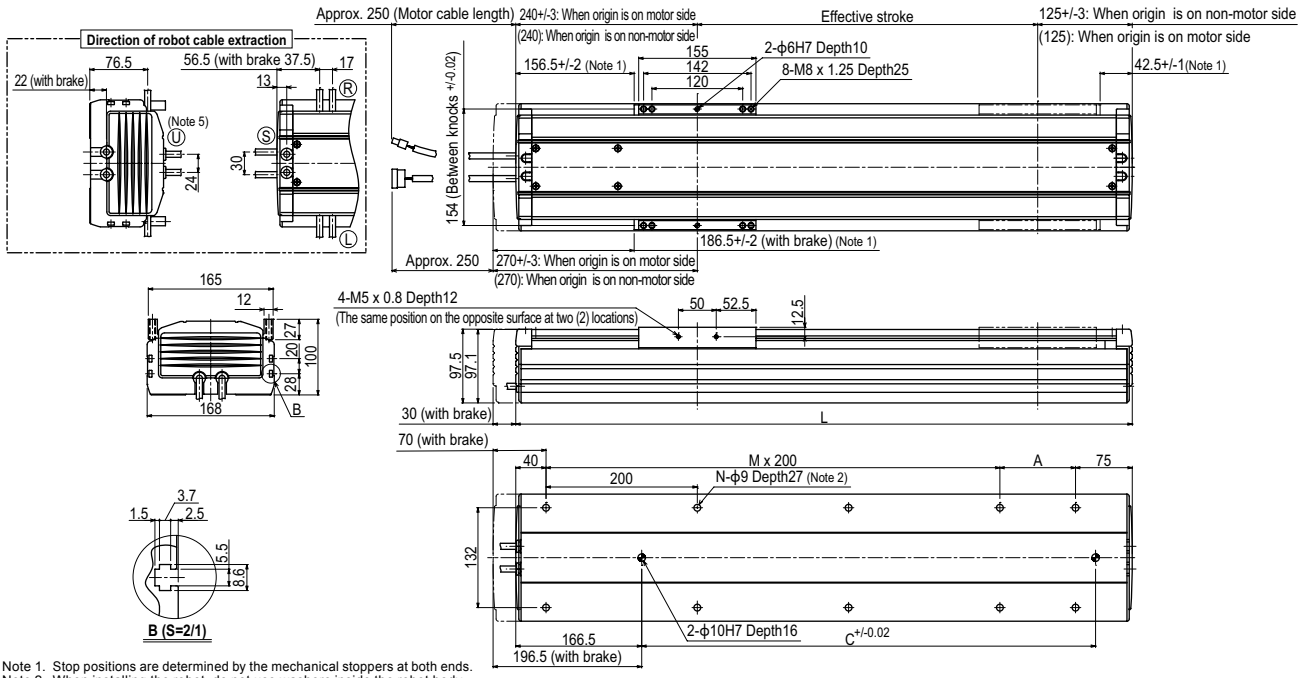
MY	MP	MR
1032	1034	908

Controller

Controller	Operation method
SR1-X20 Note RCX320, RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X220 Note	I/O point trace / Remote command
RDV-X220-RBR1 (Horizontal) RDV-X220-RBR2 (Vertical)	Pulse train control

Note. [The following arrangements require a regeneration unit.]
- Using in the upright position.
- To move at a speed exceeding 1,000 mm/sec horizontally.
- High lead (40) used horizontally.

F17

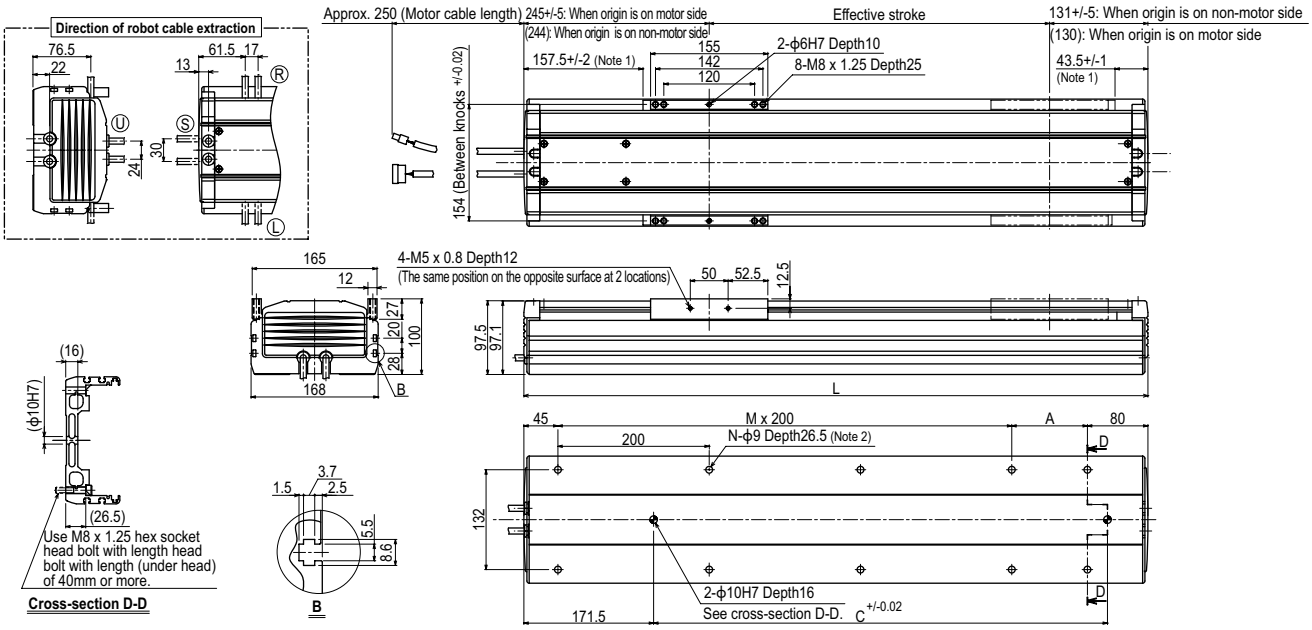


Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. When installing the robot, do not use washers inside the robot body.
Note 3. Minimum bend radius of motor cable is R50.
Note 4. Weight of models with no brake. The weight of brake-attached models is 1.2 kg heavier than the models with no brake shown in the table.
Note 5. Make a separate consultation with us regarding robot cable (brake specifications) U extraction. (External dimensions: overall length + 20 mm)
Note 6. When the stroke is longer than 800mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.
Note 7. To operate the unit at a speed exceeding 1,000mm/sec. (Max. speed), a regeneration unit RG1 is required.

Effective stroke		200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250
L		565	615	665	715	765	815	865	915	965	1015	1065	1115	1165	1215	1265	1315	1365	1415	1465	1515	1565	1615
A		50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100
M		2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6	6	7	7
N		8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18
C		240	240	420	420	420	600	600	600	600	780	780	780	780	960	960	960	960	1140	1140	1140	1140	1320
Weight (kg) Note 4		14.5	15.3	16.2	17.0	17.8	18.6	19.5	20.3	21.1	21.9	22.8	23.6	24.4	25.2	26.1	26.9	27.7	28.5	29.4	30.2	31.0	31.8
Maximum speed Note 6 (mm/sec)	**Lead 20**	1000(1200 Note 7)													960		840		720		600		480
	Lead 10	600													480		420		360		300		240
	Speed setting	–													80%		70%		60%		50%		40%

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

F17 High lead type: Lead 40



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. When installing the robot, do not use washers inside the robot body.
Note 3. Minimum bend radius of motor cable is R50.

Effective stroke	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450
L	575	625	675	725	775	825	875	925	975	1025	1075	1125	1175	1225	1275	1325	1375	1425	1475	1525	1575	1625	1675	1725	1775	1825
A	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100
M	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6	6	7	7	7	7	8	8
N	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18	18	20	20
C	240	240	420	420	420	600	600	600	600	780	780	780	780	960	960	960	960	1140	1140	1140	1140	1320	1320	1320	1320	1320
Weight (kg)	14.7	15.5	16.4	17.2	18.0	18.8	19.7	20.5	21.3	22.1	23.0	23.8	24.6	25.4	26.3	27.1	27.9	28.7	29.6	30.4	31.2	32.0	32.8	33.6	34.4	35.2
Maximum speed Note 4 (mm/sec) Lead 40	2400													1920		1680		1440		1200		960		840		720
Maximum speed Note 4 (mm/sec) Speed setting	–													80%		70%		60%		50%		40%		35%		30%

Note 4. When the stroke is longer than 800mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

F17L

Origin on the non-motor side is selectable

Note. Upper robot cable (U) on models with brakes is a special order item, so please consult our sales office or sales representative for assistance. (External dimensions: overall length + 20 mm)

Ordering method

F17L - 50 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Lead designation	Brake	Cable entry location	Origin position change	Grease type	Stroke	Cable length Note 2
		No entry: No brakes BK: Brakes provided	No entry: Standard (S) U: From the top Note 1 R: From the right L: From the left	None: Standard Z: Non-motor side	None: Standard GC: Clean	1100 to 2050 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX - **220** - **R** - [ ] - [ ] - [ ]

Positioner Note 3	Driver: Power-supply voltage / Power capacity Note 4	Regenerative unit	LCD monitor	I/O selection	Battery
TSX: TS-X	220: 200V/400 to 600W	R: With RGT	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 5	B: With battery (Absolute) N: None (Incremental)

SR1-X - **20** - [ ] - **R** - [ ] - [ ]

Controller	Driver: Power capacity Note 4	Usable for CE	Regenerative unit	I/O selection	Battery
	20: 400 to 600W	No entry: Standard E: CE marking	R: With RG1	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X - **2** - **20** - [ ]

Driver	Power-supply voltage	Driver: Power capacity Note 4	Regenerative unit
	2: AC200V	20: 600W or less	RBR1 (Horizontal) RBR2 (Vertical)

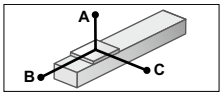
Note 1. Upper robot cable (U) on models equipped with brake is a special-order item.
Note 2. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.692 for details on robot cable.
Note 3. See P.600 for DIN rail mounting bracket.
Note 4. Acceleration / deceleration is different depending the Positioner or Controller or Driver.
Note 5. Select this selection when using the gateway function.

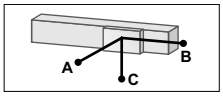
Specifications

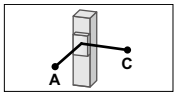
AC servo motor output (W)		600
Repeatability Note 1 (mm)		+/-0.02
Deceleration mechanism		Ball screw ϕ25
Ball screw lead (mm)		50
Maximum speed Note 2 (mm/sec)		2200
Maximum payload (kg)	Horizontal	50
	Vertical	10
Rated thrust (N)		204
Stroke (mm)		1100 to 2050 (50mm pitch)
Overall length (mm)	Horizontal	Stroke+475
	Vertical	Stroke+505
Maximum dimensions of cross section of main unit (mm)		W168 × H100
Cable length (m)		Standard: 3.5 / Option: 5,10
Linear guide type		4 rows of circular arc grooves × 2 rail
Position detector		Resolvers Note 3
Resolution (Pulse/rotation)		16384

Note 1. Positioning repeatability in one direction.
Note 2. When the stroke is longer than 1200mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
Note 3. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note







Horizontal installation (Unit: mm)

		A	B	C
Lead 50	10kg	4000	2755	2608
	30kg	3045	895	1175
	50kg	2602	523	715

Wall installation (Unit: mm)

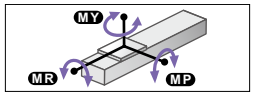
		A	B	C
Lead 50	10kg	2720	2681	4000
	30kg	1185	821	3045
	50kg	680	449	2602

Vertical installation (Unit: mm)

		A	C
Lead 50	2kg	1200	1200
	5kg	3000	3000
	10kg	2650	2650

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



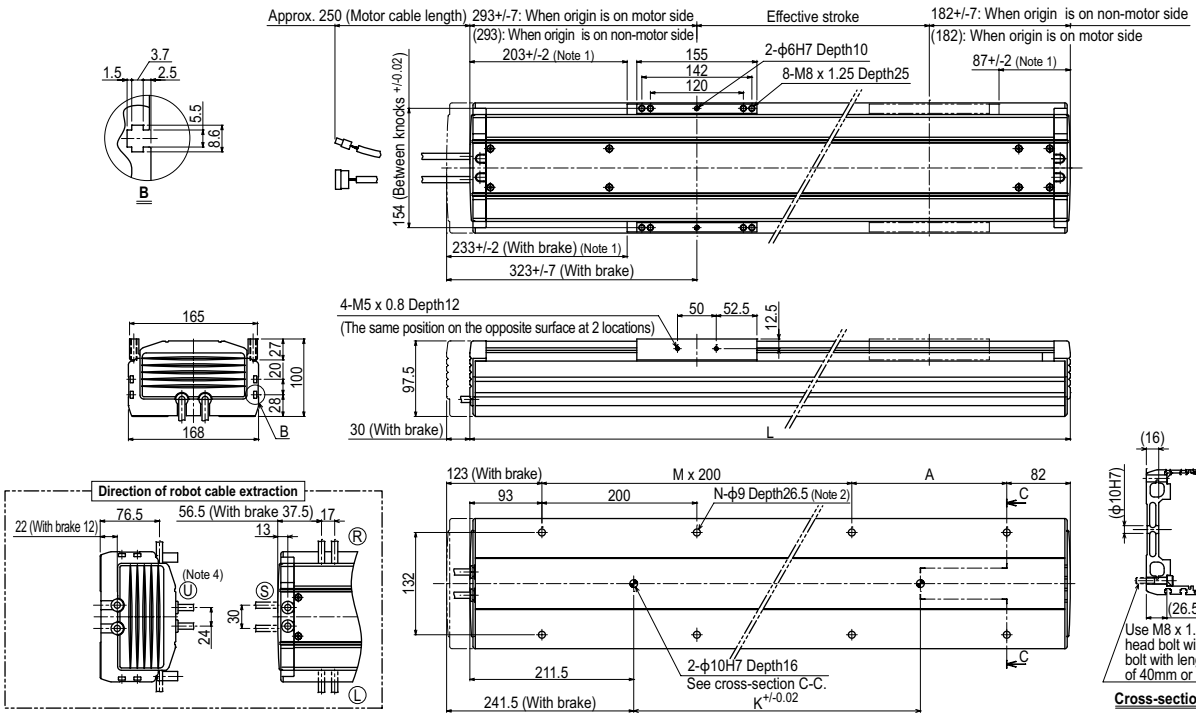
(Unit: N·m)

MY	MP	MR
1032	1034	908

Controller

Controller	Operation method
SR1-X20-R RCX320 RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X220-R	I/O point trace / Remote command
RDV-X220-RBR1 (Horizontal) RDV-X220-RBR2 (Vertical)	Pulse train control

F17L



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. It is not allowed to use a counter bore washer, etc. when installing the main unit.
Note 3. This is the weight of the model without a brake. The weight of the model equipped with a brake is 1.2kg heavier than this value.
Note 4. Make a separate consultation with us regarding robot cable (brake specifications) U extraction. (External dimensions: overall length + 20 mm)

Effective stroke		1100	1150	1200	1250	1300	1350	1400	1450	1500	1550	1600	1650	1700	1750	1800	1850	1900	1950	2000	2050
L		1575	1625	1675	1725	1775	1825	1875	1925	1975	2025	2075	2125	2175	2225	2275	2325	2375	2425	2475	2525
A		200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150
M		6	7	7	7	7	8	8	8	8	9	9	9	9	10	10	10	10	11	11	11
N		16	18	18	18	18	20	20	20	20	22	22	22	22	24	24	24	24	26	26	26
K		1140	1140	1320	1320	1320	1320	1320	1320	1320	1320	1320	1320	1320	1320	1320	1320	1320	1320	1320	1320
Weight (kg) Note 3		34.1	34.9	35.8	36.7	37.6	38.4	39.3	40.2	41.1	42	42.9	43.8	44.7	45.6	46.5	47.3	48.2	49.1	50	50.9
Maximum speed Note 5 (mm/sec)	Lead 50	2200			1900				1500				1200				900			800	
	Speed setting	–			86%				68%				54%				40%			36%	

Note 5. When the stroke exceeds 1200mm, although depending on the moving range, the ball screw may resonate (critical speed). In that case, make adjustment to lower the speed on the program using the maximum speed given in the above table as a guide.

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

GF17XL

Origin on the non-motor side is selectable

Note. If you need an installation posture other than the horizontal installation, please contact us.

Ordering method

GF17XL - S H - 20 [ ] [ ] [ ] [ ] [ ] [ ]

Model	Model	Installation direction	Lead designation	Cable entry location	Origin position change	Frame	Grease type	Stroke	Cable length Note 1
	S: Straight model	H: Horizontal installation		No entry: Standard (S) U: From the top R: From the right L: From the left	None: Standard Z: Non-motor side	No entry: Standard (Spot facing) T: Tapping	None: Standard GC: Clean	850 to 2500 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX 220 [ ] [ ] [ ] [ ]

Positioner Note 2	Driver: Power-supply voltage / Power capacity	Regenerative unit	LCD monitor	I/O selection	Battery
TSX: TS-X	220: 200V/400 to 600W	No entry: None R: With RGT	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 3	B: With battery (Absolute) N: None (Incremental)

SR1-X 20 [ ] R Note 4 [ ] [ ]

Controller	Driver: Power capacity	Usable for CE	Regenerative unit	I/O selection	Battery
	20: 400 to 600W	No entry: Standard E: CE marking	No entry: None R: With RG1	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X 2 20 - RBR1

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
	2: AC200V	20: 600W or less	

Note 1. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.692 for details on robot cable.
Note 2. See P.600 for DIN rail mounting bracket.
Note 3. Select this selection when using the gateway function.
Note 4. When operating the robot at a speed that is a maximum speed of 750 mm/sec or less, the regenerative unit is not needed.

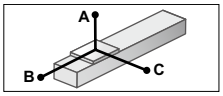
[Cautions after purchase]
- When changing the origin position, contact us since the adjustment is needed.
- When changing the cable entry location, contact us since necessary parts may vary depending on the cable entry location.
- Do not install the robot with the horizontal installation specifications in a direction other than the horizontal direction.

Specifications

AC servo motor output (W)	400
Repeatability Note 1 (mm)	+/-0.01
Deceleration mechanism	Ball screw ϕ20
Ball screw lead (mm)	20
Maximum speed (mm/sec)	1200 Note 2
Maximum payload (kg)	90
Rated thrust (N)	339
Stroke (mm)	850 to 2500 (50mm pitch)
Overall length (mm)	Stroke+686
Maximum dimensions of cross section of main unit (mm)	W168×H105.5
Cable length (m)	Standard: 3.5 / Option: 5,10
Linear guide type	4 rows of circular arc grooves × 2 rail
Position detector	Resolvers Note 3
Resolution (Pulse/rotation)	20480

Note 1. Positioning repeatability in one direction.
Note 2. To operate the unit at a speed exceeding 750 mm/sec. (Max. speed), a regeneration unit is required.
Note 3. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note

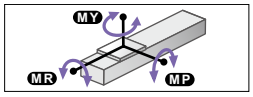


Horizontal installation (Unit: mm)

		A	B	C
Lead 20	30kg	4050	1090	1405
	50kg	2755	650	835
	90kg	1610	345	450

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.
Note. Service life is calculated for 1000mm stroke models.

Static loading moment



(Unit: N·m)

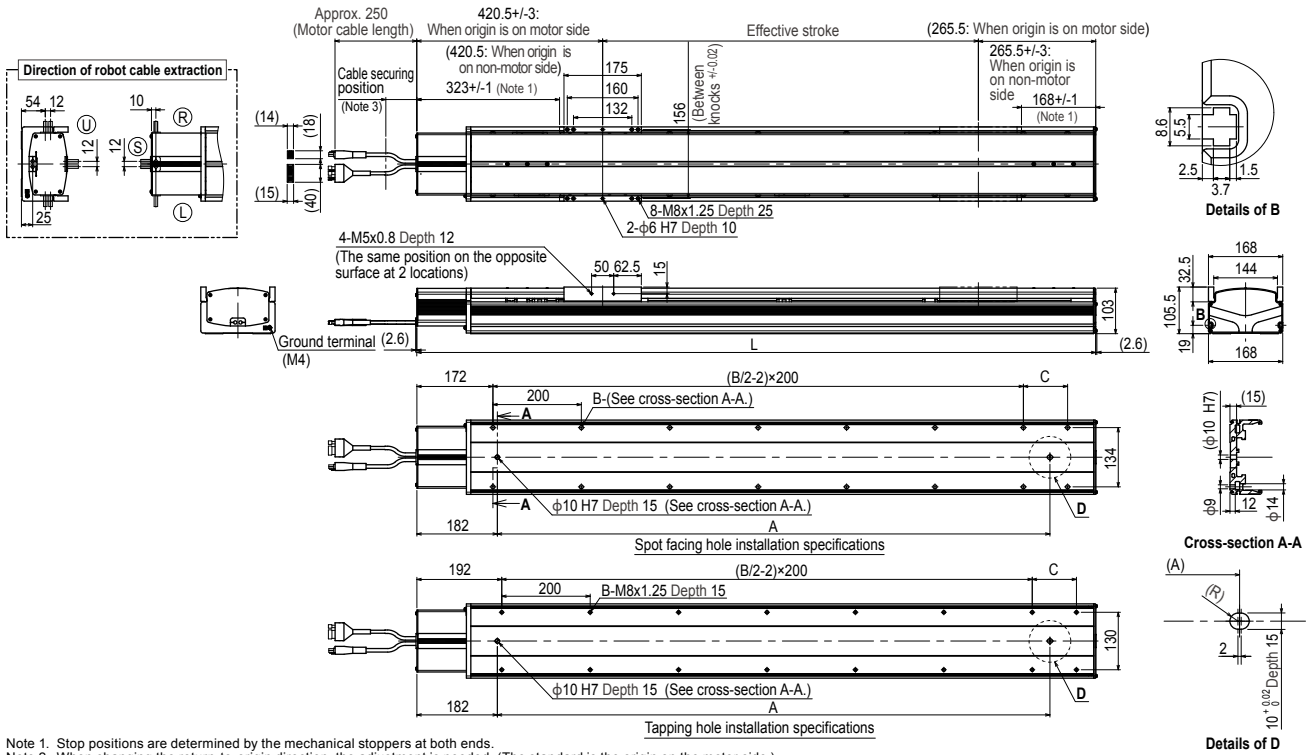
MY	MP	MR
1032	1034	908

Controller

Controller	Operation method
SR1-X20 Note RCX320 RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X220	I/O point trace/ Remote command
RDV-X220-RBR1	Pulse train control

Note. To operate the unit at a speed exceeding 750 mm/sec. (Max. speed), a regeneration unit is required.

GF17XL



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. When changing the return-to-origin direction, the adjustment is needed. (The standard is the origin on the motor side.)
Note 3. Secure the cable with a tie-band 100mm or less from unit's end face to prevent the cable from being subjected to excessive loads.
Note 4. The cable's minimum bend radius is R30.
Note 5. The length under head of the hexagonal socket head bolts (M8 x 1.25) that are used to install the main body with the spot facing hole installation specifications is 45 mm or more. It is recommended that the length under head of the hexagonal socket head bolts (M8 x 1.25) that are used to install the main body with the tapping hole installation specifications is the thickness of the installation base + 15 mm or less.

Effective stroke	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450	1500	1550	1600	1650	1700	1750	1800	1850	1900	1950	2000	2050	2100	2150	2200	2250	2300	2350	2400	2450	2500
L	1536	1586	1636	1686	1736	1786	1836	1886	1936	1986	2036	2086	2136	2186	2236	2286	2336	2386	2436	2486	2536	2586	2636	2686	2736	2786	2836	2886	2936	2986	3036	3086	3136	3186
A	1250	1300	1350	1400	1450	1500	1550	1600	1650	1700	1750	1800	1850	1900	1950	2000	2050	2100	2150	2200	2250	2300	2350	2400	2450	2500	2550	2600	2650	2700	2750	2800	2850	2900
B	16	16	16	18	18	18	18	20	20	20	20	22	22	22	22	24	24	24	24	26	26	26	26	28	28	28	28	30	30	30	30	32	32	32
C	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150
Weight (kg)	37.4	38.4	39.4	40.3	41.3	42.3	43.2	44.2	45.2	46.1	47.1	48.1	49.0	50.0	51.0	51.9	52.9	53.9	54.8	55.8	56.8	57.7	58.7	59.7	60.6	61.6	62.6	63.5	64.5	65.5	66.4	67.4	68.4	69.3

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

F20

High lead: Lead 40

Origin on the non-motor side is selectable

Note. Upper robot cable (U) on models with brakes is a special order item, so please consult our sales office or sales representative for assistance. (External dimensions: overall length + 20 mm)

Ordering method

F20 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Lead designation	Brake Note 1	Cable entry location	Origin position change	Grease type	Stroke	Cable length Note 3
	40: 40mm 20: 20mm 10: 10mm	No entry: No brakes BK: Brakes provided	No entry: Standard (S) U: From the top Note 2 R: From the right L: From the left	None: Standard Z: Non-motor side	None: Standard GC: Clean	Lead 20: 10: 200 to 1250 (50mm pitch) Lead 40: 200 to 1450 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX - **220** - [ ] - [ ] - [ ] - [ ]

Positioner Note 4	Driver: Power-supply voltage / Power capacity Note 5	Regenerative unit Note 6	LCD monitor	I/O selection	Battery
TSX: TS-X	220: 200V/400 to 600W	No entry: None R: With RGT	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 7	B: With battery (Absolute) N: None (Incremental)

SR1-X - **20** - [ ] - [ ] - [ ] - [ ]

Controller	Driver: Power capacity Note 5	Usable for CE	Regenerative unit Note 6	I/O selection	Battery
	20: 400 to 600W	No entry: Standard E: CE marking	No entry: None R: With RG1	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X - **2** - **20** - [ ]

Driver	Power-supply voltage	Driver: Power capacity Note 5	Regenerative unit Note 6
	2: AC200V	20: 600W or less	RBR1 (Horizontal) RBR2 (Vertical)

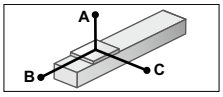
Note 1. The model with a lead of 10mm cannot select specifications without brake (horizontal specifications).
The model with a lead of 40mm cannot select specifications with brake (vertical specifications).
Note 2. Upper robot cable (U) on models equipped with brake is a special-order item.
Note 3. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.692 for details on robot cable.
Note 4. See P.600 for DIN rail mounting bracket.
Note 5. Acceleration / deceleration is different depending the Positioner or Controller or Driver.
Note 6. The robot with the high lead specifications (lead 40) needs a regenerative unit.
Note 7. Select this selection when using the gateway function.

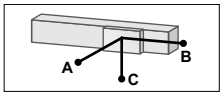
Specifications

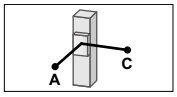
AC servo motor output (W)		600		
Repeatability Note 1 (mm)		+/-0.01		
Deceleration mechanism		Ball screw ϕ20		
Ball screw lead (mm)		40	20	10
Maximum speed Note 2 (mm/sec)		2400	1000 (1200 Note 3)	600
Maximum payload (kg)	**Horizontal**	60	120	–
	Vertical	–	25	45
Rated thrust (N)		255	510	1020
Stroke (mm)		200 to 1450 Note 4 (50mm pitch)		
Overall length (mm)	**Horizontal**	Stroke+427	Stroke+417	–
	Vertical	–	Stroke+447	
Maximum dimensions of cross section of main unit (mm)		W202 × H115		
Cable length (m)		Standard: 3.5 / Option: 5,10		
Linear guide type		4 rows of circular arc grooves × 2 rail		
Position detector		Resolvers Note 5		
Resolution (Pulse/rotation)		16384		

Note 1. Positioning repeatability in one direction.
Note 2. When the stroke is longer than 800mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
Note 3. To operate the unit at a speed exceeding 1,000mm/sec. (Max. speed), a regeneration unit RG1 is required.
Note 4. Longer than 1250mm stroke can be handled by the high lead specification (Lead 40) only.
Note 5. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note







Horizontal installation (Unit: mm)

		A	B	C
Lead 40	10kg	4000	4000	3450
	20kg	3397	2235	2073
	60kg	2443	718	977
Lead 20	50kg	2602	869	1083
	80kg	2193	528	703
	120kg	1841	339	505

Wall installation (Unit: mm)

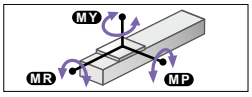
		A	B	C
Lead 40	10kg	3571	4000	4000
	20kg	2118	2164	3397
	60kg	1000	648	2443
Lead 20	50kg	1097	799	2602
	80kg	708	458	2193
	120kg	468	268	1841

Vertical installation (Unit: mm)

		A	C
Lead 20	15kg	2635	2635
	20kg	2000	2000
	25kg	1621	1621
Lead 10	20kg	2188	2188
	30kg	1446	1446
	45kg	951	951

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



(Unit: N·m)

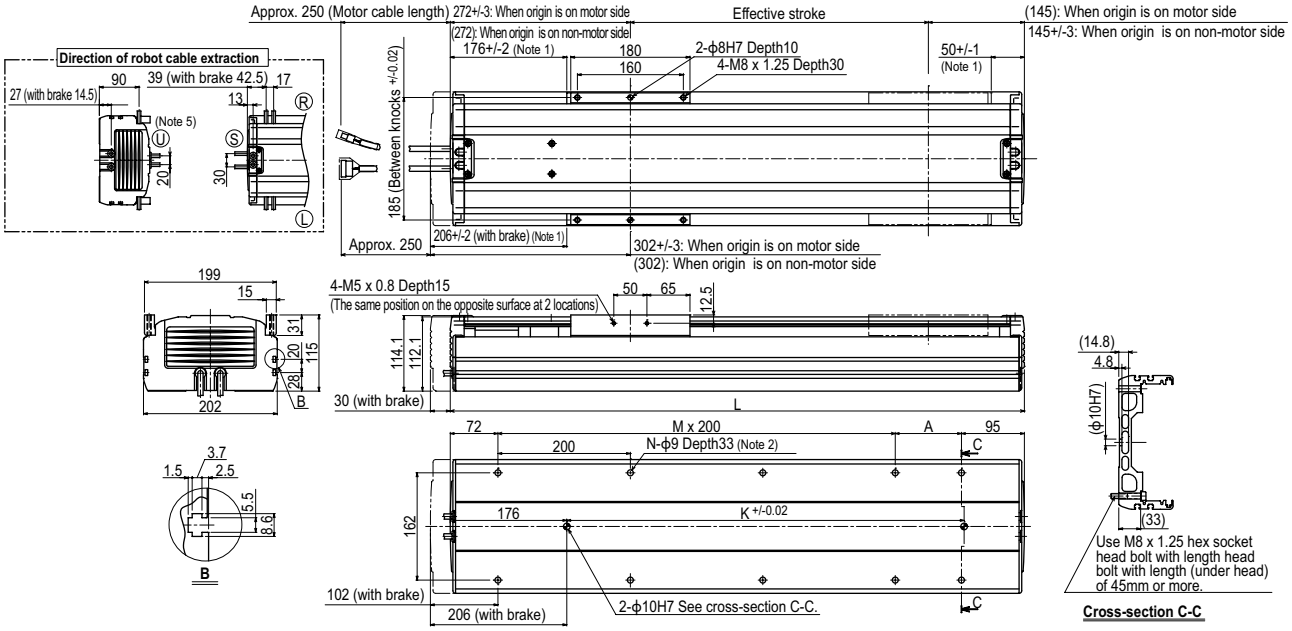
MY	MP	MR
1196	1199	1052

Controller

Controller	Operation method
SR1-X20 Note RCX320, RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X220 Note	I/O point trace / Remote command
RDV-X220-RBR1 (Horizontal) RDV-X220-RBR2 (Vertical)	Pulse train control

Note. [The following arrangements require a regeneration unit.]
- Using in the upright position.
- To move at a speed exceeding 1,000 mm/sec horizontally.
- High lead (40) used horizontally.

F20



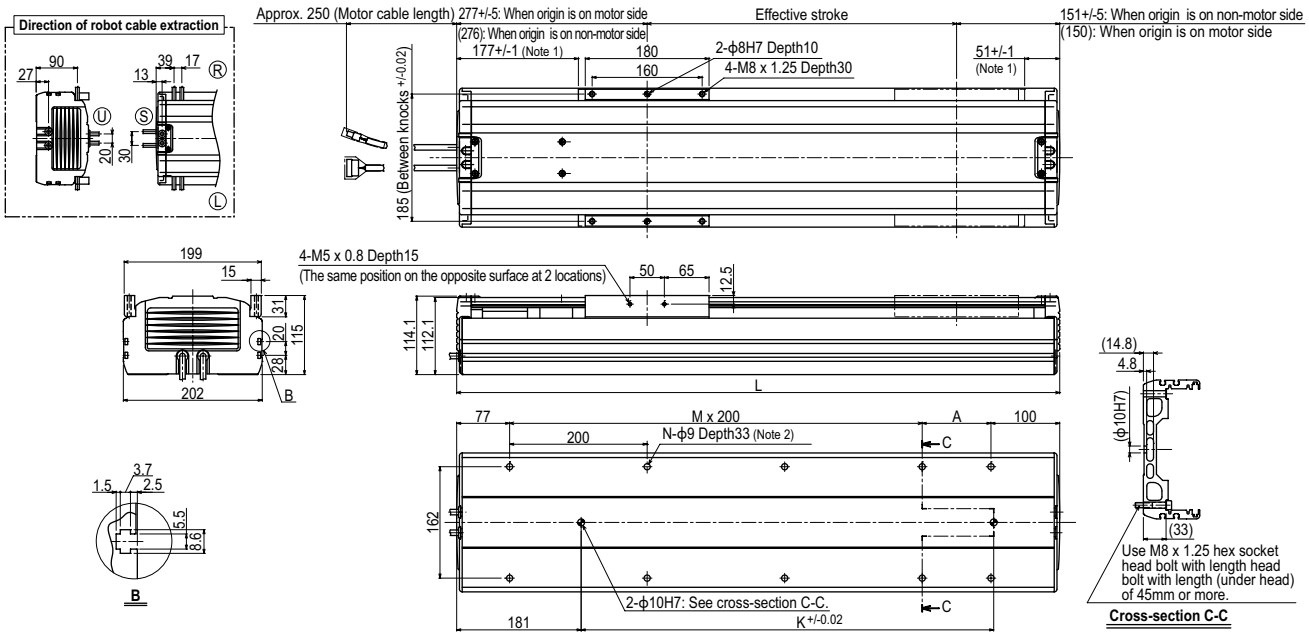
Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. When installing the robot, do not use washers inside the robot body.
Note 3. Minimum bend radius of motor cable is R50.
Note 4. Weight of models with no brake. The weight of brake-attached models is 1.5 kg heavier than the models with no brake shown in the table.
Note 5. Make a separate consultation with us regarding robot cable (brake specifications) U extraction. (External dimensions: overall length + 20 mm)

Effective stroke		200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250
L		617	667	717	767	817	867	917	967	1017	1067	1117	1167	1217	1267	1317	1367	1417	1467	1517	1567	1617	1667
A		50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100
M		2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6	6	7	7
N		8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18
K		420	420	420	420	600	600	600	600	780	780	780	780	960	960	960	960	1140	1140	1140	1320	1320	1320
Weight (kg) Note 4		21.0	22.0	22.9	23.8	24.8	25.7	26.6	27.5	28.5	29.4	30.3	31.2	32.1	33.0	34.0	34.9	35.8	36.7	37.7	38.6	39.5	40.4
Maximum speed Note 6 (mm/sec)	Lead 20	1000 (1200 Note 7)													960		840		720		600		480
	Lead 10	600													480		420		360		300		240
	Speed setting	–													80%		70%		60%		50%		40%

Note 6. When the stroke exceeds 800mm, although depending on the moving range, the ball screw may resonate (critical speed). In that case, make adjustment to lower the speed on the program using the maximum speed given in the above table as a guide.
Note 7. To operate the unit at a speed exceeding 1,000mm/sec. a regeneration unit RG1 is required.

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

F20 High lead type: Lead 40



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. When installing the robot, do not use washers inside the robot body.
Note 3. Minimum bend radius of motor cable is R50.

Effective stroke	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450
L	627	677	727	777	827	877	927	977	1027	1077	1127	1177	1227	1277	1327	1377	1427	1477	1527	1577	1627	1677	1727	1777	1827	1877
A	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100
M	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6	6	6	7	7	7	7	8	8
N	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18	18	20	20
K	420	420	420	420	600	600	600	600	780	780	780	780	960	960	960	960	1140	1140	1140	1320	1320	1320	1320	1320	1320	1320
Weight (kg)	21.2	22.2	23.1	24.0	25.0	25.9	26.8	27.7	28.7	29.6	30.5	31.4	32.3	33.2	34.2	35.1	36.0	36.9	37.9	38.8	39.7	40.6	41.5	42.4	43.3	44.2
Maximum speed (mm/sec) Note 4 — Lead 40	2400													1920		1680		1440		1200		960		840		720
Maximum speed (mm/sec) Note 4 — Speed setting	–													80%		70%		60%		50%		40%		35%		30%

Note 4. When the stroke is longer than 800mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.
Note 5. Longer than 1250mm stroke can be handled by the high lead specification (Lead 40) only.

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606

F20N

Ordering method

F20N - 20 - [ ] - [ ] - [ ] - [ ]

Model	Lead designation	Origin position change	Grease type	Stroke	Cable length Note 1
F20N	20	None: Standard Z: Non-motor side	None: Standard GC: Clean	1150 to 2050 (100mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX 220 - [ ] - [ ] - [ ] - [ ]

Positioner Note 2	Driver: Power-supply voltage / Power capacity	Regenerative unit	LCD monitor	I/O selection	Battery
TSX: TS-X	220: 200V/400 to 600W	No entry: None R: With RGT	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board Note 3	B: With battery (Absolute) N: None (Incremental)

SR1-X 20 - [ ] - [ ] - [ ] - [ ]

Controller	Driver: Power capacity	Usable for CE	Regenerative unit	I/O selection	Battery
	20: 400 to 600W	No entry: Standard E: CE marking	No entry: None R: With RG1	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X 2 20 - RBR1

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
	2: AC200V	20: 600W or less	

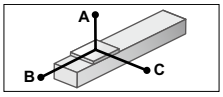
Note 1. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable.
See P.692 for details on robot cable.
Note 2. See P.600 for DIN rail mounting bracket.
Note 3. Select this selection when using the gateway function.

Specifications

AC servo motor output (W)	400
Repeatability Note 1 (mm)	+/-0.04
Deceleration mechanism	Ball screw ϕ20
Ball screw lead (mm)	20
Maximum speed (mm/sec)	1000 (1200 Note 2)
Maximum payload (kg)	80
Rated thrust (N)	339
Stroke (mm)	1150 to 2050 (100mm pitch)
Overall length (mm)	Stroke+420
Maximum dimensions of cross section of main unit (mm)	W202 × H120
Cable length (m)	Standard: 3.5 / Option: 5,10
Linear guide type	4 rows of circular arc grooves × 2 rail
Position detector	Resolvers Note 3
Resolution (Pulse/rotation)	16384

Note 1. Positioning repeatability in one direction.
Note 2. A regenerative unit is needed if using the SR1-X, TS-X at maximum speeds exceeding 1000mm /sec.. If using the RDV-X, then the regenerative unit RBR1 is required regardless of the installation conditions.
Note 3. Position detectors(resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang Note

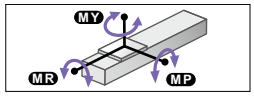


Horizontal installation (Unit: mm)

		A	B	C
Lead 20	20kg	3397	2332	2683
	40kg	2795	1144	1361
	60kg	2443	749	914
	80kg	2193	551	695

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



(Unit: N·m)

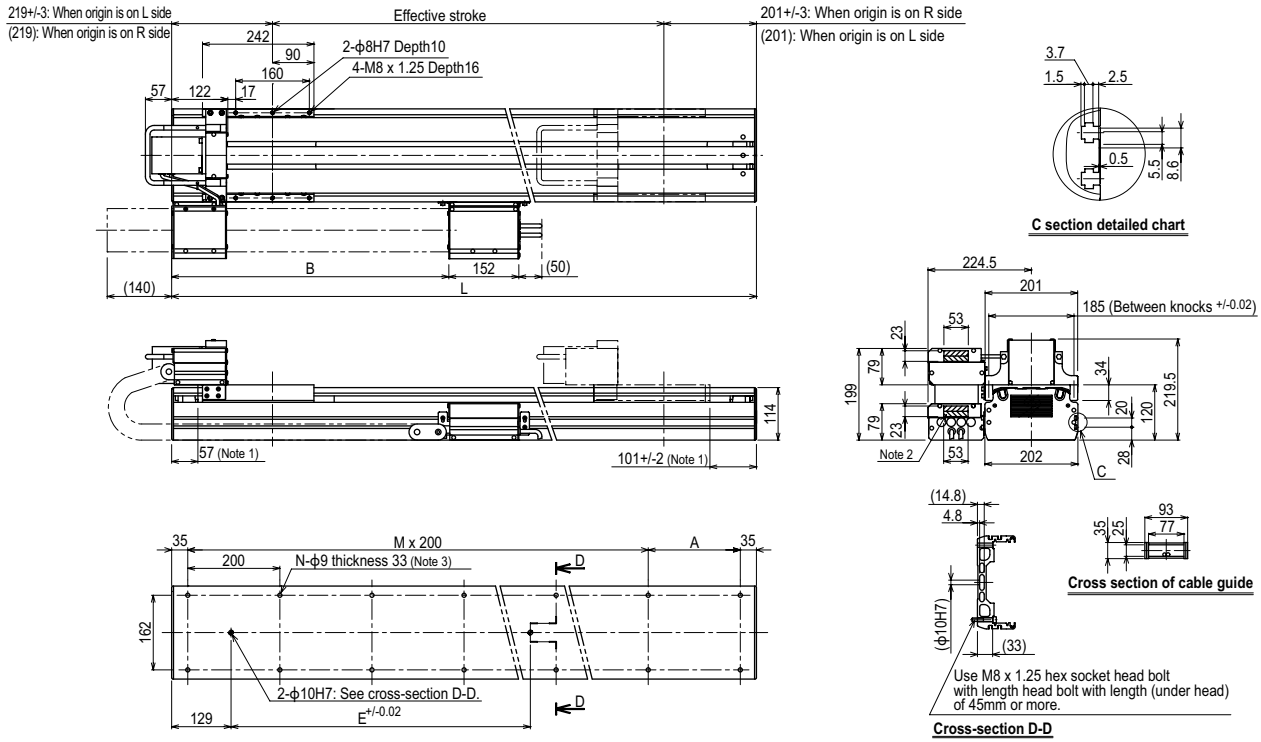
MY	MP	MR
1196	1199	1052

Controller

Controller	Operation method
SR1-X20 Note RCX320 RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X220 Note	I/O point trace / Remote command
RDV-X220-RBR1	Pulse train control

Note. When the unit is operated at a speed exceeding the maximum speed of 1,000mm/sec., a regeneration unit is required.

F20N



Effective stroke	1150	1250	1350	1450	1550	1650	1750	1850	1950	2050
L	1570	1670	1770	1870	1970	2070	2170	2270	2370	2470
A	100	200	100	200	100	200	100	200	100	200
B	602	648	694	740	786	832	878	924	970	1016
E	1320	1320	1320	1320	1320	1320	1320	1320	1320	1320
M	7	7	8	8	9	9	10	10	11	11
N	18	18	20	20	22	22	24	24	26	26
Weight (kg)	54.0	56.2	58.4	60.6	62.9	65.1	67.3	69.6	71.8	74.0

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
Note 2. The shaded position indicates the user cable extraction port.
Note 3. When installing the robot, do not use washers inside the robot body.
Note 4. The origin is set on the left (L) side at shipping.

Controller SR1-X ▶ 618 TS-X ▶ 592 RDV-X ▶ 606