

# SXYxC

4 axes / ZRSC

- Clean type
- Cable duct
- ZR-axis integrated type



## Ordering method

**SXYxC - D** [ ] [ ] [ ] [ ] - **15** - **RCX340-4** [ ] [ ] [ ] [ ] [ ] [ ] [ ] [ ] [ ] [ ]

Model	Cable	Combination	X axis stroke	Y axis stroke	ZR axis	Z axis stroke	Cable length	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	D: Cable duct	T1 T3	15 to 105cm	15 to 65cm	ZRSC12 ZRSC6		3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ **P.566**

## Basic specifications

	X axis	Y axis	Z axis ZRSC12	Z axis ZRSC6	R axis
<b>Axis construction</b> <sup>Note 1</sup>	C14H	C14	-	-	R5
<b>AC servo motor output (W)</b>	200	100	60	60	100
<b>Repeatability</b> <sup>Note 2</sup> (XYZ: mm) (R: °)	+/-0.01	+/-0.01	+/-0.02	+/-0.02	+/-0.005
<b>Drive system</b>	Ball screw φ15	Ball screw φ15	Ball screw φ12	Ball screw φ12	Harmonic gear
<b>Ball screw lead</b> <sup>Note 3</sup> (Deceleration ratio) (mm)	20	20	12	6	(1/50)
<b>Maximum speed</b> <sup>Note 4</sup> (XYZ: mm/sec) (R: °/sec)	1000	1000	1000	500	1020
<b>Moving range (XYZ: mm) (R: °)</b>	150 to 1050	150 to 650	150	150	360
<b>Robot cable length (m)</b>	Standard: 3.5 Option: 5, 10				
<b>Degree of cleanliness</b>	CLASS 10 <sup>Note 5</sup>				
<b>Intake air (Nl/min)</b>	90 <sup>Note 6</sup>				

- Note 1. Use caution that the frame machining (installation holes, tap holes) differs from single-axis robots.  
 Note 2. Positioning repeatability in one direction.  
 Note 3. Leads not listed in the catalog are also available. Contact us for details.  
 Note 4. When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.  
 Note 5. Per 1cf (0.1µm base), when suction blower is used.  
 Note 6. The necessary intake amount varies depending on the use conditions and environment.

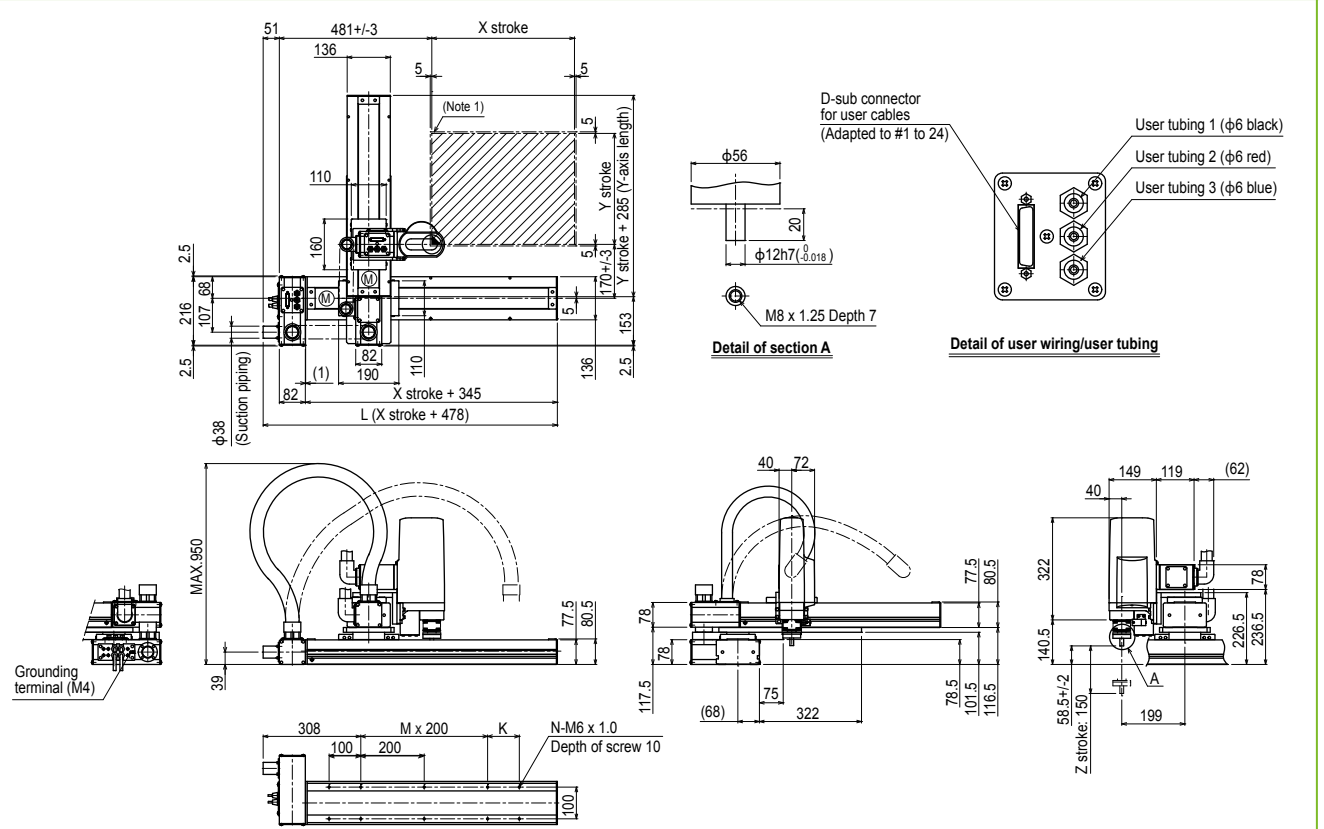
## Maximum payload (kg)

Y stroke (mm)	ZRSC12	ZRSC6
150	3	5
250		
350		
450		
550		
650	4	

## Controller

Controller	Operation method
RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication

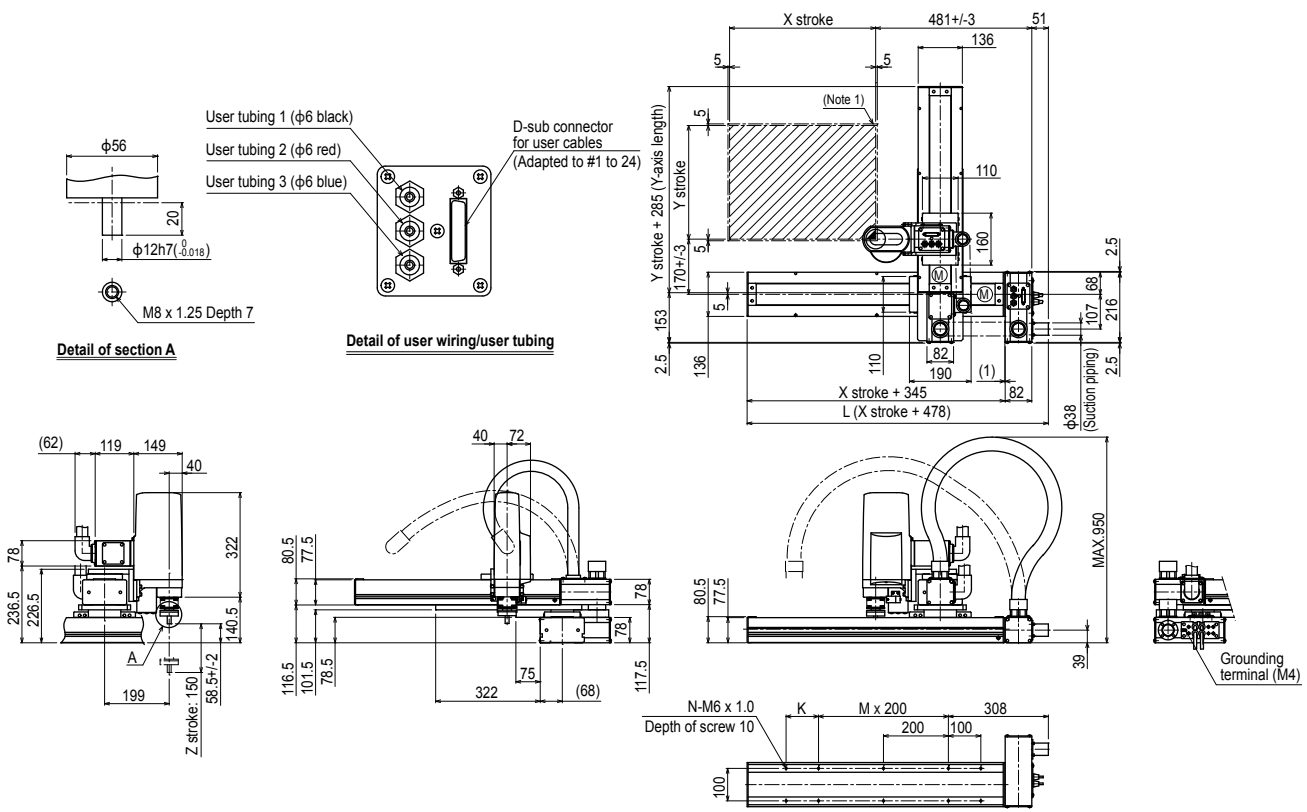
## SXYxC 4 axes / ZRSC (T1)



X stroke	150	250	350	450	550	650	750	850	950	1050	
	L	628	728	828	928	1028	1128	1228	1328	1428	1528
K	200	100	200	100	200	100	200	100	200	100	
M	0	1	1	2	2	3	3	4	4	5	
N	6	8	8	10	10	12	12	14	14	16	
<b>Y stroke</b>	<b>150</b>	<b>250</b>	<b>350</b>	<b>450</b>	<b>550</b>	<b>650</b>					
<b>Z stroke</b>	<b>150</b>										
<b>Maximum speed for each stroke (mm/sec)</b> <sup>Note 2</sup>	<b>X axis</b>	1000				800	650	550			
	<b>Speed setting</b>	-				80%	65%	55%			

- Note 1. The moving range when returning to origin and the stop position when stopping by mechanical stopper.  
 Note 2. When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

SXYxC 4 axes / ZRSC **T3**



X stroke	150	250	350	450	550	650	750	850	950	1050	
L	628	728	828	928	1028	1128	1228	1328	1428	1528	
K	200	100	200	100	200	100	200	100	200	100	
M	0	1	1	2	2	3	3	4	4	5	
N	6	8	8	10	10	12	12	14	14	16	
Y stroke	150	250	350	450	550	650					
Z stroke	150										
Maximum speed for each stroke (mm/sec)	1000					800			650	550	
Speed setting	-					80%			65%	55%	

Note 1. The moving range when returning to origin and the stop position when stopping by mechanical stopper.

Note 2. When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.