YK-X
Series

Product Lineup

YK-TW	Orbit type
YK-XG/YK-X	Completely beltless model Note
YK-XE	Low cost high performance model
YK-XGS	Wall mount/inverse model
YK-XGP	Dust-proof & drip-proof model

Note. Except for YK1200X

SCARA ROBOTS

Arm length of 120 mm to 1200 mm, full-selection of the lineup is top in the world.

Low cost high performance model
YK400XE-4

History of 45 years

The first YAMAHA robots were SCARA robots. Since the first SCARA robot called "CAME" was produced in 1979, some 45 years of SCARA robot innovations have continually appeared. These SCARA robots have undergone countless modifications in an ever changing marketplace and amassed a hefty record of successful products making them an essential part of the YAMAHA robot lineup.

1979
<YK7000>

Comprehensive line of YAMAHA SCARA robots

Orbit type

■ Arm length 350 mm / 500 mm
■ Maximum payload 5 kg

YK500TW

Low cost high performance model

■ Arm length 400 mm to 710 mm
■ Maximum payload 4 kg to 10 kg

YK400XE-4

YK510XE-10
YK610XE-10
YK710XE-10

Extra small type

■ Arm length 120 mm to 220 mm
■ Maximum payload 1 kg

YK120XG/YK150XG/YK180XG

YK180X/YK220X

Large type

■ Arm length 700 mm to 1200 mm
■ Maximum payload 10 kg to 50 kg

YK700XG

YK900XG

YK1000XG

YK1200X

Small type

■ Arm length 250 mm to 400 mm
■ Maximum payload 5 kg

YK250XG/YK350XG/YK400XG

Wall mount/inverse model

YK300XGS to YK1000XGS

Wall mount type

Inverse type

■ Wall mount type
Type where the robot body is installed in the wall.

■ Inverse type
Type where the wall mount type is installed upside down.

Medium type

■ Arm length 500 mm to 600 mm
■ Maximum payload 5 kg to 20 kg

YK500XGL

YK500XG

YK600XGL

YK600XG/XGH

Dust-proof & drip-proof model

YK250XGP/YK350XGP/YK400XGP
YK500XGLP/YK600XGLP

YK500XGP to YK1000XGP

Plays active part in the working environment with a large amount of water or dust (protection class equivalent to IP65).
● Please consult YAMAHA for anti-droplet protection for fluids other than water.

YK-TW Orbit type

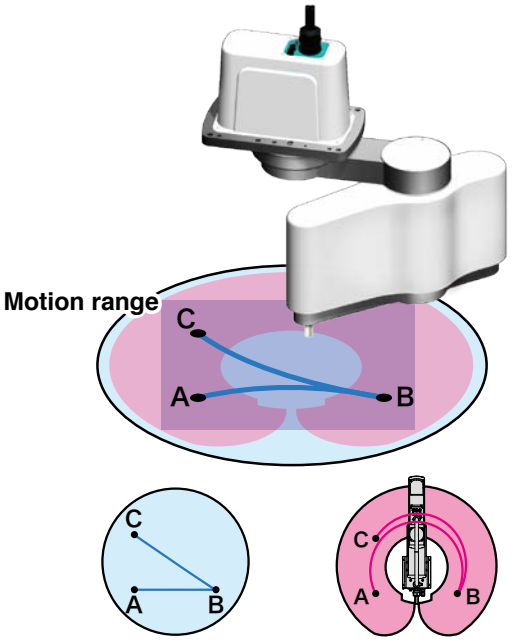
YK-TW POINT 1

Layout design freedom

User: We want a smaller equipment footprint.

YK-TW can move anywhere through the full ϕ 1000 mm Note 2 work envelope.

Featuring a ceiling-mount configuration with a wide arm rotation angle, the YK-TW can access any point within the full ϕ 1000 mm downward range. This eliminates all motion-related restrictions with regard to pallet and conveyor placement operations, while dramatically reducing the equipment footprint.



Orbit type SCARA robot Standard type SCARA robot

YK-TW POINT 2

Higher productivity

User: We need to reduce cycle time.

Standard cycle time of 0.29 secs. Note 2

Y-axis (arm 2) passes beneath the X-axis (arm 1) and it has a horizontal articulated structure, allowing it to move along the optimal path between points. Moreover, the optimized weight balance of the internal components reduces the cycle time by 36 % as compared to previous models.

The standard cycle time for moving a 1-kg load horizontally 300 mm and up/down 25 mm is shortened by approximately 36 % compared to existing YAMAHA models.

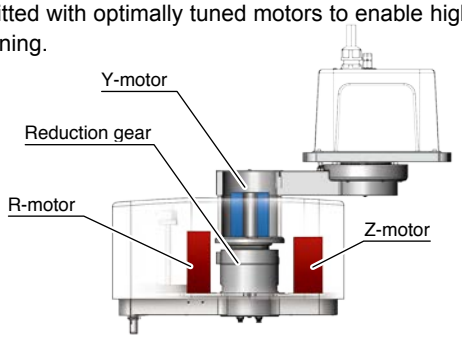
YK-TW POINT 3

High quality

User: We want a high precision assembly system.

YK-TW offers a repeated positioning accuracy of +/-0.01 mm Note 1 (XY axes).

Higher repeated positioning accuracy than that offered by a parallel-link robot. This was accomplished by optimizing the robot's weight balance through an extensive re-design of its internal construction. The lightweight yet highly rigid arm has also been fitted with optimally tuned motors to enable high accuracy positioning.



Hollow construction

Y-motor and reduction gear feature a hollow construction which allows them to be housed inside the harness arm.

360 ° Rotation.

Optimized rotation center of gravity moment

Weight balance was optimized by placing the R-motor and Z-motor at the left and right sides respectively.

Reduced inertia enables high-speed motion.

YK-TW POINT 4

Suitable for a wide range of applications

User: We need to move heavy workpieces at high speeds.

YK-TW handles payloads up to 5 kg.

Handles loads up to 5 kg. Also accommodates arm-end tools which tend to be heavy, making it highly adaptable to various applications.

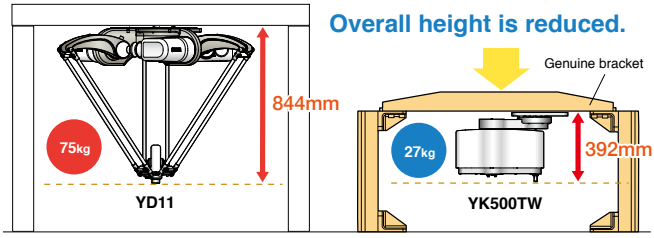
YK-TW POINT 5

Smaller equipment footprint

User: We want to reduce the height of our equipment.

YK-TW offers both a lower height and a smaller footprint.

YK-TW height is only 392 mm. This compact size enables more freedom in the equipment layout design.



Note 1. Applies to the YK350TW Note 2. Applies to the YK500TW

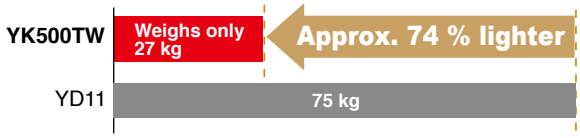
YK-TW POINT 6

Easy installation

User: Parallel-link robots require large frames which complicates installation…

YK-TW has a total height of only 392 mm, and weighs only 27 kg.

Lower inertia = Lighter frame



YK-TW POINT 7

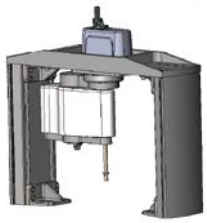
Reduce the number of steps

User: Preparing the frame is extra work.

We can optionally provide a dedicated frame for the YK-TW.

With no need for complex calculations of strength, startup steps can be reduced.

Note. For details on dimensions and price, please contact Yamaha.

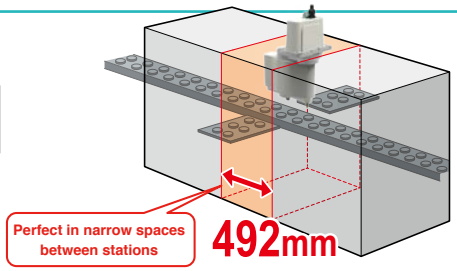


YK-TW POINT 8

Ideal for narrow space applications

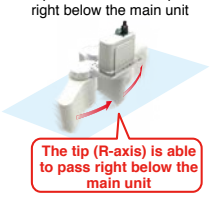
User: We need to install in limited space, such as between equipment.

Minimum installation width 492mm Note 1



Underpass motion

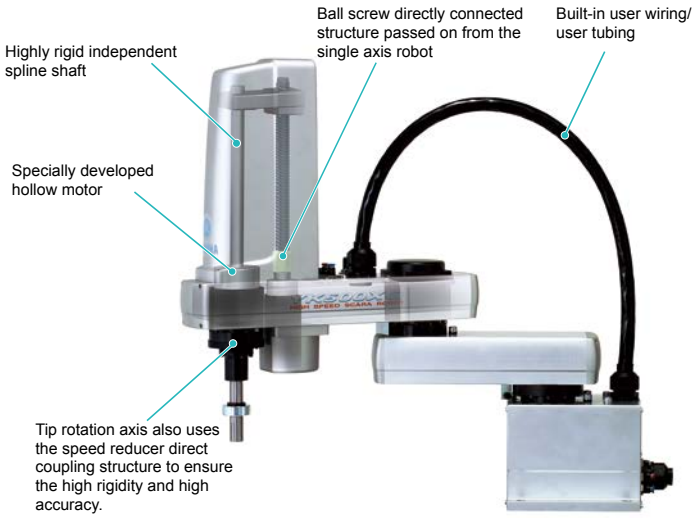
Optimize use of the space right below the main unit



YK-XG Completely beltless type

Integral structure designed for optimal operation

Note. The following shows an example of YK500XG.

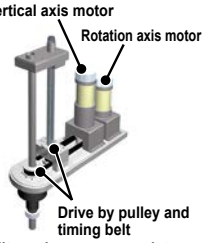


YK-XG POINT 1

Completely beltless structure

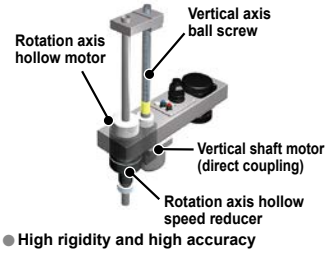
A completely beltless structure was achieved using a ZR-axis direct coupling structure. This completely beltless structure greatly reduces waste motion. This structure also maintains high accuracy for an extended period of time. Additionally, this structure ensures maintenance-free operation for an extended period of time without worrying about belt breakage, elongation, or secular deterioration (except for Orbit type and large type).

Conventional model



- Rigidity and accuracy are determined by belt.
- Secular change, such as belt elongation occurs.

YK-XG series



- High rigidity and high accuracy
- No worry about belt elongation and breakage
- Maintenance free

YK-XG POINT 2

Resolver is used for position detector.

As the resolver uses a simple and rigid structure without using electronic components and optical elements, it features high environment resistance and low failure ratio. Detection problems due to electronic component breakdown, dew condensation on or oil sticking to the disk that may occur in optical encoders do not occur in the resolver due to its structure. Additionally, as the absolute specifications and incremental specifications use the same mechanical specifications and common controller, the specifications can be changed only by setting parameters. Furthermore, even when the absolute battery is consumed completely, the robot can still operate as the incremental specifications. So, even if a trouble occurs, the line stop is not needed to ensure the safe production line. The backup circuit has been completely renovated and now has a backup period of one year in the non-energizing state.

Note. The resolver has a simple structure without using electronic components. So, the resolver is highly resistant to low and high temperatures, impacts, electrical noise, dust particles, and oil, etc., and is used in automobiles, trains, and aircrafts that particularly require the reliability.

Optical encoder

- Optical type
- Electronic components are required and structure is complicated.
- Electronic component malfunction, or dew condensation on or oily content sticking to disk may occur easily.

Detection failure

Resolver

- Magnetic type
- Simple structure only with iron core and winding has less potential failure factors.
- Immune to shock and electric noise.

High reliability

YK-XG POINT 3

Excellent maintenance ability

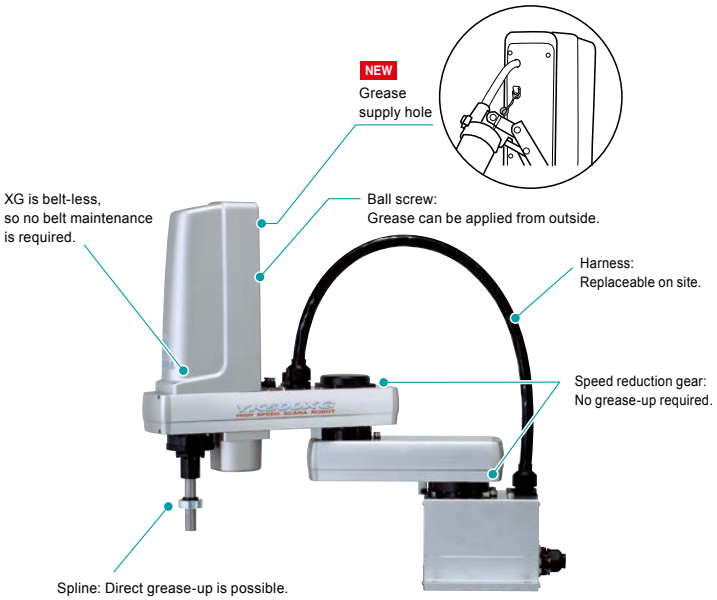
The covers of YAMAHA SCARA robot YK-XG series can be removed forward or upward. The cover is separated from the cable, so the maintenance work is easy. Additionally, the grease replacement of the speed reducer needs many steps to disassemble the gear and may cause positional deviation. However, since the speed reducer of the YAMAHA SCARA robot uses long-life grease, the grease replacement is not needed.

NEW

A grease supply hole is provided in the back of the cover. Even when greasing is required, the cover does not need to be removed for easy maintenance.

* The covers of the products shipped before March 2020 do not have grease supply holes, but can be replaced with covers that have grease supply holes. (Installation compatible. Please order a cover with grease supply hole separately.)

Target product: YK600XGH, YK700XG, YK800XG, YK900XG, YK1000X



YK-XG POINT 4

User can replace the motor and ball screw, etc.

In the case of other companies' SCARA robots, replacing motors and ball screws is time-consuming and in some cases difficult for customers to replace.
In this respect, YAMAHA SCARA robots are easy to replace these parts, so they can be replaced by the customer.

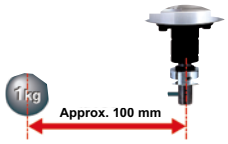
YK-XG POINT 5

High-speed transfer is possible even with heavy workpieces and large offsets.

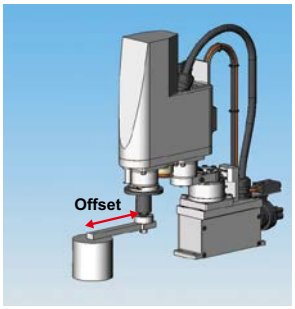
The SCARA robot performance cannot be expressed only by the standard cycle time. In actual operating environments, there are various workpieces, such as heavy workpiece or workpiece with large offset. At this time, since the robot with low R-axis tolerable moment of inertia needs to decrease the speed during operation, the cycle time decreases greatly. All YAMAHA SCARA robot YK-XG types have the tip rotation axis directly coupled to the speed reducer. Since the R-axis tolerable moment of inertia is very high when compared to a general structure in which the moment of inertia is transmitted by a belt after decelerating, the robot can operate at a high speed even with workpieces that have been offset.

YK180XG
(R-axis tolerable moment of inertia: 0.01 kgfcms^2)

When the tip load weight is 1 kg, it is possible to operate at **approx. 100 mm** offset.



Optimal acceleration and deceleration are set automatically.

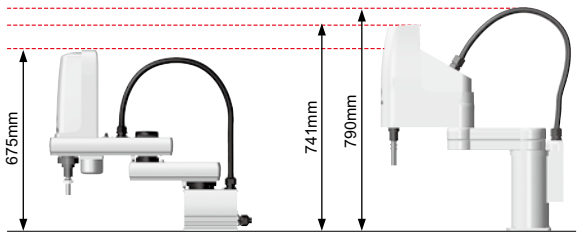


The moment of inertia varies depending on the shape of the workpiece and the offset distance from the R-axis tip to the load center of gravity.
When the offset is large even with the same payload, this value increases. So, the acceleration during operation needs to be reduced.
With the RCX340, the optimum acceleration is automatically set by simply setting the moment of inertia value, so there is no need for troublesome settings.

YK-XG POINT 6

Compact

As the cable layout is changed, the cable height becomes lower than the main body cover. Additionally, use of extruded material base and motor with low overall height achieves the lowest overall height in the same class.



YK500XG YAMAHA's conventional model

YK-XG POINT 7

Hollow shaft and tool flange options are selectable.

Hollow shaft that allows easy wiring to the tip tool and tool flange for tool mounting are provided as options.

Hollow shaft option convenient for routing of air tubes and harness wires

Note. YK250XG to YK400XG
YK500XGL/YK600XGL

Tool flange option for easy mounting of a tool to the tip

Note. YK250XG to YK1000XG

YK-XG POINT 8

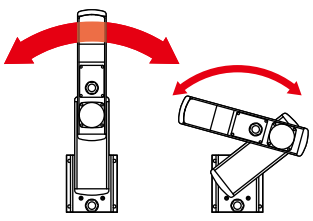
Zone control (= Optimal acceleration/deceleration automatic setting) function

In the SCARA robot, the load applied to the motor and speed reducer in the arm folded state greatly differs from that in the arm extended state. YAMAHA SCARA robot automatically selects optimal acceleration and deceleration from the arm postures at operation start and operation end. Therefore, the robot does not exceed the tolerance value of the motor peak torque or speed reducer allowable peak torque only by entering the initial payload. So, full power can be extracted from the motor whenever needed and high acceleration/deceleration are maintained.

For X-axis of YK500XG

The torque in the arm folded state is 5 or more times different from that in the arm extended state.

This may greatly affect the service life, vibration during operation, and controllability.



If the motor torque exceeds the peak value
→ **This may adversely affect the controllability and mechanical vibration, etc.**
If the torque exceeds the tolerable peak torque value of the speed reducer
→ **This may cause early breakage or extremely shorten the service life.**

Robot stops at a desired position accurately to ensure long service life.

YK-XE Low cost high performance model

YK-XE POINT 1

Both the high operation performance and low-price are provided.

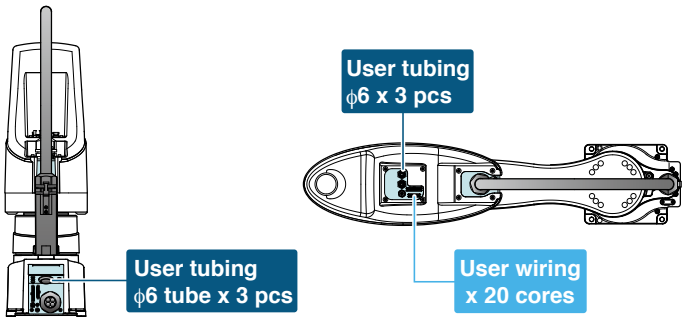
Both the high operation performance and low-price are provided.
Production equipment with high cost performance can be constructed.

YK400XE-4 | YK510XE-10 | YK610XE-10 | YK710XE-10

YK-XE POINT 2

Improved User Interface

Enhanced size and numbers of air tubes and user I/O for end effectors.
Tubes and wires are positioned for easy layout and reduced risk of disconnection.
(YK510XE-10, YK610XE-10, YK710XE-10)



Note. YK400XE-4 provides the user wiring x 10 cores and the User tubing ϕ4 x 3 pcs.

YK-XE POINT 3

Option specifications

Through-shaft and through-cap have been added.

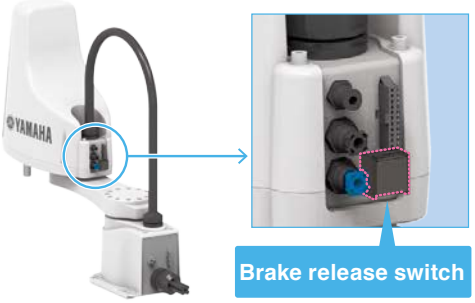
"Through-shaft" or "through-cap" option for wiring and tubing that is convenient to run the air tubing and wiring can be selected. The wiring and tubing routes can be investigated easily without designing and manufacturing a stay for installing the wiring and tubing. In addition, by passing the wiring and tubing through the inside of the main body, worries about wire breakage or disconnection are reduced during operation. (Through-shaft is only available with the YK400XE-4.)

YK-XE POINT 4

Option specifications

Brake release switch is selectable.

In the emergency stop state, the Z-axis brake is released and the Z-axis can be moved up or down while the brake release switch is held down. Releasing the switch applies the brake to the Z-axis. This improves the convenience during installation adjustment.



YK-XGS Wall mount/inverse model

Hanging type is renewed. Completely beltless structure and high rigidity

As the conventional hanging type is changed to the wall mount type, the flexibility of the system design is improved. The production equipment can be downsized. Additionally, as an inverse type that allows upward operation is also added to the product lineup, the flexibility of the working direction is widened. Furthermore, use of a completely beltless structure achieves a maximum payload of 20 kg and a R-axis tolerable moment of inertia of 1 kgm^2 Note that are the top in the class. A large hand can also be installed. So, this robot is suitable for heavy load work.

Note. YK700XGS to YK1000XGS

Inverse type

YK-XGP Dust-proof & drip-proof model

Up/down bellows structure improves the dust-proof and drip-proof performance.

The dust-proof and drip-proof type that can be operated even in a work environment where water or particle dust scatters was renewed to a completely beltless structure. The belt does not deteriorate and poor environment resistance is improved. Additionally, an up/down bellows structure is used to improve the dust-proof and drip-proof performance.

Note. YK250XGP to YK600XGLP

Protection class equivalent to IP65 (IEC60529)

Seals are added to the joints to maintain the dust-proof and drip-proof performance without air purging. The robot conforms to the protection class equivalent to IP65 (IEC60529).

IP 6 5

Class of protection against invasion of water: 5
Water injected from any direction does not affect adversely.
The standard pressure of the injected water is 30 KPa (30 KN/m², 0.3 kgf/cm).
The injection speed is 12.5 liters/min. and the injection time is 3 min.
Note. The water injected under conditions exceeding those shown above may enter the unit.

Class of protection against solid objects: 6
No invasion of particle dust.

Dust-proof and drip-proof connector for user wiring is provided as standard.

YK250XGP to 600XGLP (arm part)

YK250XGP to 600XGLP (base part)

SCARA robot / Single-axis robot / Cartesian robot / Pick and place robot Various targets

Food grade grease can be used.

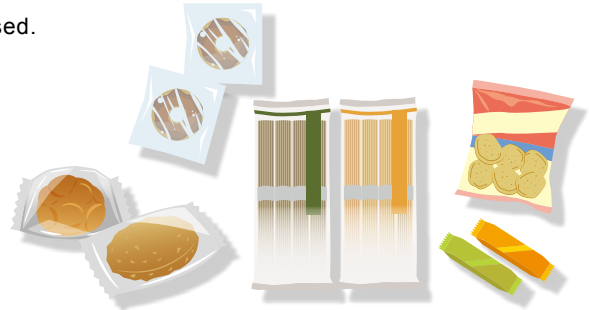
The grease used in our robots can be changed to food grade grease.

- Unless otherwise specified, the grease specified by YAMAHA is used.
- It is possible to change to grease other than our specified grease. (At this time, please supply the grease from the customer.)

For details, contact YAMAHA sales representative.

Bellows can also be added by special order!

* For use outside Japan, please contact YAMAHA.



Model/Type		Model	Arm length (mm)	Z-axis stroke (mm)	Maximum payload (kg)	Standard cycle time (sec.) Note 1
Orbit type		YK350TW	350	130	5.0	0.32
		YK500TW	500	130	5.0 (4.0) Note 3	0.29
Standard	Extra small type	YK120XG	120	50	1.0	0.33
		YK150XG	150	50	1.0	0.33
		YK180XG	180	50	1.0	0.33
		YK180X	180	100	1.0	0.39
		YK220X	220	100	1.0	0.42
	Small type	YK250XG	250	150	5.0 (4.0) Note 3	0.43
		YK350XG	350	150	5.0 (4.0) Note 3	0.44
		YK400XE-4	400	150	4.0 (3.0) Note 3	0.41
		YK400XG	400	150	5.0 (4.0) Note 3	0.45
	Medium type	YK500XGL	500	150	5.0 (4.0) Note 3	0.48
		YK500XG	500	200/300	10.0	0.42
		YK510XE-10	510	200	10.0 (9.0) Note 3	0.38
		YK600XGL	600	150	5.0 (4.0) Note 3	0.54
		YK600XG	600	200/300	10.0	0.43
		YK610XE-10	610	200	10.0 (9.0) Note 3	0.39
		YK600XGH	600	200/400	20.0 (19.0) Note 3	0.47
	Large type	YK700XGL	700	200/300	10.0 (9.0) Note 3	0.50
		YK710XE-10	710	200	10.0 (9.0) Note 3	0.42
		YK700XG	700	200/400	20.0 (19.0) Note 3	0.42
		YK800XG	800	200/400	20.0 (19.0) Note 3	0.48
		YK900XG	900	200/400	20.0 (19.0) Note 3	0.49
		YK1000XG	1000	200/400	20.0 (19.0) Note 3	0.49
		YK1200X	1200	400	50.0	0.91
Wall mount/inverse model		YK300XGS Note 2	300	150	5.0 (4.0) Note 3	0.49
		YK400XGS Note 2	400	150	5.0 (4.0) Note 3	0.49
		YK500XGS	500	200/300	10.0	0.45
		YK600XGS	600	200/300	10.0	0.46
		YK700XGS	700	200/400	20.0	0.42
		YK800XGS	800	200/400	20.0	0.48
		YK900XGS	900	200/400	20.0	0.49
		YK1000XGS	1000	200/400	20.0	0.49
Dust-proof & drip-proof model		YK250XGP	250	150	4.0	0.50
		YK350XGP	350	150	4.0	0.52
		YK400XGP	400	150	4.0	0.50
		YK500XGLP	500	150	4.0	0.66
		YK500XGP	500	200/300	10.0	0.55
		YK600XGLP	600	150	4.0	0.71
		YK600XGP	600	200/300	10.0	0.56
		YK600XGHP	600	200/400	18.0	0.57
		YK700XGP	700	200/400	20.0	0.52
		YK800XGP	800	200/400	20.0	0.58
		YK900XGP	900	200/400	20.0	0.59
		YK1000XGP	1000	200/400	20.0	0.59
Clean model		See P.103				

Note 1. The standard cycle time is measured under the following conditions.
- During back and forth movement 25mm vertically and 100mm horizontally (extra small type)
- During back and forth movement 25mm vertically and 300mm horizontally (small type / medium type / large type)

Note 2 The YK300XGS and YK400XGS are custom-order products. For details about the delivery time, please contact YAMAHA.

Note 3. For the option specifications (tool flange mount type and user wiring/tubing through spline type), the maximum payload becomes the value in ( ).

SCARA ROBOTS

YK-X SERIES

CONTENTS

YK-X SPECIFICATION SHEET

Type		Model	Arm length (mm) and XY axis resultant maximum speed (m/s)															Standard cycle time (sec) Note 1	Maximum payload (kg)	R-axis tolerable moment of inertia (kgm²)	Completely beltless structure Note 2	Detailed info page
			120	150	180	220	250	300	350	400	500	600	700	800	900	1000	1200					
Orbit type		YK350TW	5.6															0.32	5.0	0.005 (Rated) 0.05 (Maximum)		P.72
Orbit type		YK500TW	6.8															0.29	5.0	0.005 (Rated) 0.05 (Maximum)		P.74
Standard	Extra small type	YK120XG	3.3															0.33	1.0	0.01	●	P.76
Standard	Extra small type	YK150XG	3.4															0.33	1.0	0.01	●	P.77
Standard	Extra small type	YK180XG	3.3															0.33	1.0	0.01	●	P.78
Standard	Extra small type	YK180X	3.3															0.39	1.0	0.01	●	P.79
Standard	Extra small type	YK220X	3.4															0.42	1.0	0.01	●	P.80
Standard	Small type	YK250XG	4.5															0.43	5.0	0.05	●	P.81
Standard	Small type	YK350XG	5.6															0.44	5.0	0.05	●	P.83
Standard	Small type	YK400XE-4	6.0															0.41	4.0	0.05		P.86
Standard	Small type	YK400XG	6.1															0.45	5.0	0.05	●	P.88
Standard	Medium type	YK500XGL	5.1															0.48	5.0	0.05	●	P.90
Standard	Medium type	YK500XG	7.6															0.42	10.0	0.30	●	P.92
Standard	Medium type	YK510XE-10	7.8															0.38	10.0	0.30		P.93
Standard	Medium type	YK600XGL	4.9															0.54	5.0	0.05	●	P.94
Standard	Medium type	YK600XG	8.4															0.43	10.0	0.30	●	P.96
Standard	Medium type	YK610XE-10	8.6															0.39	10.0	0.30		P.97
Standard	Medium type	YK600XGH	7.7															0.47	20.0	1.0	●	P.98
Standard	Large type	YK700XGL	9.2															0.50	10.0	0.30	●	P.99
Standard	Large type	YK710XE-10	9.5															0.42	10.0	0.30		P.100
Standard	Large type	YK700XG	8.4															0.42	20.0	1.0	●	P.101
Standard	Large type	YK800XG	9.2															0.48	20.0	1.0	●	P.102
Standard	Large type	YK900XG	9.9															0.49	20.0	1.0	●	P.103
Standard	Large type	YK1000XG	10.6															0.49	20.0	1.0	●	P.104
Standard	Large type	YK1200X	7.4															0.91	50.0	2.45		P.105
Standard	Large type	YK1200XG	7.7															0.61	50.0	2.45	●	P.106
Wall mount / inverse type		YK300XGS	4.4															0.49	5.0	0.05	●	P.107
Wall mount / inverse type		YK400XGS	6.1															0.49	5.0	0.05	●	P.109
Wall mount / inverse type		YK500XGS	7.6															0.45	10.0	0.3	●	P.111
Wall mount / inverse type		YK600XGS	8.4															0.46	10.0	0.3	●	P.112
Wall mount / inverse type		YK700XGS	8.4															0.42	20.0	1.0	●	P.113
Wall mount / inverse type		YK800XGS	9.2															0.48	20.0	1.0	●	P.114
Wall mount / inverse type		YK900XGS	9.9															0.49	20.0	1.0	●	P.115
Wall mount / inverse type		YK1000XGS	10.6															0.49	20.0	1.0	●	P.116
Dust-proof & drip-proof type		YK250XGP	4.5															0.50	4.0	0.05	●	P.117
Dust-proof & drip-proof type		YK350XGP	5.6															0.52	4.0	0.05	●	P.119
Dust-proof & drip-proof type		YK400XGP	6.1															0.50	4.0	0.05	●	P.121
Dust-proof & drip-proof type		YK500XGLP	5.1															0.66	4.0	0.05	●	P.123
Dust-proof & drip-proof type		YK500XGP	7.6															0.55	10.0	0.3	●	P.125
Dust-proof & drip-proof type		YK600XGLP	4.9															0.71	4.0	0.05	●	P.126
Dust-proof & drip-proof type		YK600XGP	8.4															0.56	10.0	0.3	●	P.128
Dust-proof & drip-proof type		YK600XGHP	7.7															0.57	20.0	1.0	●	P.129
Dust-proof & drip-proof type		YK700XGP	8.4															0.52	20.0	1.0	●	P.130
Dust-proof & drip-proof type		YK800XGP	9.2															0.58	20.0	1.0	●	P.131
Dust-proof & drip-proof type		YK900XGP	9.9															0.59	20.0	1.0	●	P.132
Dust-proof & drip-proof type		YK1000XGP	10.6															0.59	20.0	1.0	●	P.133

Note 1. The standard cycle time is measured under the following conditions.
- During back and forth movement 25mm vertically and 100mm horizontally (extra small type)
- During back and forth movement 25mm vertically and 300mm horizontally (small type / medium type / large type)

Note 2. Maintains high accuracy over long periods because the beltless structure drastically cuts down on wasted motion.
Operation is also nearly maintenance-free for long periods with no worries about belt breakage, stretching or deterioration over time.

Robot ordering method description

In the order format for the YAMAHA SCARA robots YK-X series, the notation (letters/numbers) for the mechanical section is shown linked to the controller section notation.

[Example]

● **Mechanical ▶ YK250XG**
- Z-axis stroke ▷ 150mm
- Tool flange ▷ With tool flange
- Hollow shaft ▷ With hollow shaft
- Cable length ▷ 3.5m

● **Controller ▶ RCX340**

● **Ordering method**

YK250XG-150-F-S-3L-RCX340

Mechanical section | Controller section

To find detailed controller information see the controller page. **RCX340** ▶ P.636

① Model	②Z-axis stroke		③ Tool flange		④ Hollow shaft		⑤ Cable		⑥Controller
YK***	50	50mm	No entry	None	No entry	None	2L	2m	RCX340
	100	100mm	F	With tool flange	S	With hollow shaft	3L	3.5m	
	150	150mm					5L	5m	
	200	200mm					10L	10m	
	300	300mm							
	400	400mm							

Note 1. Available only for the master.

Robot ordering method terminology

Note. The selection items available for ordering method may vary depending on the model.Note. The selection items available for ordering method may vary depending on the model.

① Model	Enter the robot unit model.
② Return-to-origin method (YK400XE-4 only)	Select the return-to-origin method. **S**: Sensor **T**: Stroke end
③ Z-axis stroke	Select the Z axis stroke. The stroke varies with the model you select so see that model's page to confirm the specifications.
④ Tool flange	Tool flange option for easy mounting of a tool to the tip. **No entry**: None **F**: With tool flange
⑤ Hollow shaft	Hollow shaft option for easy routing of air tubes and harness wires. **No entry**: None **S: With hollow shaft** **C: With hollow cap**
⑥ Brake release switch	Select whether a brake release switch is present. **No entry**: None **BS**: With tool flange
⑦ Cable	Select the length of the robot cable connecting the robot and controller. **2L**: 2m (Note 1) **3L**: 3.5m **5L**: 5m **10L**: 10m Note 1. Only selectable for YK120XG, YK150XG, YK180XG.
⑧ Controller	Select the RCX340.

YK350TW

Orbit type

Arm length 350mm **Maximum payload 5kg**

Ordering method

YK350TW - 130 - [ ] - [ ] - [ ] - RCX340-4 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK350TW	130: 130mm	No entry: None F: With tool flange	No entry: None S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		175 mm	175 mm	130 mm	-
	Rotation angle		+/-225 °	+/-225 °	-	+/-720 °
AC servo motor output			750 W	400 W	200 W	105 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Timing belt	Direct-coupled	Timing belt	Timing belt
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.01 °
Maximum speed			5.6 m/sec		1.5 m/sec	3000 °/sec
Maximum payload Note 2			5 kg			
Standard cycle time: with 1kg payload Note 3			0.32 sec			
R-axis tolerable moment of inertia Note 4		Rated	0.005 kgm²			
		Maximum	0.05 kgm²			
User wiring			0.15 sq × 8 wires			
User tubing (Outer diameter)			ϕ 6 × 2			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			26 kg			

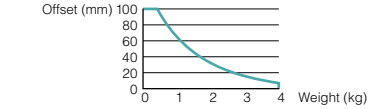
Note 1. This is the value at a constant ambient temperature.
Note 2. Tool flange specifications (option) are 4 kg.
Note 3. When moving a 1 kg load back and forth 300mm horizontally and 25mm vertically (rough positioning arch motion).
Note 4. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

R-axis moment of inertia (load inertia)

Recommended positional relationship between the load weight and the offset amount from the center of the R-axis (center of gravity position)

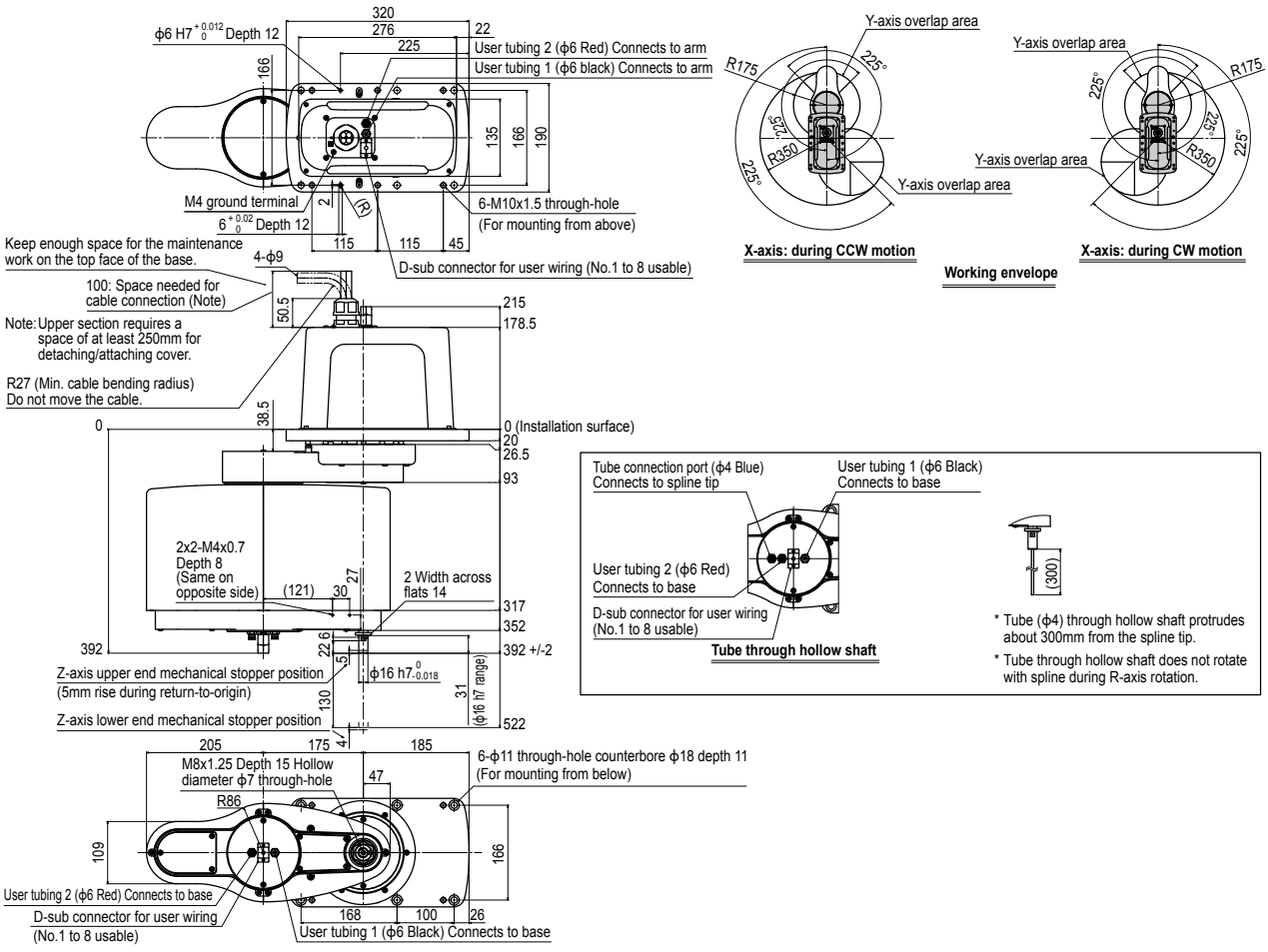


Note. When the payload exceeds 4kg, it is predicted that the R-axis moment of inertia may exceed the rated value. So, make proper parameter setting.

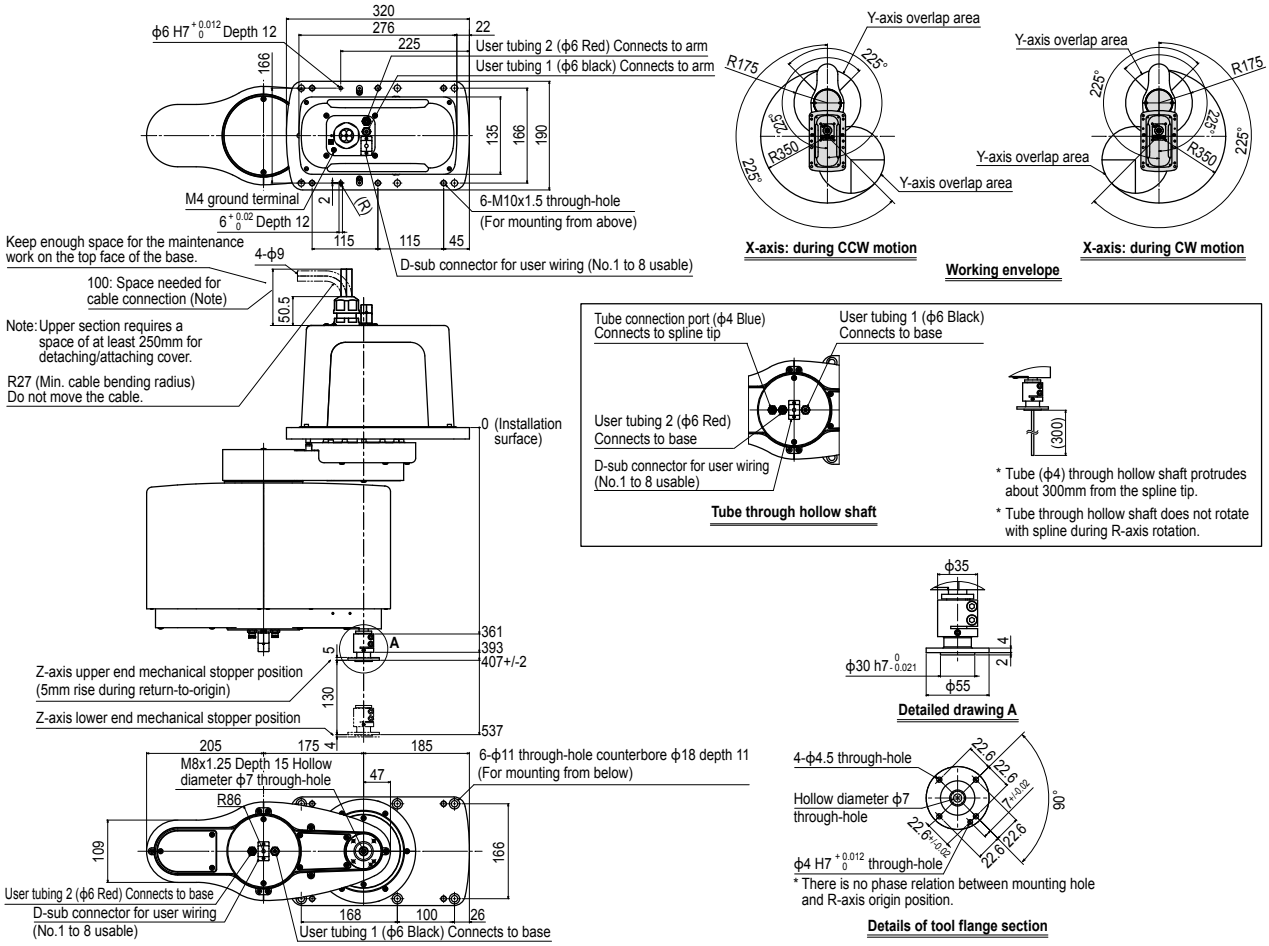
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

YK350TW



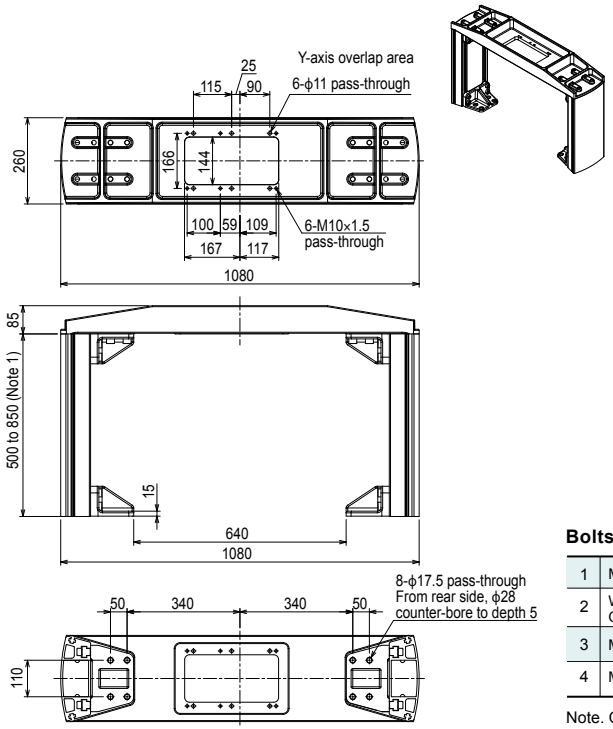
YK350TW Tool flange mount type



Dedicated mounting bracket for the YK-TW <BASE POST ASSY.>

The YK-TW can be easily installed on top of a customer-provided stand.

External diagram for the YK350TW



The mounting bracket is assembled by the customer.
Refer to the included assembly diagram for assembly.

Note 1. Identical to the height of the robot mounting surface.
The height of the stand can be selected at a 50 mm pitch.

Height (mm)	Model	Unit weight (kg)
500	KDU-M6100-P0	46
550	KDU-M6100-50	48
600	KDU-M6100-R0	50
650	KDU-M6100-60	51
700	KDU-M6100-S0	54
750	KDU-M6100-70	55
800	KDU-M6100-T0	57
850	KDU-M6100-80	59

Note. YK350TW and YK500TW are parts in common.
Note. The top plate by itself weighs 19 kg.

Bolts supplied with the controller

1	M16 x Pitch 2.0 x Length 45 [Hexagonal socket head bolt]	8 pcs. (For securing the installation base)
2	Washer for M16 bolt [Plate thickness 3 mm, Outside diameter ϕ26, Inside diameter ϕ16]	8 pcs.
3	M10 × Pitch 1.5 × Length 30	6 pcs. (Bolts used to secure the SCARA main body from the bottom surface.)
4	M10 × Pitch 1.5 × Length 40	6 pcs. (Bolts used to secure the SCARA main body from the top surface.)

Note. Only either 3 or 4 is used.

YK500TW

Orbit type

- Arm length 500mm
- Maximum payload 5kg

Ordering method

YK500TW - 130 - [ ] - [ ] - [ ] - RCX340-4 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK500TW	130: 130mm	No entry: None F: With tool flange	No entry: None S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		250 mm	250 mm	130 mm	-
	Rotation angle		+/-225 °	+/-225 °	-	+/-720 °
AC servo motor output			750 W	400 W	200 W	105 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Timing belt	Direct-coupled	Timing belt	Timing belt
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.015 mm		+/-0.01 mm	+/-0.01 °
Maximum speed			6.8 m/sec		1.5 m/sec	3000 °/sec
Maximum payload Note 2			5 kg			
Standard cycle time: with 1kg payload Note 3			0.29 sec			
R-axis tolerable moment of inertia Note 4		Rated	0.005 kgm^2			
		Maximum	0.05 kgm^2			
User wiring			0.15 sq × 8 wires			
User tubing (Outer diameter)			ϕ 6 × 2			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			27 kg			

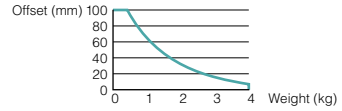
Note 1. This is the value at a constant ambient temperature.
Note 2. For the option specifications (tool flange mount type), the maximum payload becomes 4 kg.
Note 3. When moving a 1 kg load back and forth 300 mm horizontally and 25 mm vertically (rough positioning arch motion).
Note 4. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

R-axis moment of inertia (load inertia)

Recommended positional relationship between the load weight and the offset amount from the center of the R-axis (center of gravity position)



Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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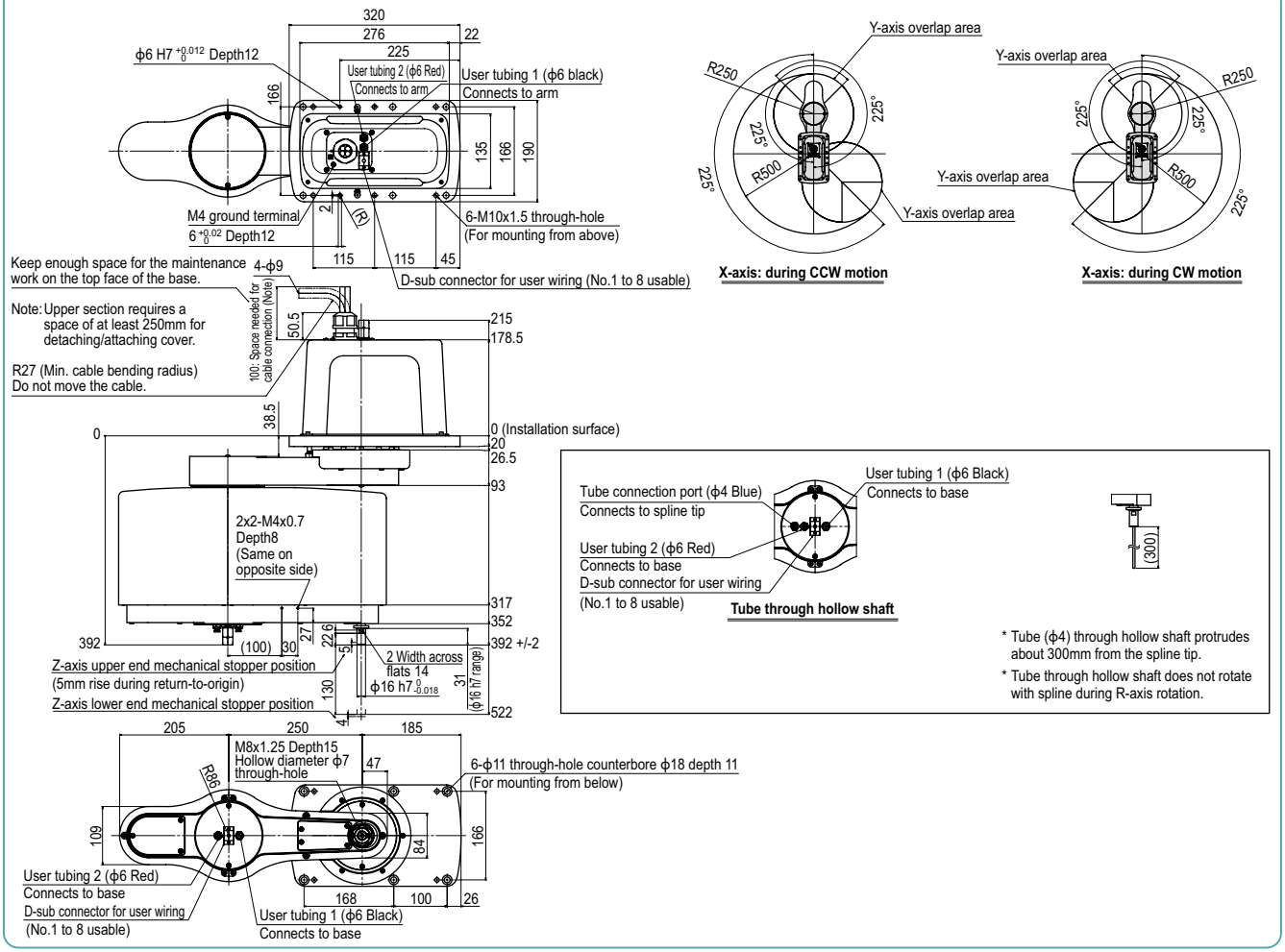
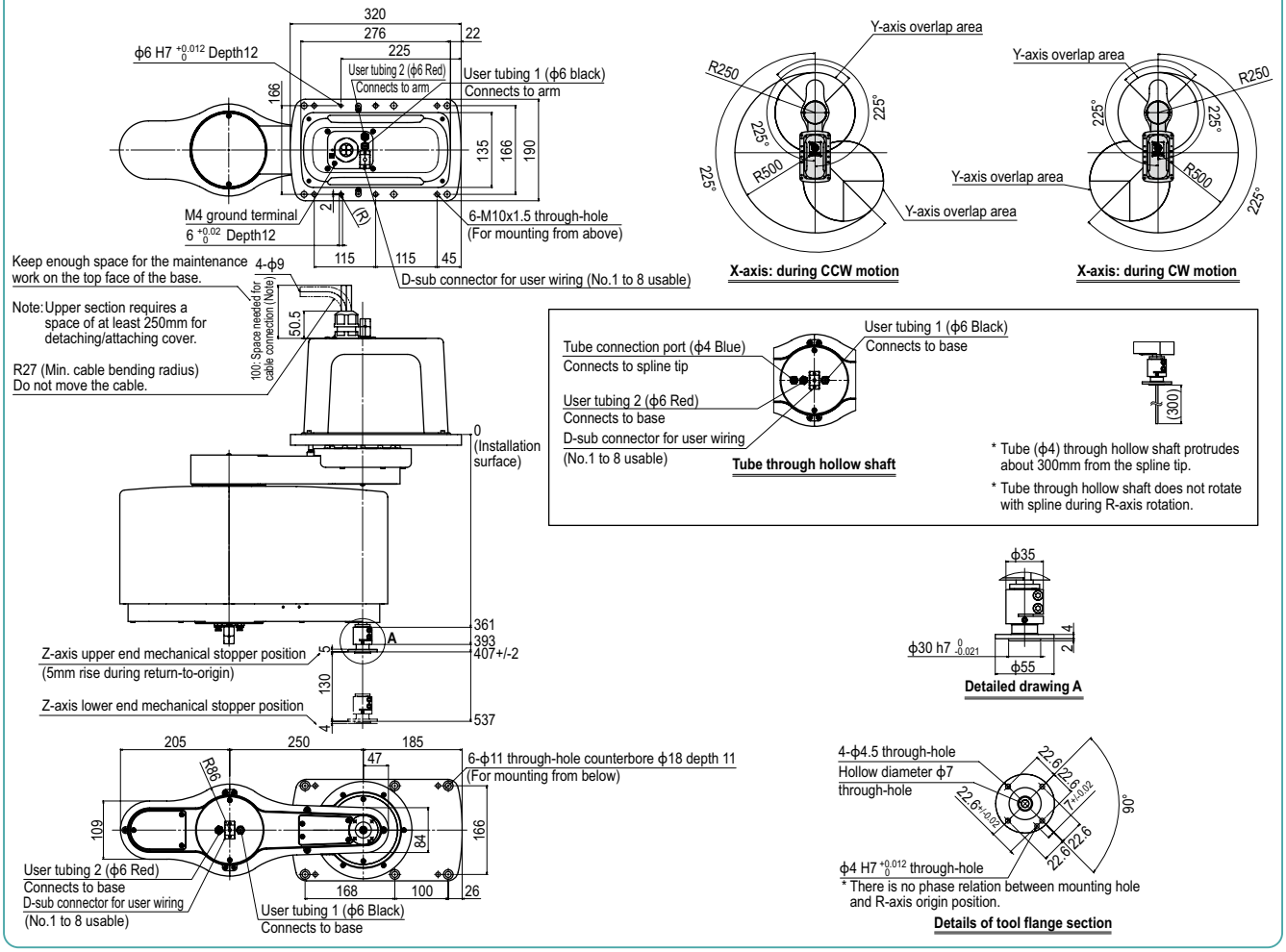
YK500TW



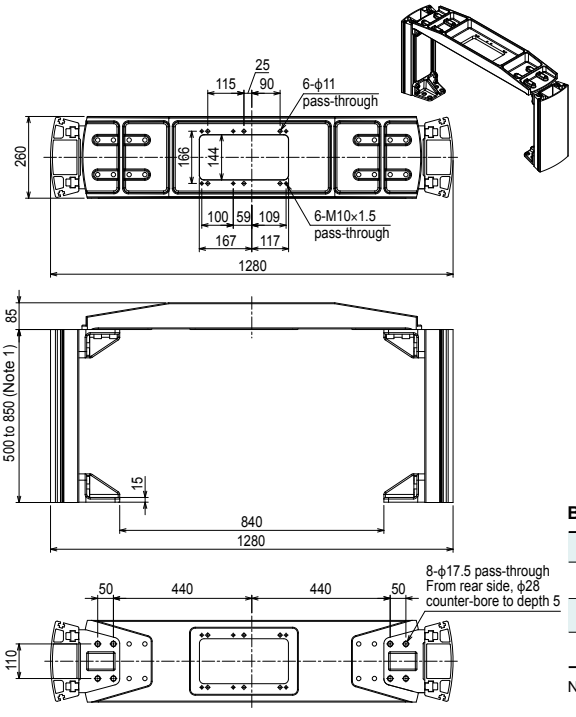
YK500TW Tool flange mount type



Dedicated mounting bracket for the YK-TW <BASE POST ASSY.>

The YK-TW can be easily installed on top of a customer-provided stand.

External diagram for the YK500TW



The mounting bracket is assembled by the customer.
Refer to the included assembly diagram for assembly.

Note 1. Identical to the height of the robot mounting surface.
The height of the stand can be selected at a 50 mm pitch.

Height (mm)	Model	Unit weight (kg)
500	KDU-M6100-P0	46
550	KDU-M6100-50	48
600	KDU-M6100-R0	50
650	KDU-M6100-60	51
700	KDU-M6100-S0	54
750	KDU-M6100-70	55
800	KDU-M6100-T0	57
850	KDU-M6100-80	59

Note. YK350TW and YK500TW are parts in common.
Note. The top plate by itself weighs 19 kg.

Bolts supplied with the controller

1	M16 x Pitch 2.0 x Length 45 [Hexagonal socket head bolt]	8 pcs. (For securing the installation base)
2	Washer for M16 bolt [Plate thickness 3 mm, Outside diameter ϕ26, Inside diameter ϕ16]	8 pcs.
3	M10 × Pitch 1.5 × Length 30	6 pcs. (Bolts used to secure the SCARA main body from the bottom surface.)
4	M10 × Pitch 1.5 × Length 40	6 pcs. (Bolts used to secure the SCARA main body from the top surface.)

Note. Only either 3 or 4 is used.

YK120XG

Standard type: Extra small type

- Arm length 120mm
- Maximum payload 1kg

Ordering method

YK120XG - 50 - [ ] - RCX340-4 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Z axis stroke	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK120XG	50: 50mm	2L: 2m 3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		45 mm	75 mm	50 mm	–
	Rotation angle		+/-125 °	+/-145 °	–	+/-360 °
AC servo motor output			30 W	30 W	30 W	30 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			3.3 m/sec		0.9 m/sec	1700 °/sec
Maximum payload			1.0 kg			
Standard cycle time: with 0.1kg payload Note 2			0.33 sec			
R-axis tolerable moment of inertia Note 3			0.01 kgm^2			
User wiring			0.1 sq × 8 wires			
User tubing (Outer diameter)			ϕ 4 × 2			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 2 m Option: 3.5 m, 5 m, 10 m			
Weight (Excluding robot cable) Note 4			3.9 kg			
Robot cable weight			0.9 kg (2 m) 1.5 kg (3.5 m) 2.1 kg (5 m) 4.2 kg (10 m)			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When moving 25mm in vertical direction and 100mm in horizontal direction reciprocally.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. The total robot weight is the sum of the robot body weight and the cable weight.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	300	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

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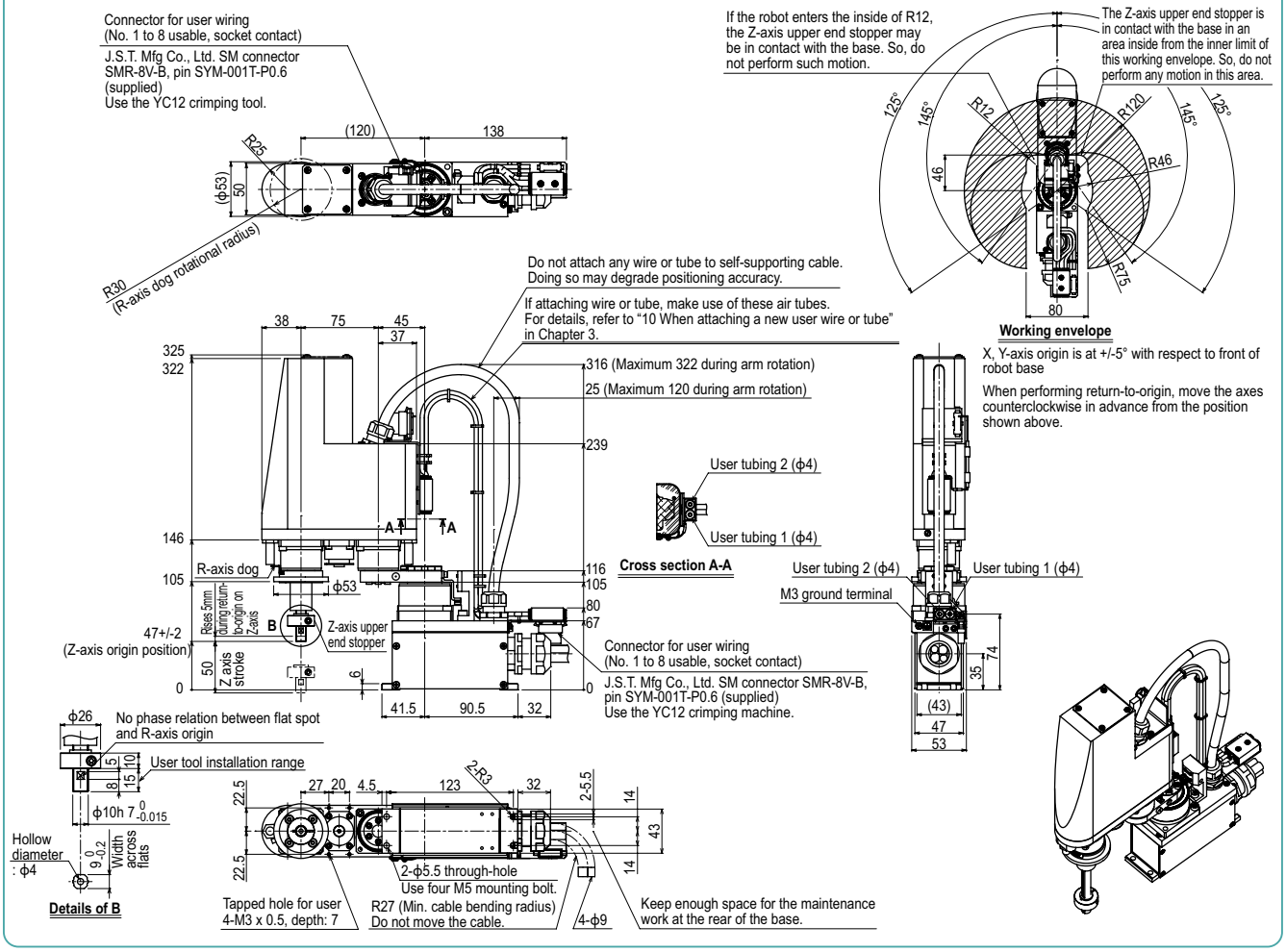
YK120XG



YK150XG

Standard type: Extra small type

- Arm length 150mm
- Maximum payload 1kg

Ordering method

YK150XG - 50 - [ ] - RCX340-4 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Z axis stroke	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK150XG	50: 50mm	2L: 2m 3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		75 mm	75 mm	50 mm	–
	Rotation angle		+/-125 °	+/-145 °	–	+/-360 °
AC servo motor output			30 W	30 W	30 W	30 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			3.4 m/sec		0.9 m/sec	1700 °/sec
Maximum payload			1.0 kg			
Standard cycle time: with 0.1kg payload Note 2			0.33 sec			
R-axis tolerable moment of inertia Note 3			0.01 kgm^2			
User wiring			0.1 sq × 8 wires			
User tubing (Outer diameter)			ϕ 4 × 2			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 2 m Option: 3.5 m, 5 m, 10 m			
Weight (Excluding robot cable) Note 4			4.0 kg			
Robot cable weight			0.9 kg (2 m) 1.5 kg (3.5 m) 2.1 kg (5 m) 4.2 kg (10 m)			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When moving 25mm in vertical direction and 100mm in horizontal direction reciprocally.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. The total robot weight is the sum of the robot body weight and the cable weight.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	300	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

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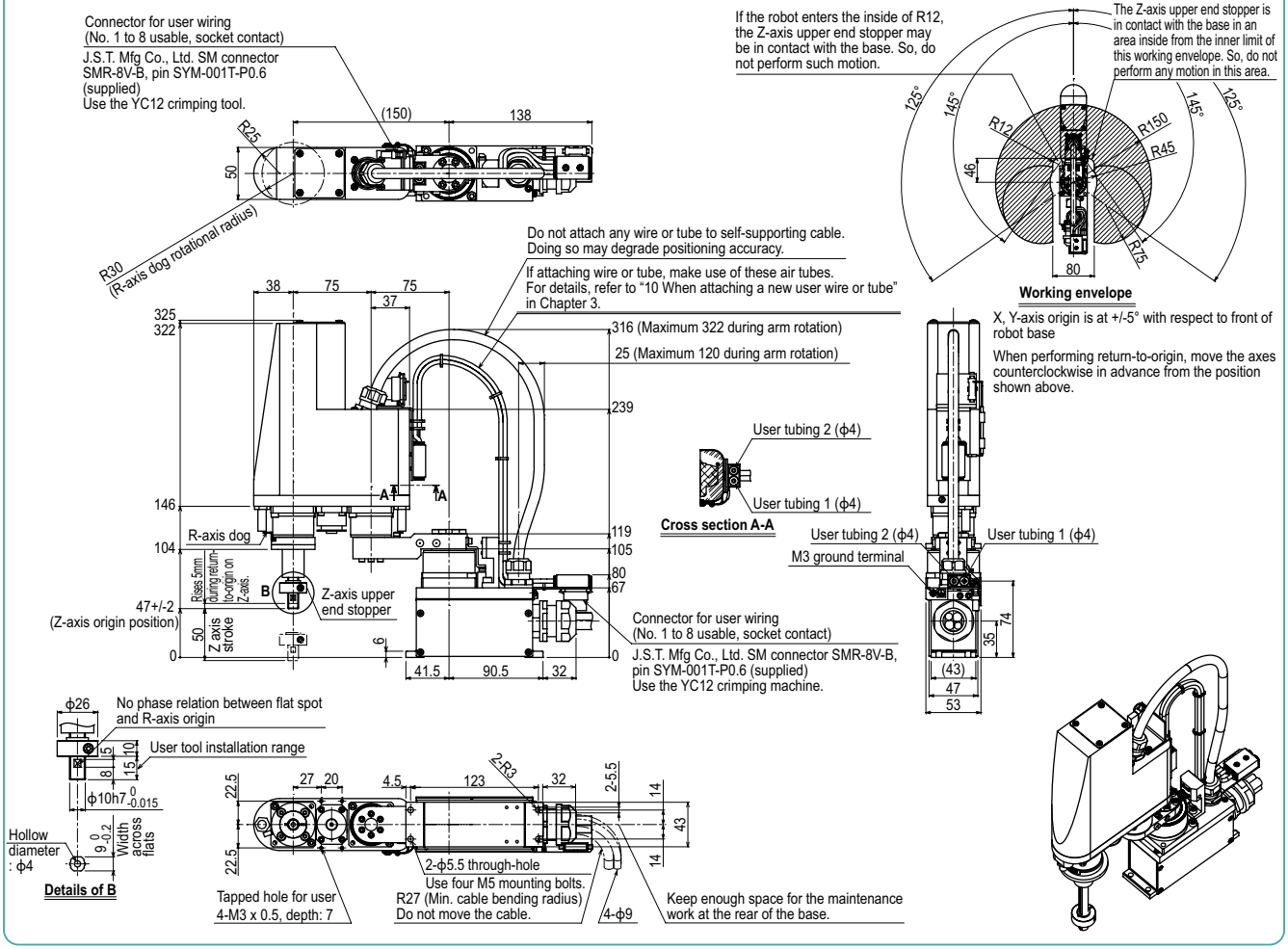
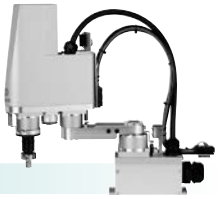
YK150XG



Controller RCX340 ▶ 636

YK180XG

Standard type: Extra small type



- Arm length 180mm
- Maximum payload 1kg

Ordering method

YK180XG - 50			RCX340-4							
Model	Z axis stroke	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	50 : 50mm	2L: 2m 3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		105 mm	75 mm	50 mm	–
	Rotation angle		+/-125 °	+/-145 °	–	+/-360 °
AC servo motor output			30 W	30 W	30 W	30 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			3.3 m/sec		0.9 m/sec	1700 °/sec
Maximum payload			1.0 kg			
Standard cycle time: with 0.1kg payload Note 2			0.33 sec			
R-axis tolerable moment of inertia Note 3			0.01 kgm^2			
User wiring			0.1 sq × 8 wires			
User tubing (Outer diameter)			ϕ 4 × 2			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 2 m Option: 3.5 m, 5 m, 10 m			
Weight (Excluding robot cable) Note 4			4.1 kg			
Robot cable weight			0.9 kg (2 m) 1.5 kg (3.5 m) 2.1 kg (5 m) 4.2 kg (10 m)			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When moving 25mm in vertical direction and 100mm in horizontal direction reciprocally.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. The total robot weight is the sum of the robot body weight and the cable weight.

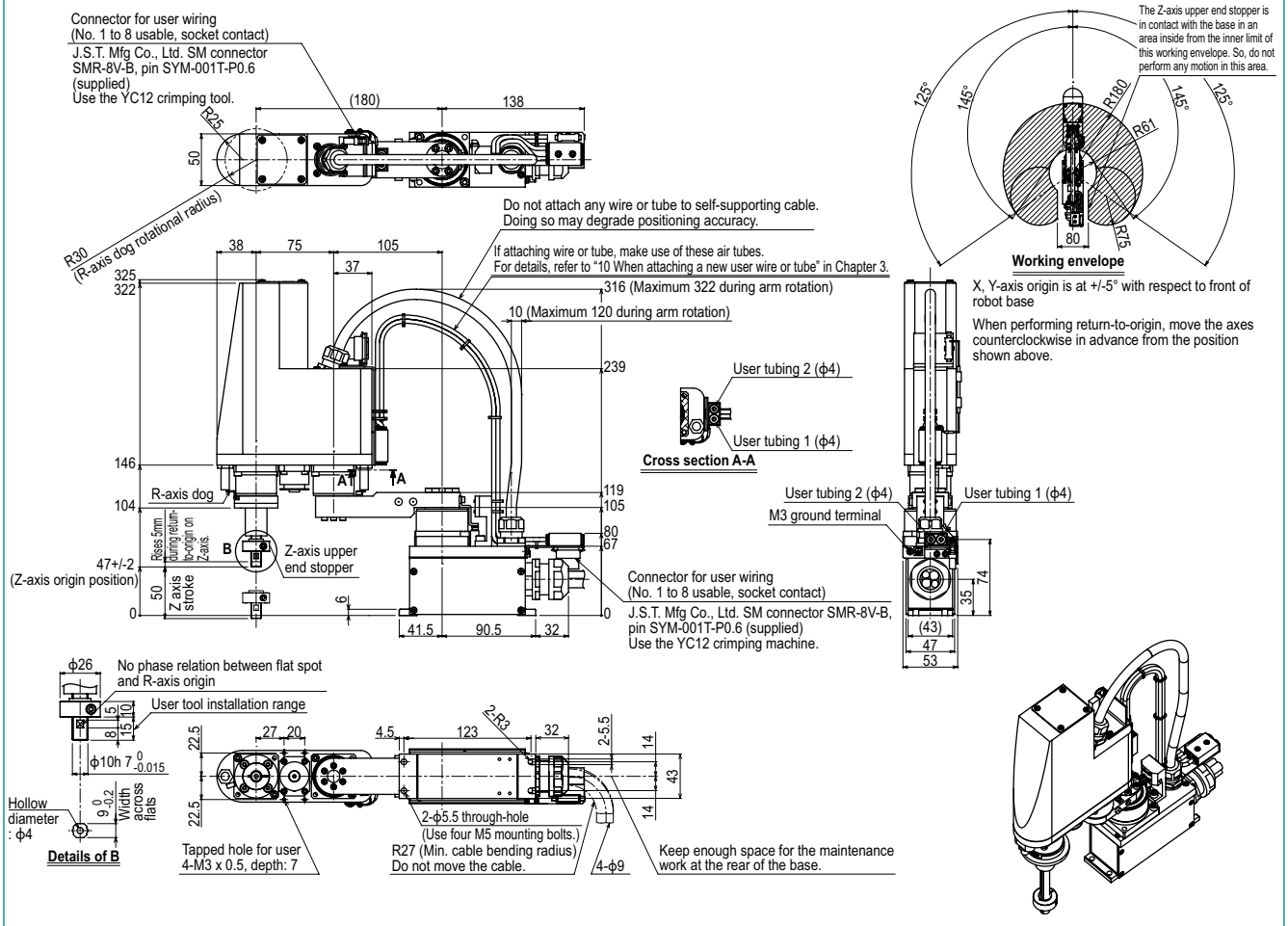
Controller

Controller	Power capacity (VA)	Operation method
RCX340	500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

YK180XG



YK180X

Standard type: Extra small type

- Arm length 180mm
- Maximum payload 1kg

Ordering method

YK180X - 100 - [ ] - RCX340-4 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Z axis stroke	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK180X	100: 100mm	3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		71 mm	109 mm	100 mm	–
	Rotation angle		+/-120 °	+/-140 °	–	+/-360 °
AC servo motor output			50 W	30 W	30 W	30 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			3.3 m/sec		0.7 m/sec	1700 °/sec
Maximum payload			1.0 kg			
Standard cycle time: with 0.1kg payload Note 2			0.39 sec			
R-axis tolerable moment of inertia Note 3			0.01 kgm^2			
User wiring			0.1 sq × 6 wires			
User tubing (Outer diameter)			ϕ 3 × 2			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight (Excluding robot cable) Note 4			5.5 kg			
Robot cable weight			1.5 kg (3.5 m) 2.1 kg (5 m) 4.2 kg (10 m)			

Note 1. This is the value at a constant ambient temperature.
Note 2. When reciprocating 100mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. The total robot weight is the sum of the robot body weight and the cable weight.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

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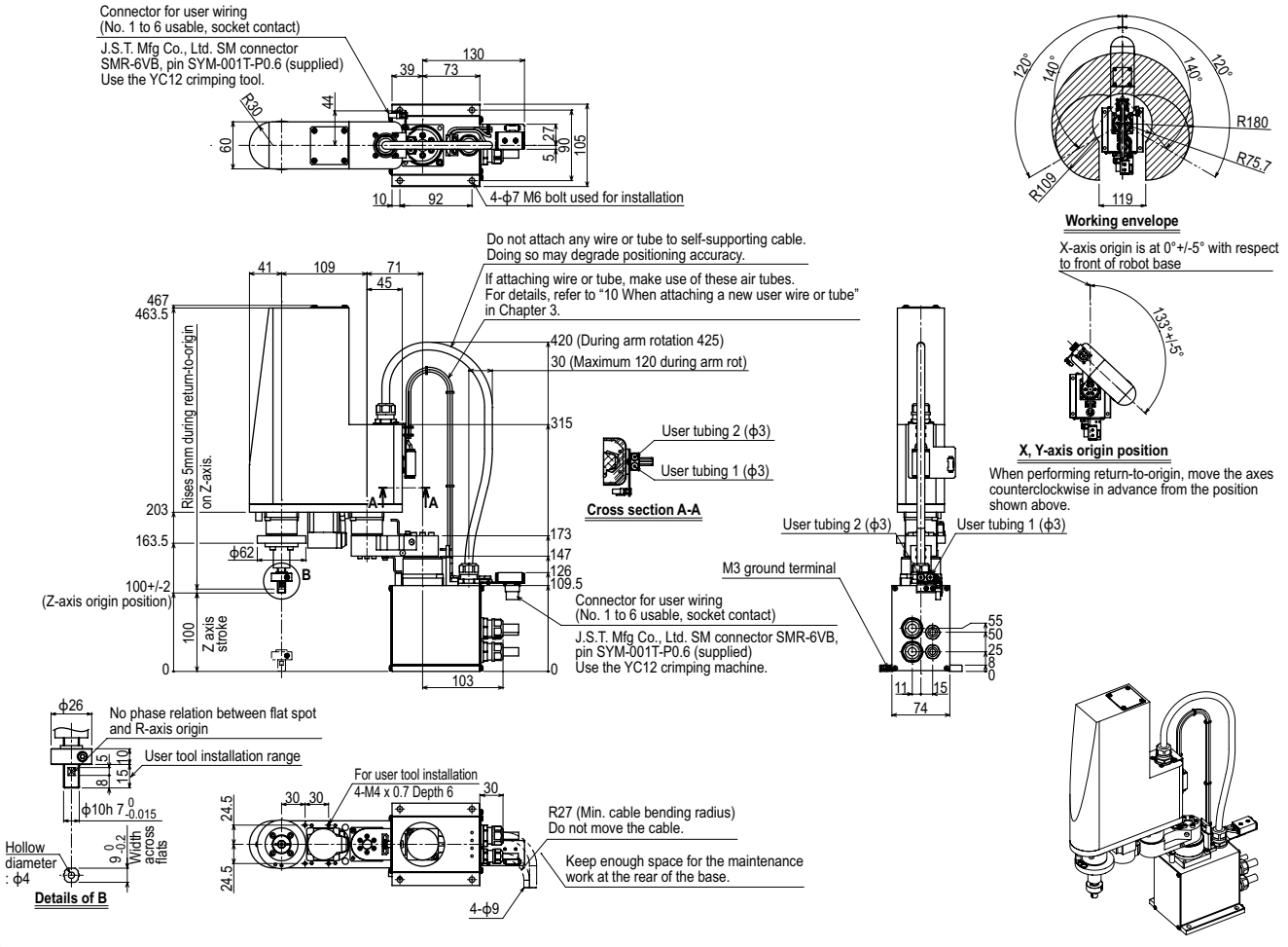
YK180X



Controller RCX340 ▶ 636

YK220X

Standard type: Extra small type

- Arm length 220mm
- Maximum payload 1kg

Ordering method

YK220X	- 100	-	- RCX340-4	-	-	-	-	-	-	-
Model	Z axis stroke 100: 100mm	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		111 mm	109 mm	100 mm	–
	Rotation angle		+/-120 °	+/-140 °	–	+/-360 °
AC servo motor output			50 W	30 W	30 W	30 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			3.4 m/sec		0.7 m/sec	1700 °/sec
Maximum payload			1.0 kg			
Standard cycle time: with 0.1kg payload Note 2			0.42 sec			
R-axis tolerable moment of inertia Note 3			0.01 kgm^2			
User wiring			0.1 sq × 6 wires			
User tubing (Outer diameter)			ϕ 3 × 2			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight (Excluding robot cable) Note 4			5.5 kg			
Robot cable weight			1.5 kg (3.5 m) 2.1 kg (5 m) 4.2 kg (10 m)			

Note 1. This is the value at a constant ambient temperature.
Note 2. When reciprocating 100mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. The total robot weight is the sum of the robot body weight and the cable weight.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

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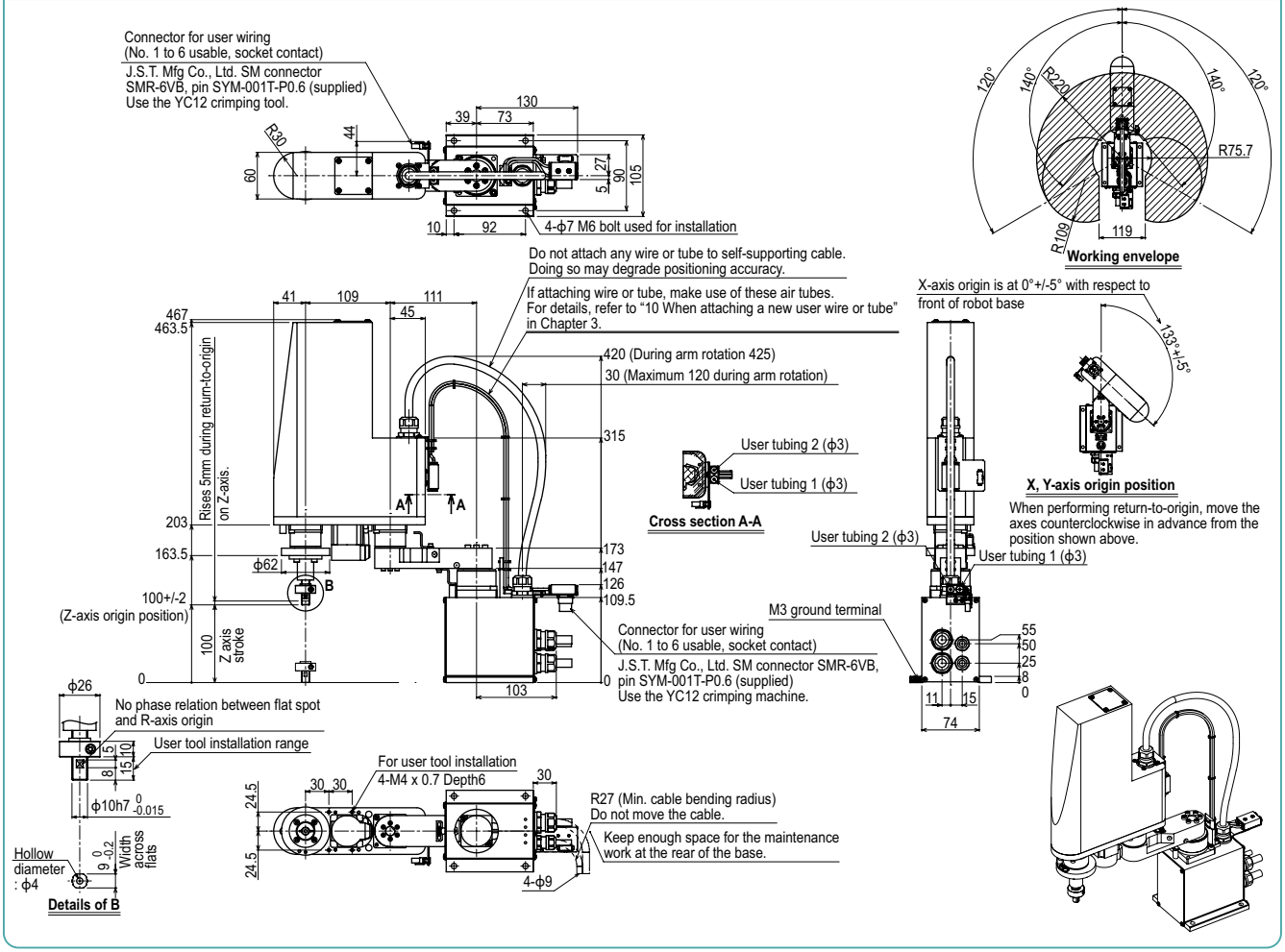
YK220X



YK250XG

Standard type: Small type

- Arm length 250mm
- Maximum payload 5kg

Ordering method

YK250XG - 150 - [ ] - [ ] - [ ] - RCX340-4 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	150: 150mm	No entry: None F: With tool flange	No entry: None S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		100 mm	150 mm	150 mm	-
	Rotation angle		+/-140 °	+/-144 °	-	+/-360 °
AC servo motor output			200 W	150 W	50 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			4.5 m/sec		1.1 m/sec	1020 °/sec
Maximum payload			5 kg (Standard specification), 4 kg (Option specifications Note 4)			
Standard cycle time: with 2kg payload Note 2			0.43 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm^2 (0.5 kgfcms^2)			
User wiring			0.2 sq × 10 wires			
User tubing (Outer diameter)			ϕ 4 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			18.5 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Maximum payload of option specifications (with tool flange attached or with user wiring and tubing routed through spline shaft) is 4kg.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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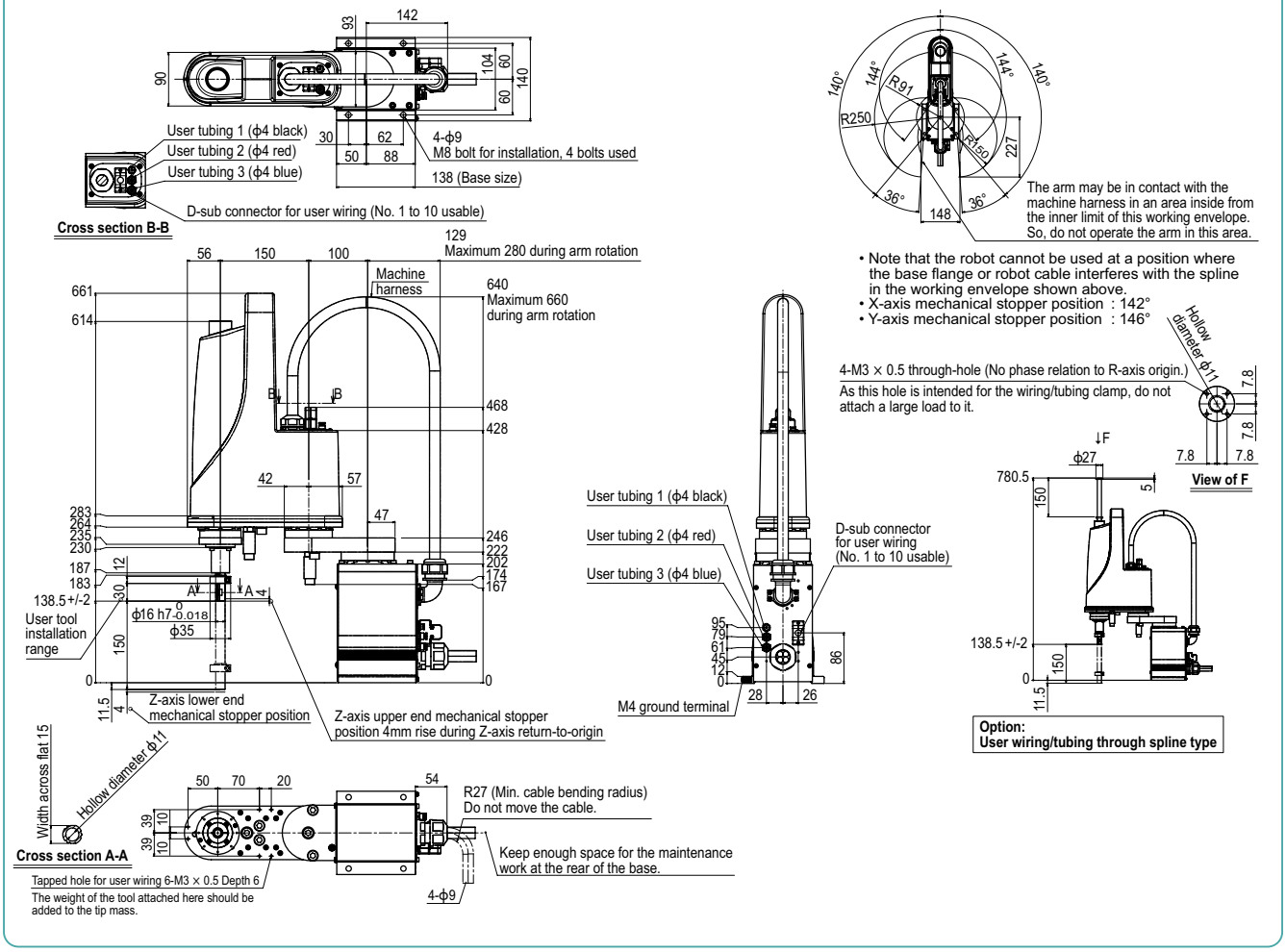
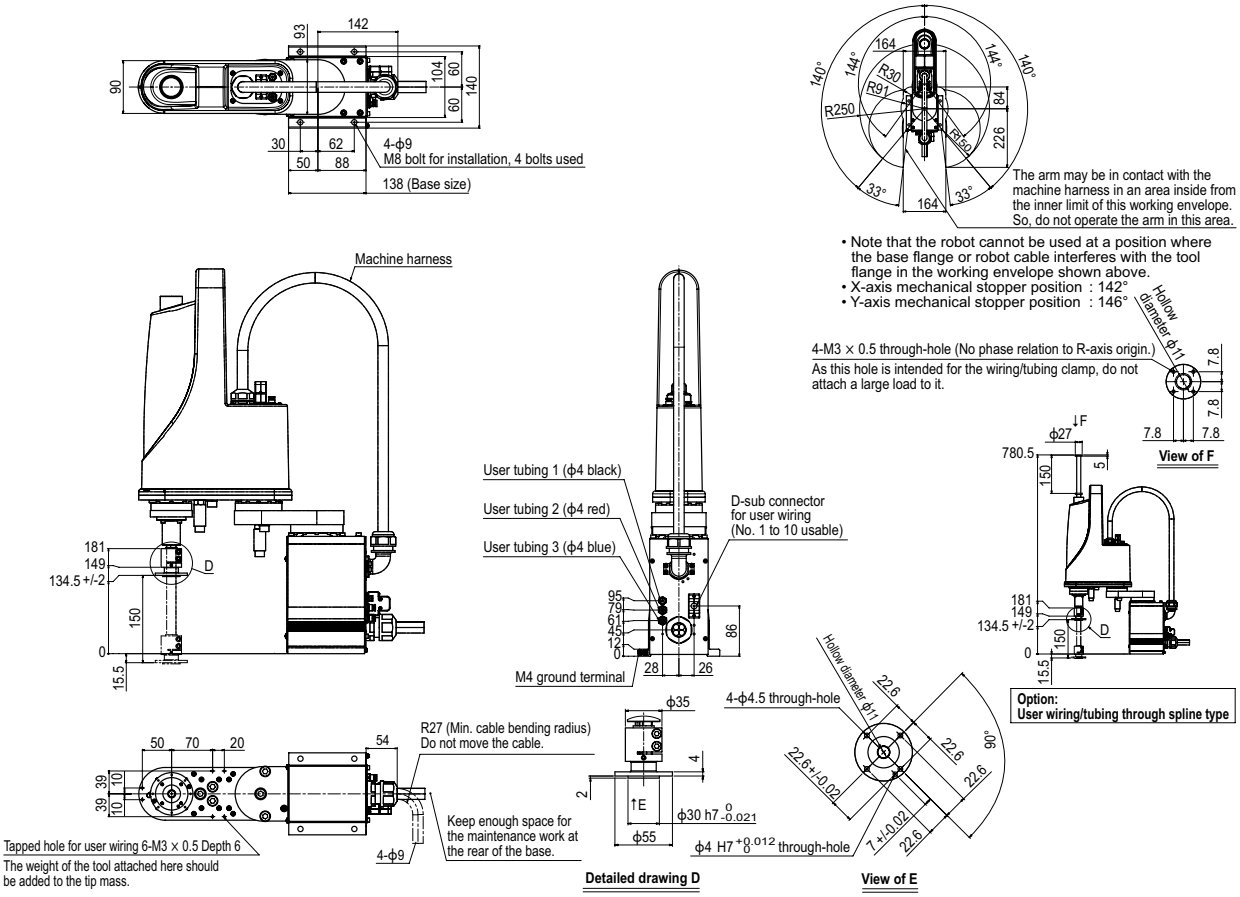
YK250XG



Controller RCX340 ▶ 636

YK250XG

YK250XG Tool flange mount type



YK350XG

Standard type: Small type

- Arm length 350mm
- Maximum payload 5kg

Ordering method

YK350XG - 150 - [ ] - [ ] - [ ] - RCX340-4 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK350XG	150: 150mm	No entry: None F: With tool flange	No entry: None S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		200 mm	150 mm	150 mm	-
	Rotation angle		+/-140 °	+/-144 °	-	+/-360 °
AC servo motor output			200 W	150 W	50 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			5.6 m/sec		1.1 m/sec	1020 °/sec
Maximum payload			5 kg (Standard specification), 4 kg (Option specifications Note 4)			
Standard cycle time: with 2kg payload Note 2			0.44 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm² (0.5 kgfcms²)			
User wiring			0.2 sq × 10 wires			
User tubing (Outer diameter)			ϕ 4 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			19 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Maximum payload of option specifications (with tool flange attached or with user wiring and tubing routed through spline shaft) is 4kg.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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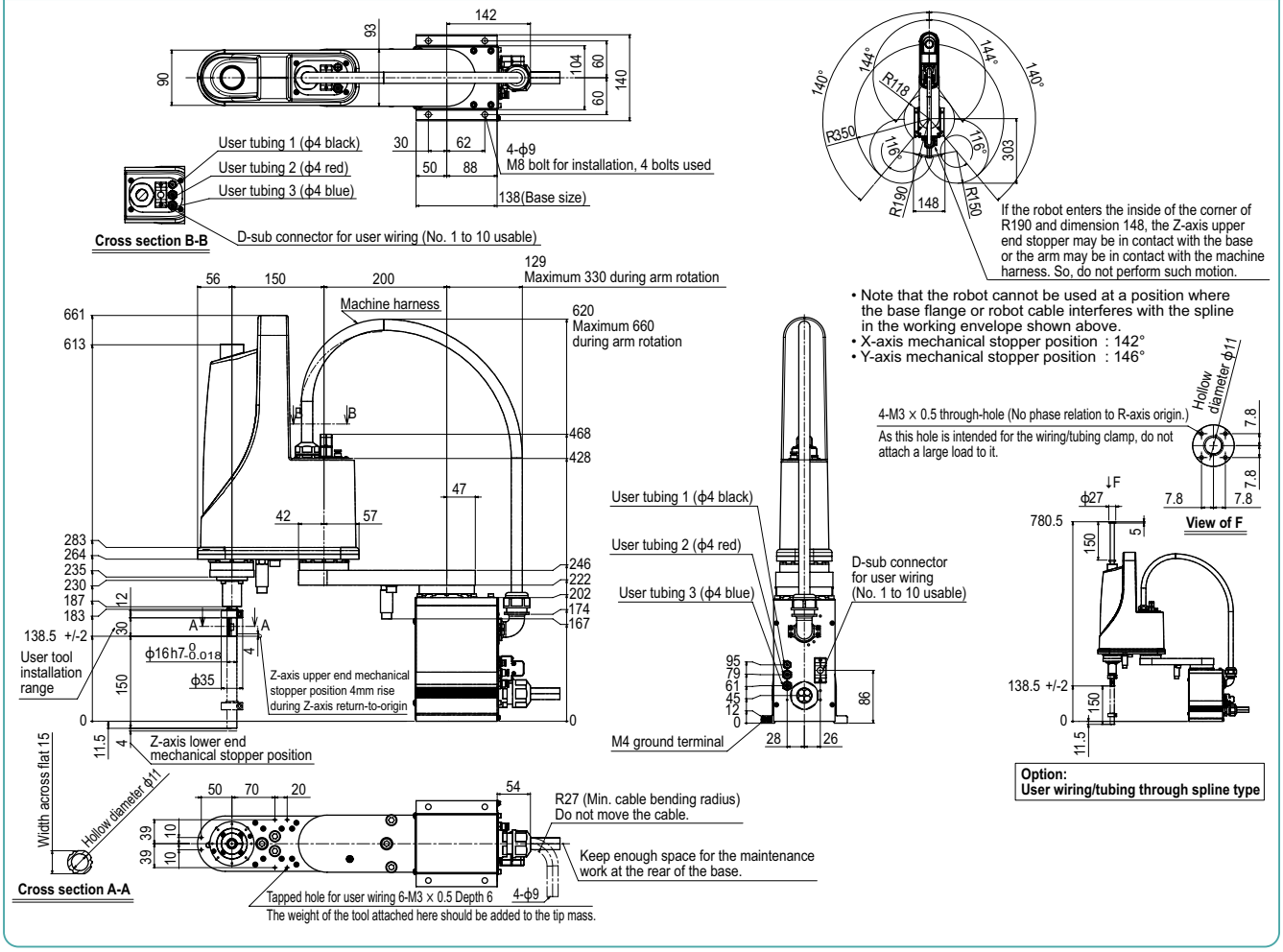
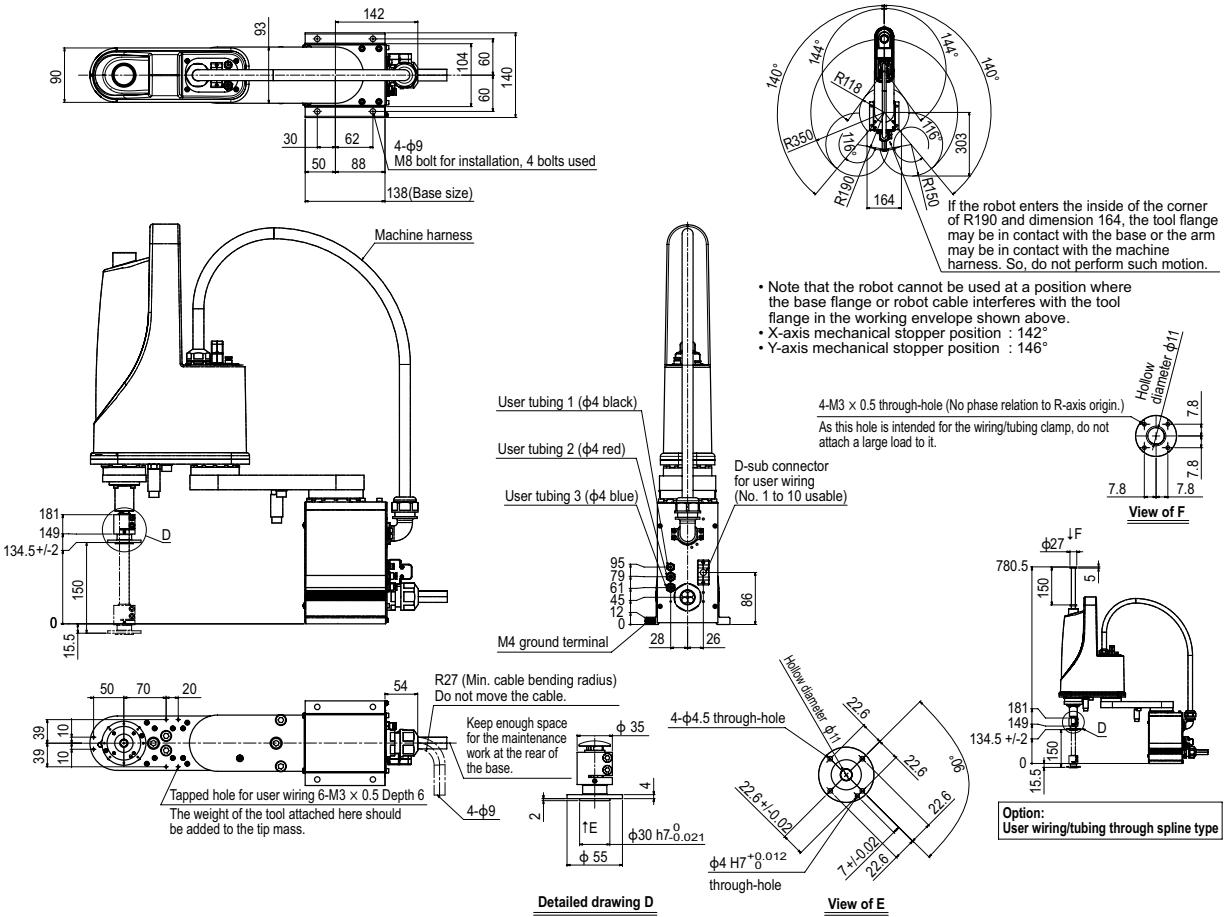
YK350XG



Controller RCX340 ▶ 636

YK350XG Tool flange mount type



MEMO

YK400XE-4

Standard type: Small type

LOW COST HIGH PERFORMANCE MODEL

Arm length 400mm **Maximum payload 4kg**

Ordering method

YK400XE	- 4	-	- 150	-	-	-	RCX340-4	-	-	-
Model	Maximum payload	Return-to-origin method S: Sensor T: Stroke end	Z axis stroke	Hollow shaft No entry: None S: With hollow shaft	Brake release switch No entry: None BS: With brake release switch	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A to E (OP.A to E)	Absolute battery

Specify various controller setting items.

RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		225 mm	175 mm	150 mm	-
	Rotation angle		+/-132 °	+/-150 °	-	+/-360 °
AC servo motor output			200 W	100 W	100 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled		Timing belt	
		Speed reducer to output	Direct-coupled			Timing belt
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.01 °
Maximum speed			6 m/sec		1.1 m/sec	2600 °/sec
Maximum payload			4 kg (Standard specification, Option specifications Note 4), 3 kg (Option specifications Note 5)			
Standard cycle time: with 2kg payload Note 2			0.41 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm²			
User wiring			0.2 sq × 10 wires			
User tubing (Outer diameter)			ϕ 4 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			17 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions and performing the coarse positioning arch operation.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and offset amount for R-axis moment of inertia settings.
Note 4. Maximum payload of the standard or option specifications (brake release switch type) is 4 kg.
Note 5. Maximum payload of the option specifications (user wiring/tubing through shaft type) is 3 kg.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be restricted by adding the X- and Y-axis mechanical stoppers. (The maximum movement range was set at shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
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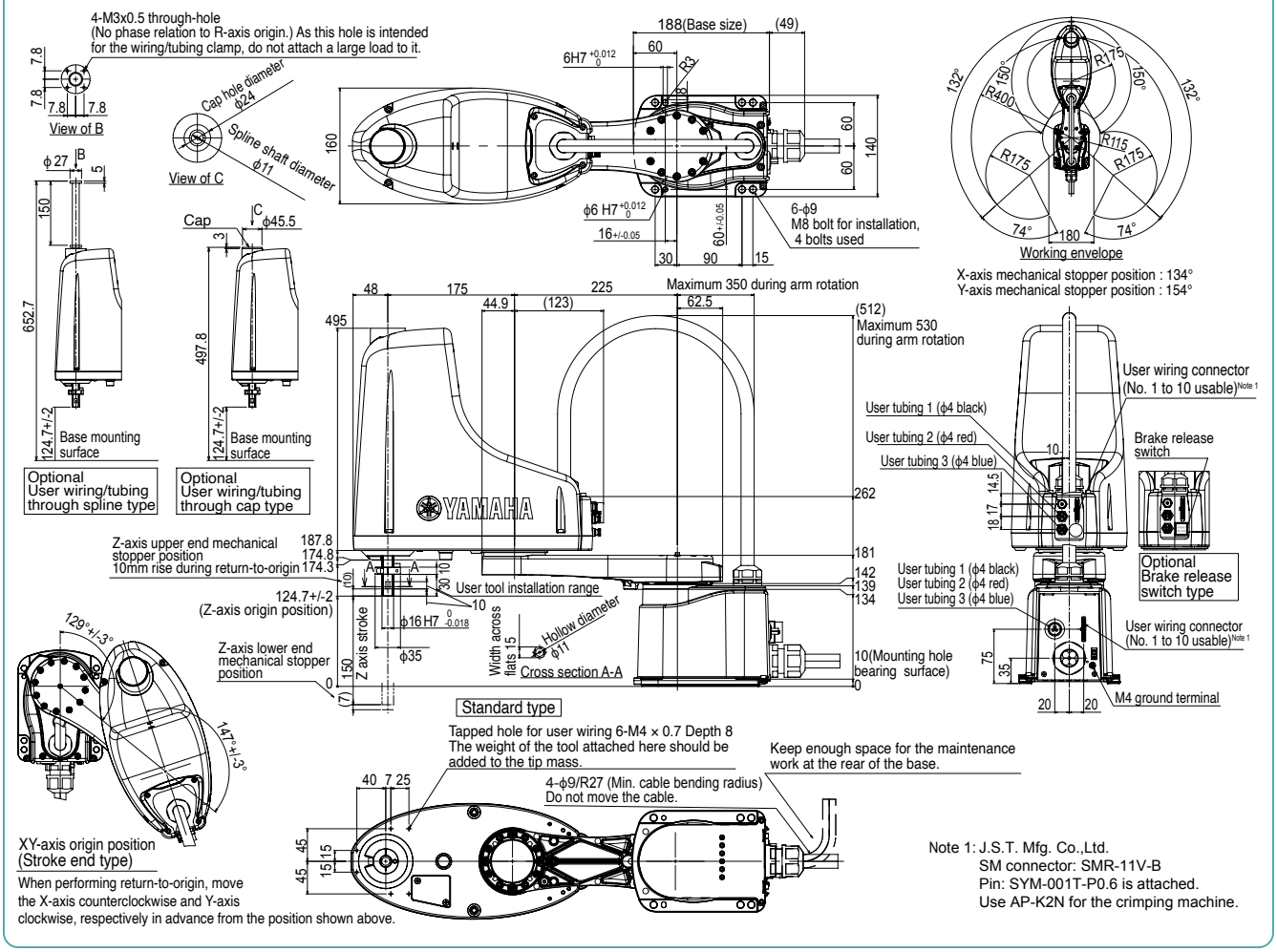
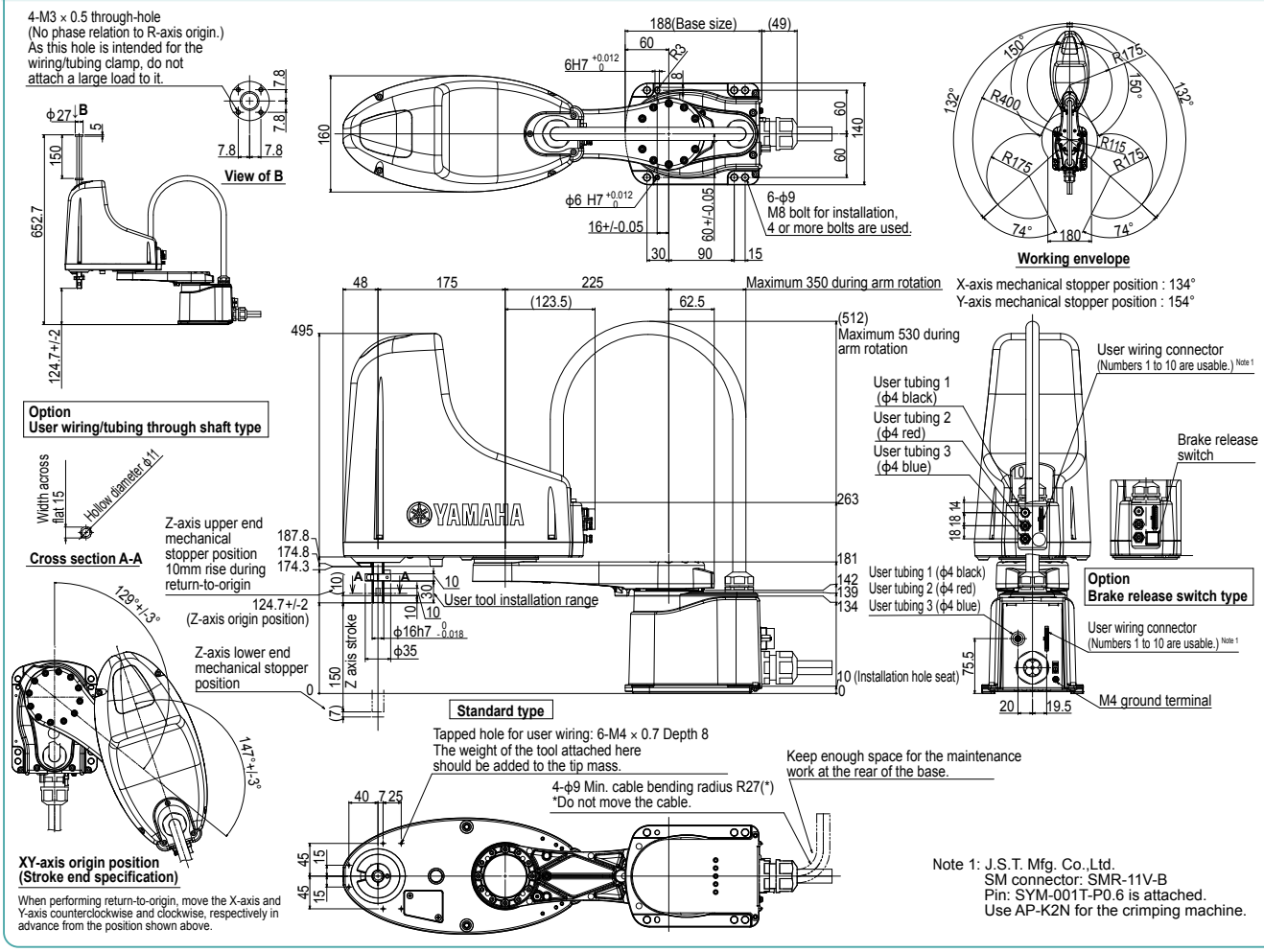
YK400XE-4 Shipment on February 2025 or later



Note 1: J.S.T. Mfg. Co.,Ltd.
SM connector: SMR-11V-B
Pin: SYM-001T-P0.6 is attached.
Use AP-K2N for the crimping machine.

YK400XE-4

Shipment on January 2025 or earlier



YK400XG

Standard type: Small type

- Arm length 400mm
- Maximum payload 5kg

Ordering method

YK400XG - 150 - [ ] - [ ] - [ ] - RCX340-4 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK400XG	150: 150mm	No entry: None F: With tool flange	No entry: None S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		250 mm	150 mm	150 mm	-
	Rotation angle		+/-140 °	+/-144 °	-	+/-360 °
AC servo motor output			200 W	150 W	50 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			6.1 m/sec		1.1 m/sec	1020 °/sec
Maximum payload			5 kg (Standard specification), 4 kg (Option specifications Note 4)			
Standard cycle time: with 2kg payload Note 2			0.45 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm² (0.5 kgfcms²)			
User wiring			0.2 sq × 10 wires			
User tubing (Outer diameter)			ϕ 4 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			19.5 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Maximum payload of option specifications (with tool flange attached or with user wiring and tubing routed through spline shaft) is 4kg.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.) See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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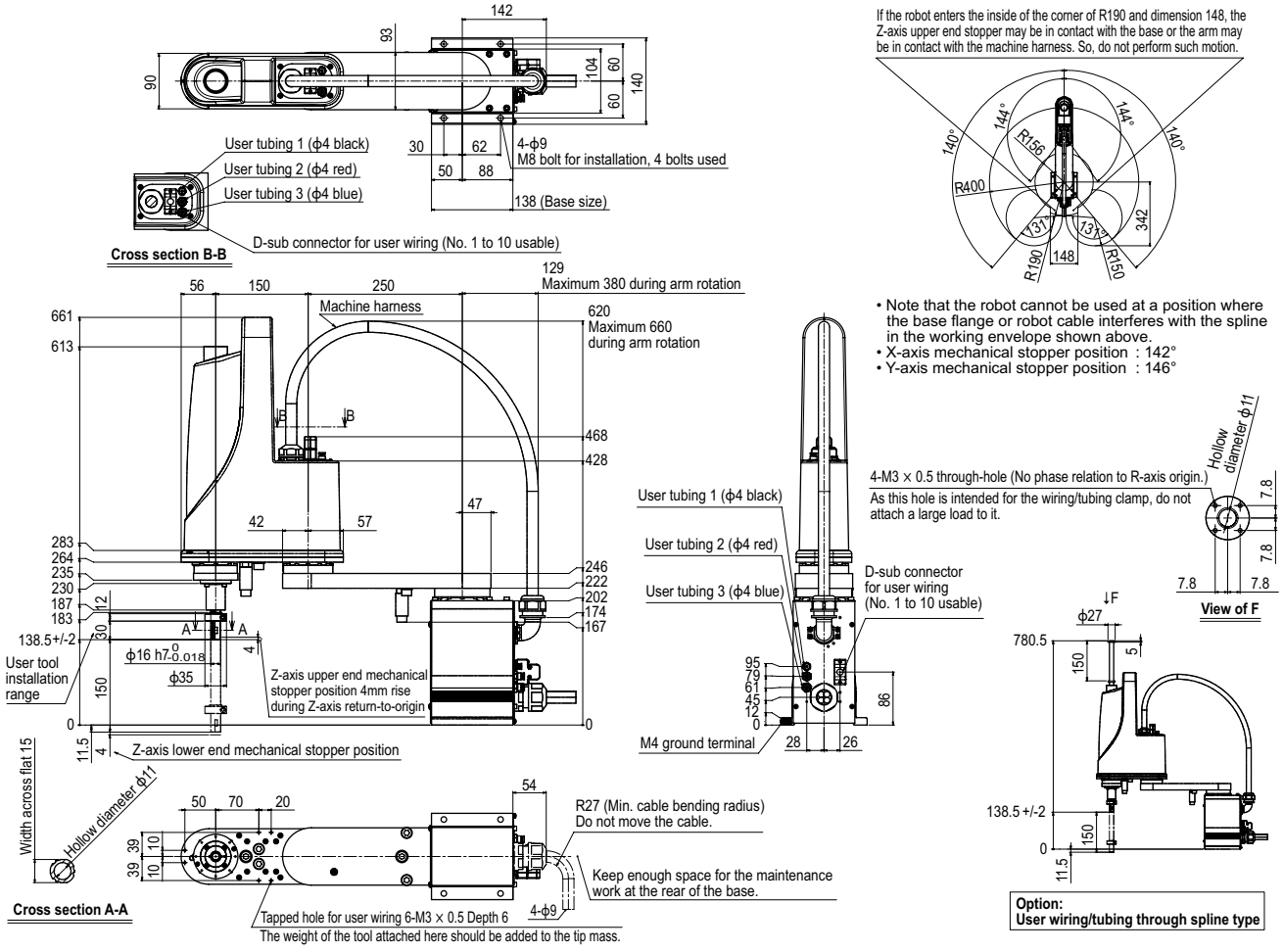
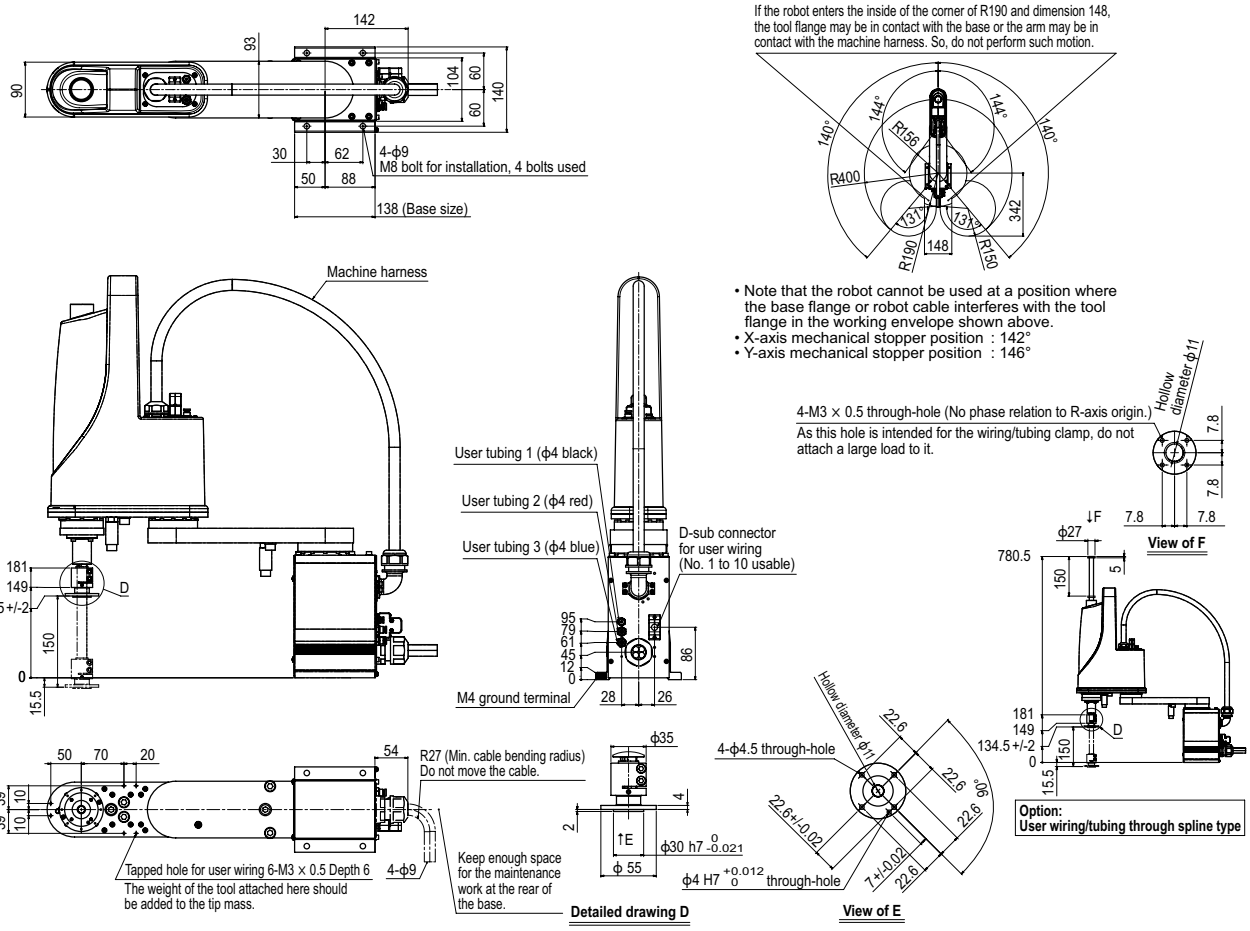
YK400XG



YK400XG Tool flange mount type



YK500XGL

Standard type: Medium type

- Arm length 500mm
- Maximum payload 5kg

Ordering method

YK500XGL - 150					RCX340-4							
Model	Z axis stroke 150: 150mm	Tool flange No entry: None F: With tool flange	Hollow shaft No entry: None S: With hollow shaft	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		250 mm	250 mm	150 mm	-
	Rotation angle		+/-140 °	+/-144 °	-	+/-360 °
AC servo motor output			200 W	150 W	50 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			5.1 m/sec		1.1 m/sec	1020 °/sec
Maximum payload			5 kg (Standard specification), 4 kg (Option specifications Note 4)			
Standard cycle time: with 2kg payload Note 2			0.48 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm² (0.5 kgfcms²)			
User wiring			0.2 sq × 10 wires			
User tubing (Outer diameter)			ϕ 4 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			21 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Maximum payload of option specifications (with tool flange attached or with user wiring and tubing routed through spline shaft) is 4kg.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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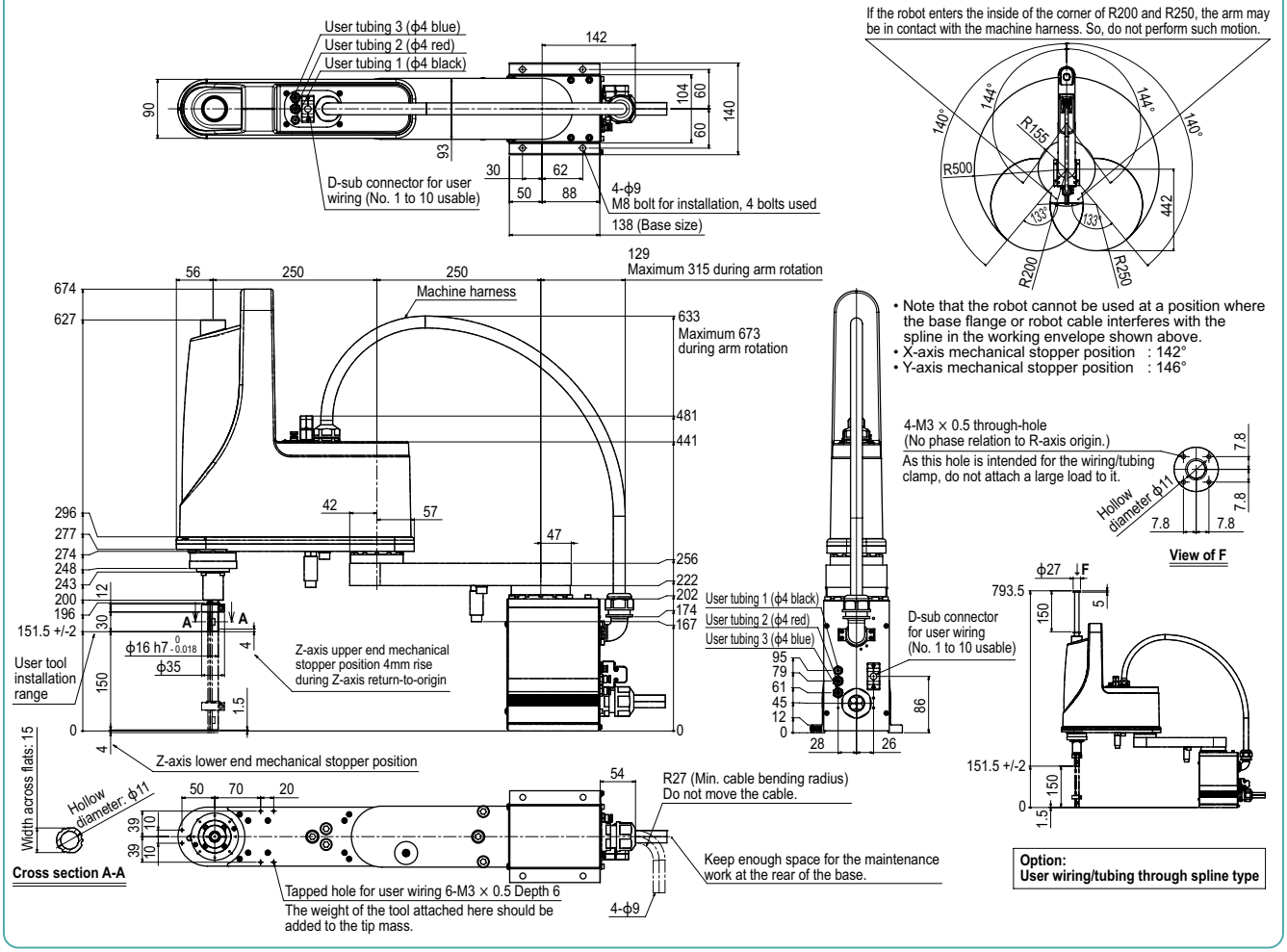
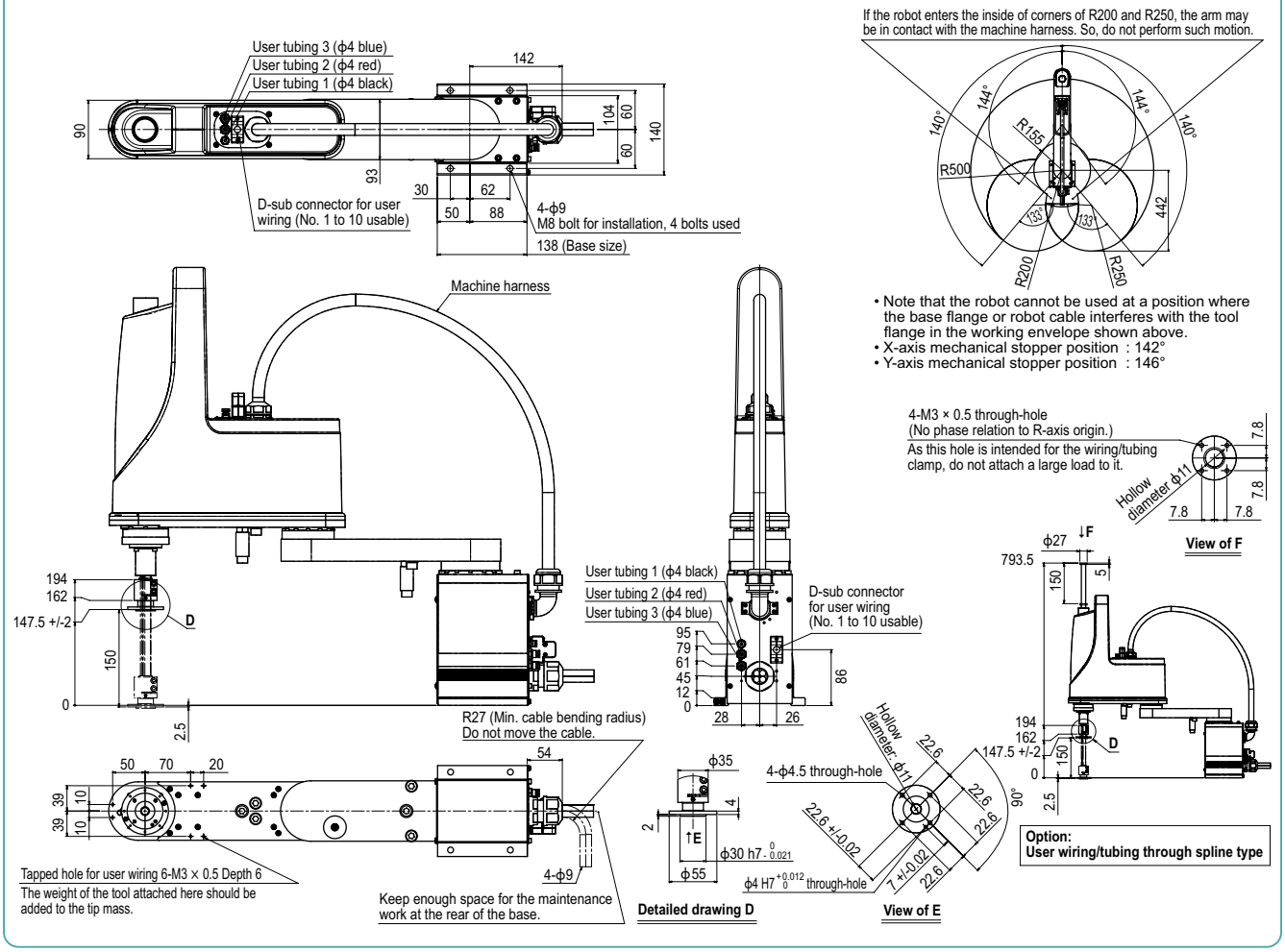
YK500XGL



YK500XGL Tool flange mount type



YK500XG

Standard type: Medium type

- Arm length 500mm
- Maximum payload 10kg

Ordering method

YK500XG	–		–		–	RCX340-4								
Model	Z axis stroke 200: 200mm 300: 300mm		Tool flange No entry: None F: With tool flange		Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		200 mm	300 mm	200 mm | 300 mm	–
	Rotation angle		+/-130 °	+/-145 °	–	+/-360 °
AC servo motor output			400 W	200 W	200 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			7.6 m/sec		2.3 m/sec | 1.7 m/sec	1700 °/sec
Maximum payload			10 kg (Standard type), 9 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload Note 2			0.42 sec			
R-axis tolerable moment of inertia Note 3			0.30 kgm^2			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			φ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			30 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1700	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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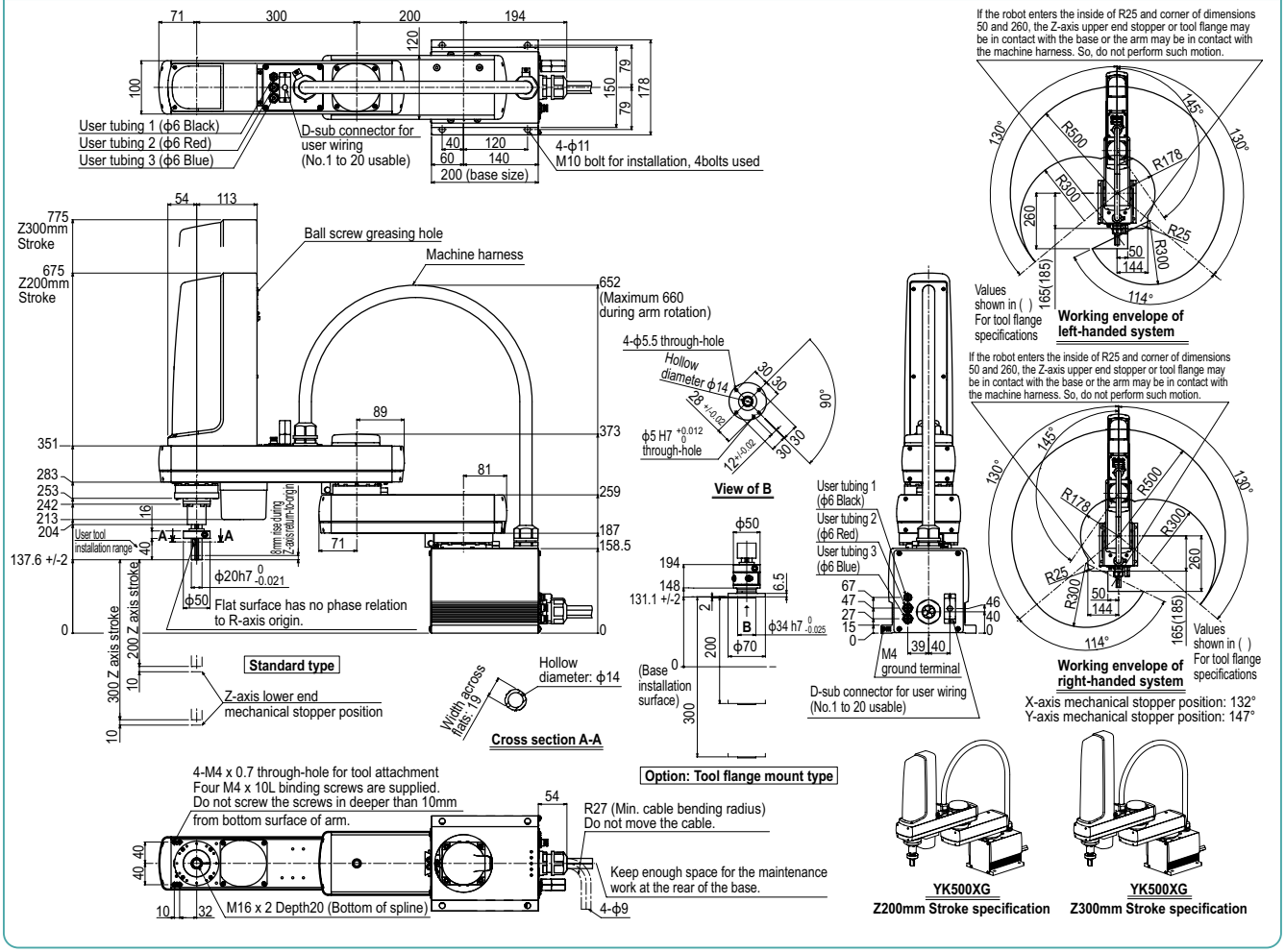
YK500XG



YK510XE-10

Standard type: Medium type

LOW COST HIGH PERFORMANCE MODEL

Arm length 510mm **Maximum payload 10kg**

Ordering method

YK510XE - 10 - 200 [ ] [ ] [ ] [ ] RCX340-4 [ ] [ ] [ ]

Model	Maximum payload	Z axis stroke	Tool flange	Hollow shaft/cap	Brake release switch	Cable	Controller / Number of controllable axes	Safety standard	Option A to E (OP.A to E)	Absolute battery
			No entry: None F: With tool flange	No entry: None S: With hollow shaft C: With hollow cap	No entry: None BS: With brake release switch	3L: 3.5m 5L: 5m 10L: 10m				

Specify various controller setting items.

RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		235 mm	275 mm	200 mm	-
	Rotation angle		+/-134 °	+/-152 °	-	+/-360 °
AC servo motor output			400 W	200 W	200 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled		Timing belt	
		Speed reducer to output	Direct-coupled			Timing belt
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.01 °
Maximum speed			7.8 m/sec		2 m/sec	2600 °/sec
Maximum payload			10 kg (Standard specification, Option specifications Note 4), 9 kg (Option specifications Note 5)			
Standard cycle time: with 2kg payload Note 2			0.38 sec			
R-axis tolerable moment of inertia Note 3			0.3 kgm^2			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			25 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions and performing the coarse positioning arch operation.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and offset amount for R-axis moment of inertia settings.
Note 4. Maximum payload of the standard or option specifications (brake release switch type, user wiring/tubing through cap type) is 10 kg.
Note 5. Maximum payload of the option specifications (tool flange mount type, user wiring/tubing through shaft type) is 9 kg.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1700	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be restricted by adding the X- and Y-axis mechanical stoppers. (The maximum movement range was set at shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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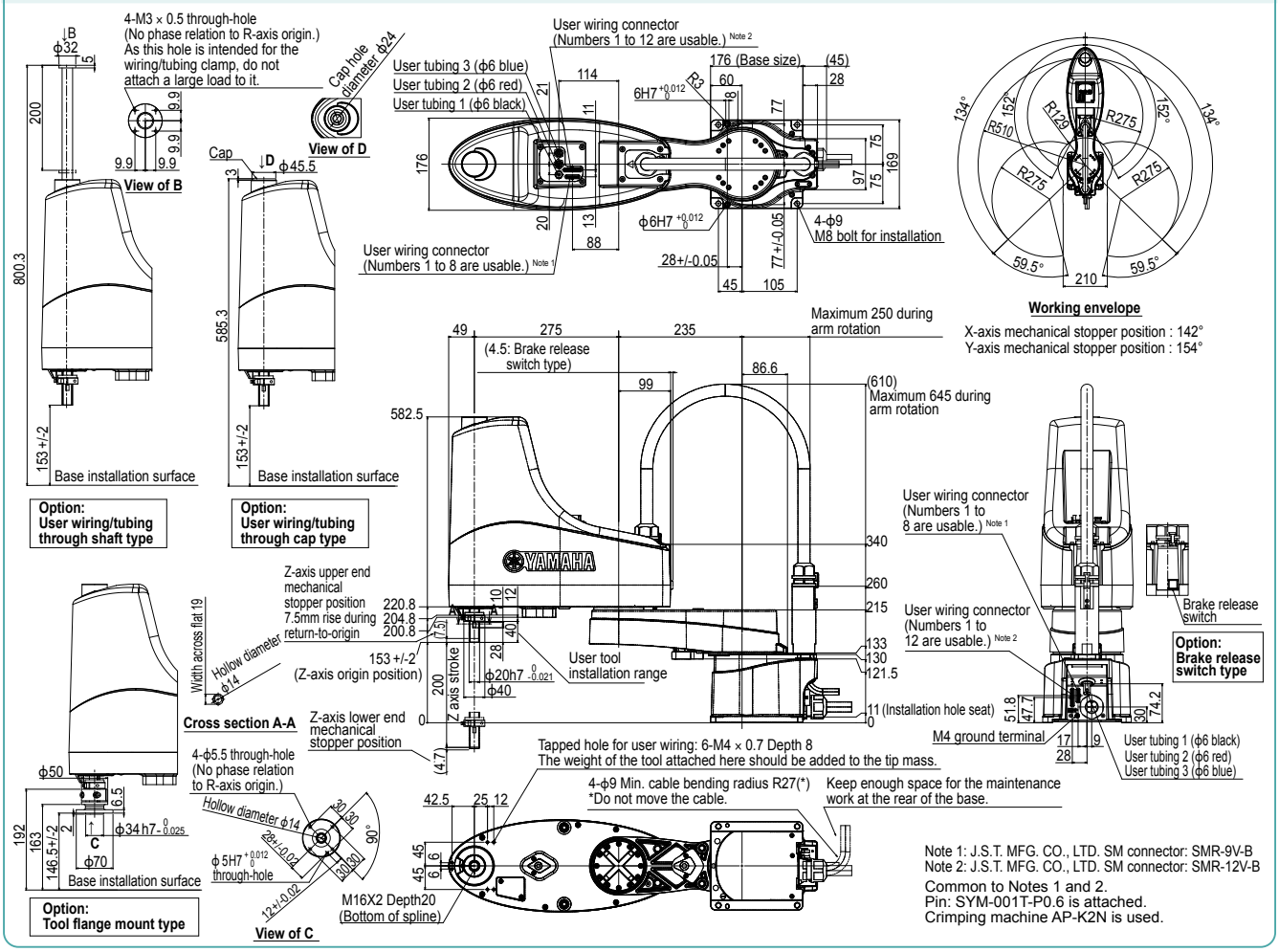
YK510XE-10



Note 1: J.S.T. MFG. CO., LTD. SM connector: SMR-9V-B
Note 2: J.S.T. MFG. CO., LTD. SM connector: SMR-12V-B
Common to Notes 1 and 2.
Pin: SYM-001T-P0.6 is attached.
Crimping machine AP-K2N is used.

YK600XGL

Standard type: Medium type

- Arm length 600mm
- Maximum payload 5kg

Ordering method

YK600XGL - 150 - [ ] - [ ] - [ ] - RCX340-4 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK600XGL	150: 150mm	No entry: None F: With tool flange	No entry: None S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		350 mm	250 mm	150 mm	-
	Rotation angle		+/-140 °	+/-144 °	-	+/-360 °
AC servo motor output			200 W	150 W	50 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			4.9 m/sec		1.1 m/sec	1020 °/sec
Maximum payload			5 kg (Standard specification), 4 kg (Option specifications Note 4)			
Standard cycle time: with 2kg payload Note 2			0.54 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm² (0.5 kgfcms²)			
User wiring			0.2 sq × 10 wires			
User tubing (Outer diameter)			ϕ 4 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			22 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings..
Note 4. Maximum payload of option specifications (with tool flange attached or with user wiring and tubing routed through spline shaft) is 4kg.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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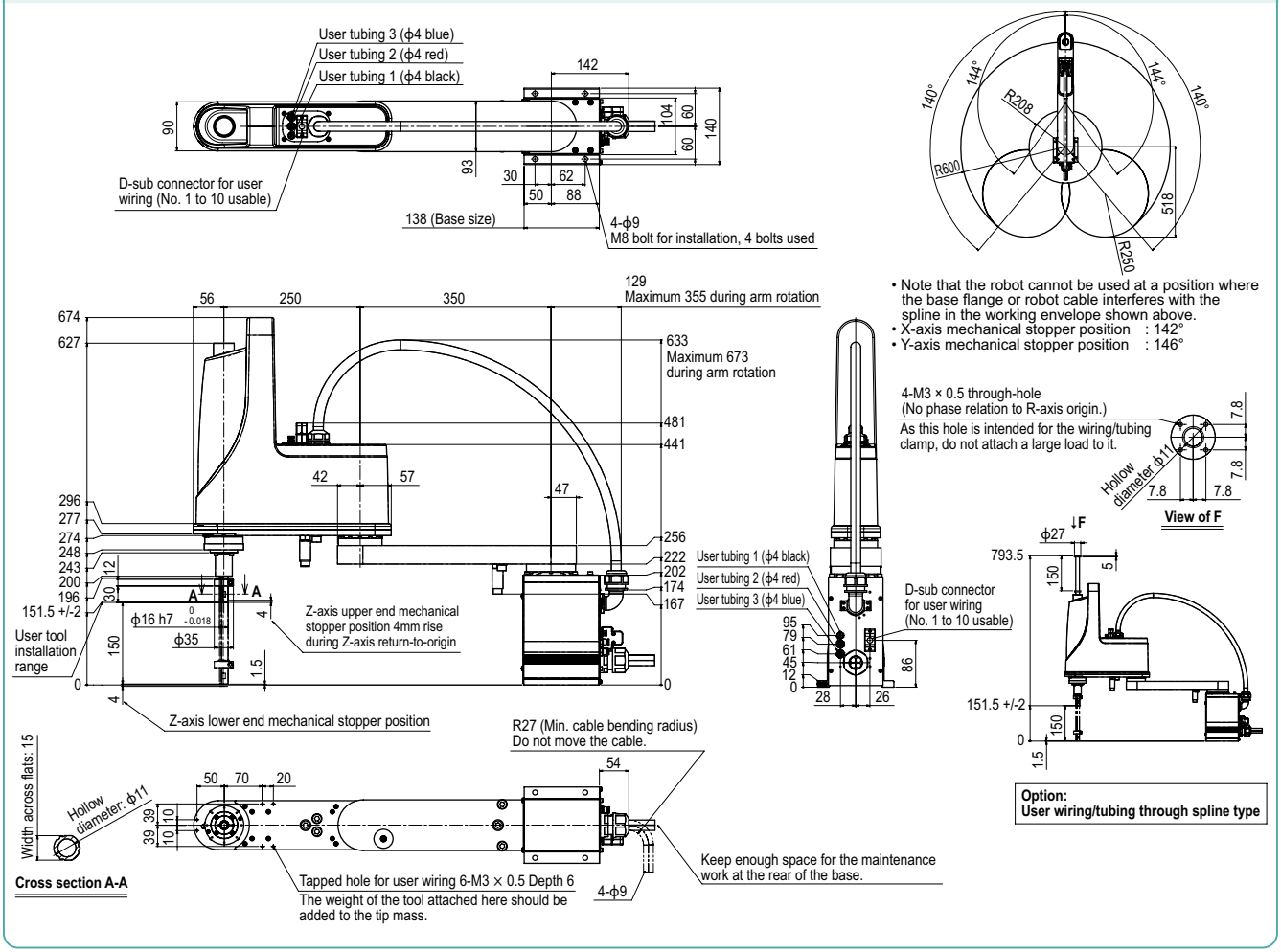
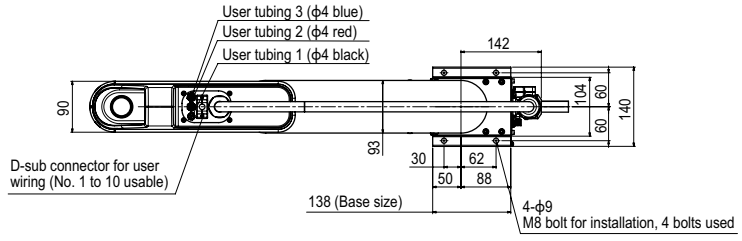
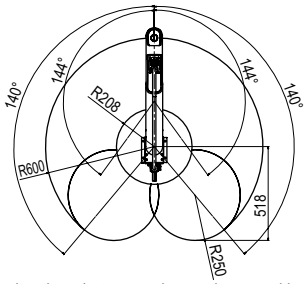
YK600XGL

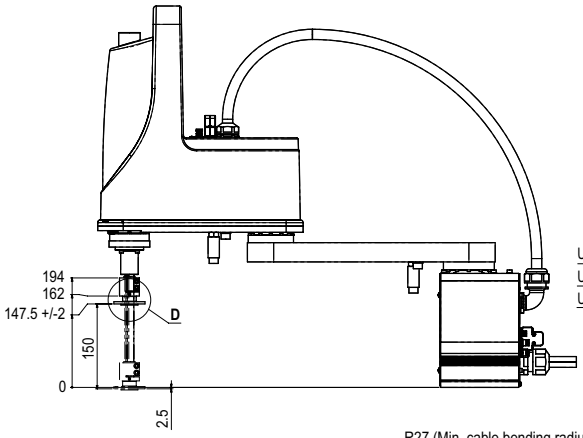


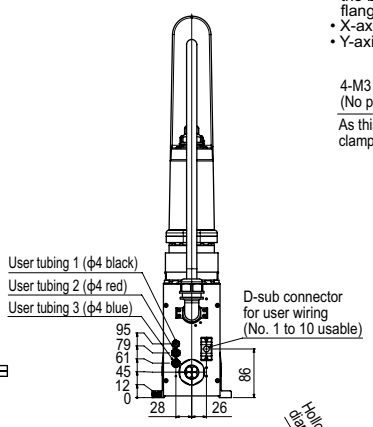
YK600XGL Tool flange mount type

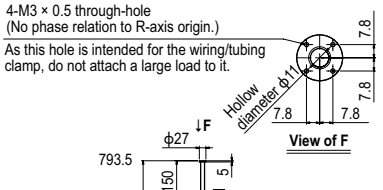


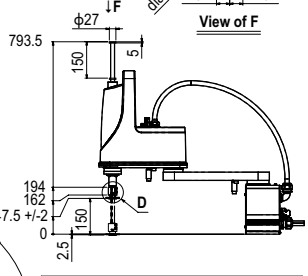


- Note that the robot cannot be used at a position where the base flange or robot cable interferes with the tool flange in the working envelope shown above.
- X-axis mechanical stopper position : 142°
- Y-axis mechanical stopper position : 146°

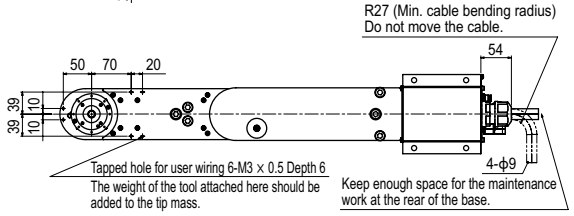


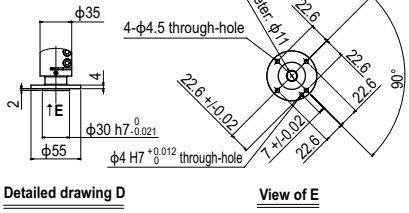






Option:
User wiring/tubing through spline type





Detailed drawing D

View of E

YK600XG

Standard type: Medium type

- Arm length 600mm
- Maximum payload 10kg

Ordering method

YK600XG	-		-		-	RCX340-4	-								
Model		Z axis stroke 200: 200mm 300: 300mm		Tool flange No entry: None F: With tool flange		Cable 3L: 3.5m 5L: 5m 10L: 10m		Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		300 mm	300 mm	200 mm | 300 mm	–
	Rotation angle		+/-130 °	+/-145 °	–	+/-360 °
AC servo motor output			400 W	200 W	200 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			8.4 m/sec		2.3 m/sec | 1.7 m/sec	1700 °/sec
Maximum payload			10 kg (Standard type), 9 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload Note 2			0.43 sec			
R-axis tolerable moment of inertia Note 3			0.30 kgm^2			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			31 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1700	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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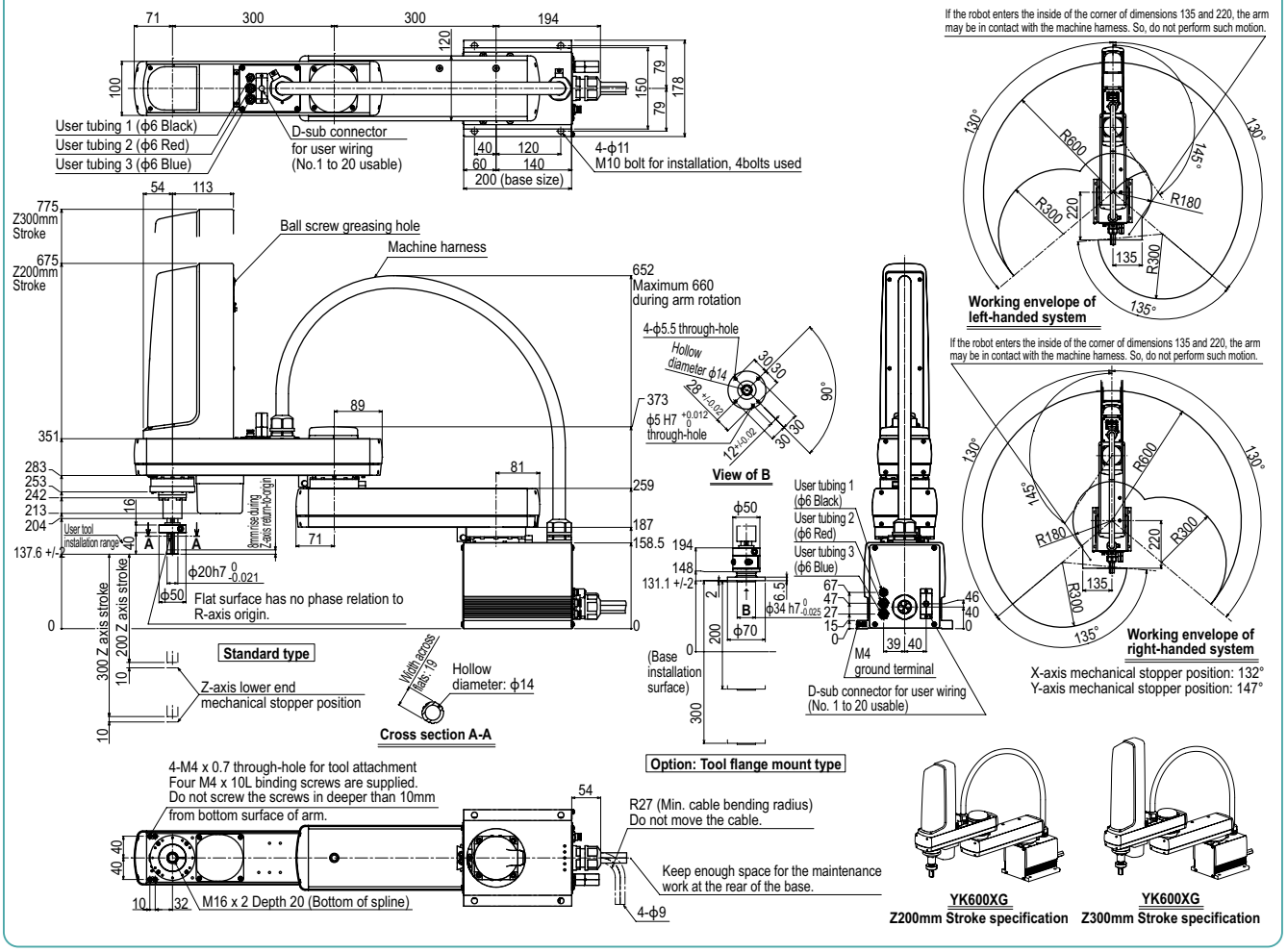
YK600XG



YK610XE-10

Standard type: Medium type

LOW COST HIGH PERFORMANCE MODEL

Arm length 610mm **Maximum payload 10kg**

Ordering method

YK610XE - 10 - 200 [ ] [ ] [ ] [ ] RCX340-4 [ ] [ ] [ ]

Model	Maximum payload	Z axis stroke	Tool flange	Hollow shaft/cap	Brake release switch	Cable	Controller / Number of controllable axes	Safety standard	Option A to E (OP.A to E)	Absolute battery
			No entry: None F: With tool flange	No entry: None S: With hollow shaft C: With hollow cap	No entry: None BS: With brake release switch	3L: 3.5m 5L: 5m 10L: 10m				

Specify various controller setting items.

RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		335 mm	275 mm	200 mm	-
	Rotation angle		+/-134 °	+/-152 °	-	+/-360 °
AC servo motor output			400 W	200 W	200 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled		Timing belt	
		Speed reducer to output	Direct-coupled			Timing belt
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.01 °
Maximum speed			8.6 m/sec		2 m/sec	2600 °/sec
Maximum payload			10 kg (Standard specification, Option specifications Note 4), 9 kg (Option specifications Note 5)			
Standard cycle time: with 2kg payload Note 2			0.39 sec			
R-axis tolerable moment of inertia Note 3			0.3 kgm^2			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			25 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions and performing the coarse positioning arch operation.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and offset amount for R-axis moment of inertia settings.
Note 4. Maximum payload of the standard or option specifications (brake release switch type, user wiring/tubing through cap type) is 10 kg.
Note 5. Maximum payload of the option specifications (tool flange mount type, user wiring/tubing through shaft type) is 9 kg.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1700	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be restricted by adding the X- and Y-axis mechanical stoppers. (The maximum movement range was set at shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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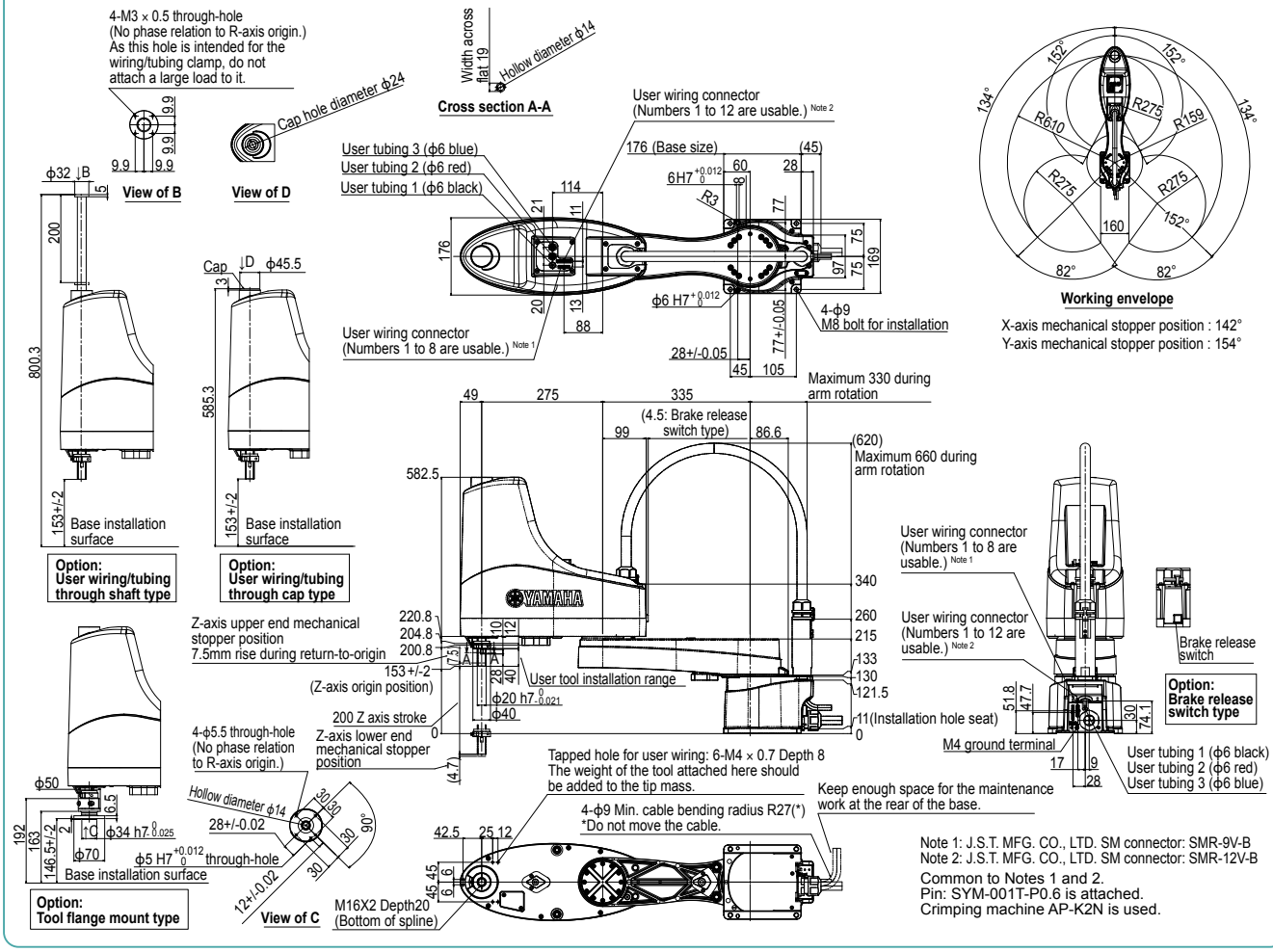
YK610XE-10



Controller RCX340 ▶ 636

YK600XGH

Standard type: Medium type

- Arm length 600mm
- Maximum payload 20kg

Ordering method

YK600XGH				RCX340-4							
Model	Z axis stroke	Tool flange	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	200: 200mm 400: 400mm	No entry: None F: With tool flange	3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		200 mm	400 mm	200 mm | 400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			7.7 m/sec		2.3 m/sec | 1.7 m/sec	920 °/sec
Maximum payload			20 kg (Standard type), 19 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload Note 2			0.47 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm^2			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 48 kg Z axis 400 mm: 50 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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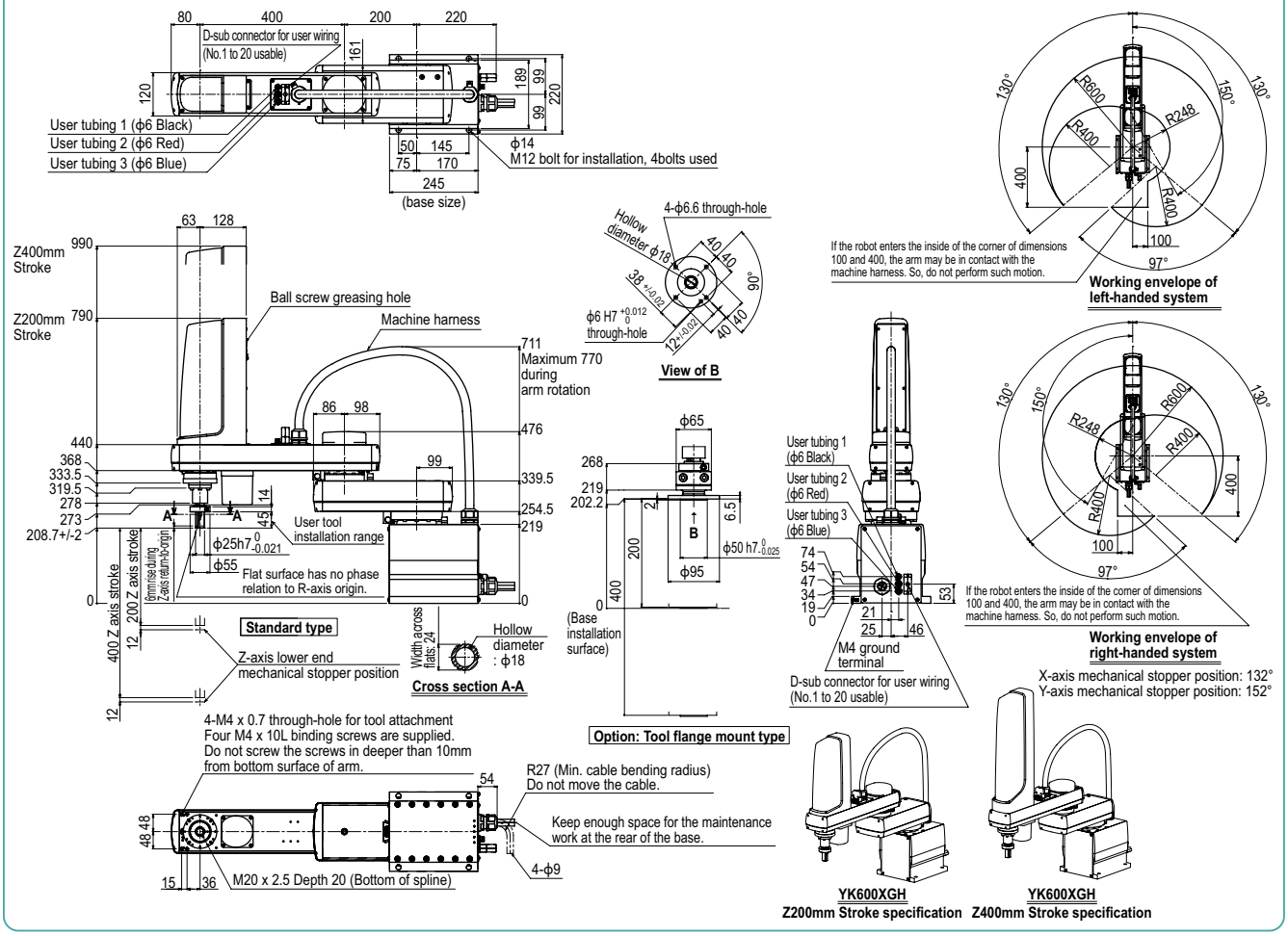
YK600XGH



YK700XGL

Standard type: Large type

Arm length 700mm | Maximum payload 10kg

Note. This model is a special order product. Please consult us for delivery time.

Ordering method

YK700XGL				RCX340-4							
Model	Z axis stroke	Tool flange	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	200: 200mm 300: 300mm	No entry: None F: With tool flange	3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		400 mm	300 mm	200 mm / 300 mm	-
	Rotation angle		+/-130 °	+/-145 °	-	+/-360 °
AC servo motor output			400 W	200 W	200 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.005 °
Maximum speed			9.2 m/sec		2.3 m/sec / 1.7 m/sec	1700 °/sec
Maximum payload			10 kg (Standard type), 9 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload Note 2			0.50 sec			
R-axis tolerable moment of inertia Note 3			0.30 kgm^2			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5, 10 m			
Weight			32 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1700	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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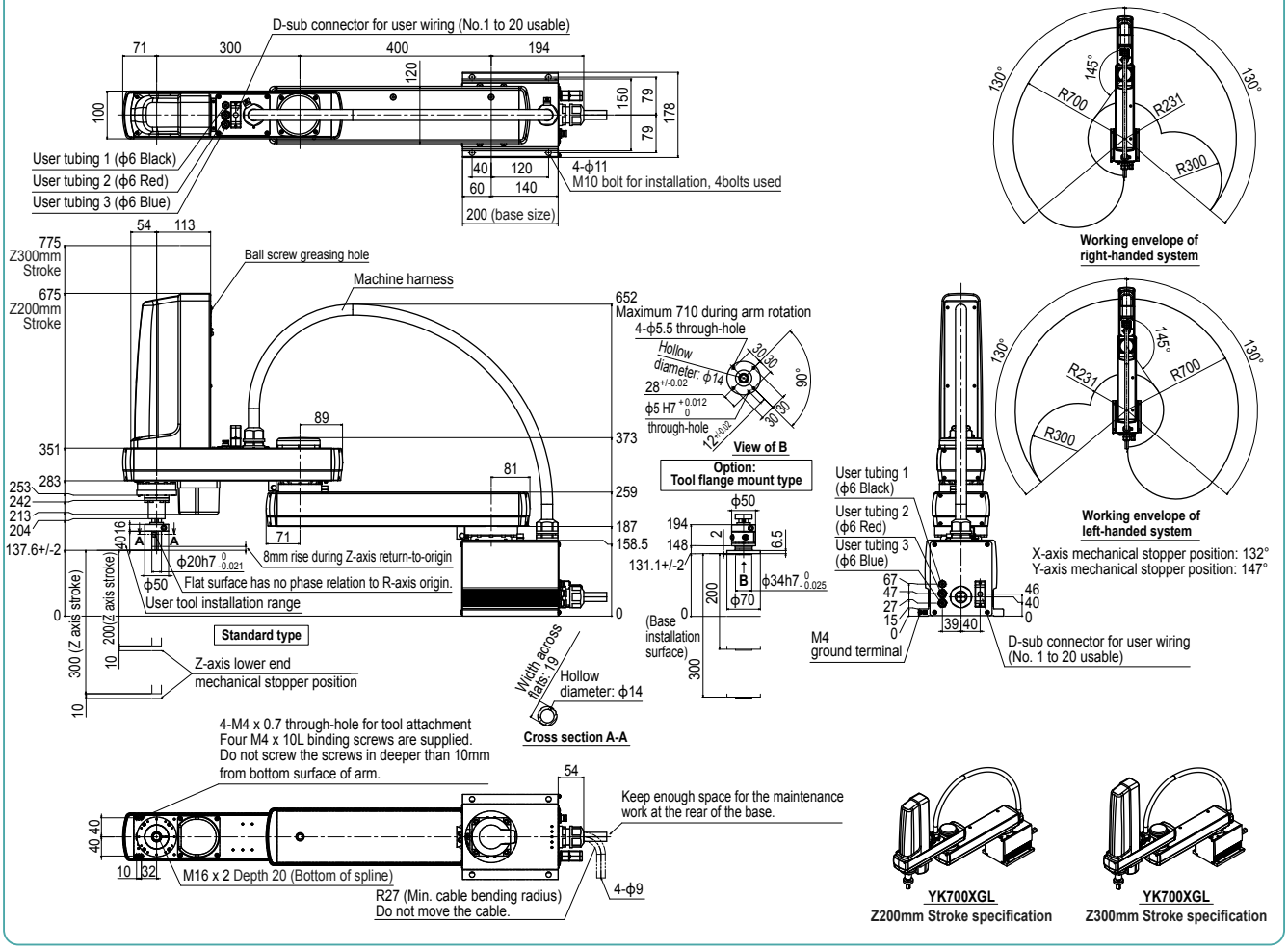
YK700XGL



Controller RCX340 ▶ 636

YK710XE-10

Standard type: Large type

LOW COST HIGH PERFORMANCE MODEL

Arm length 710mm **Maximum payload 10kg**

Ordering method

YK710XE - 10 - 200 - [ ] - [ ] - [ ] - [ ] - RCX340-4 - [ ] - [ ] - [ ]

Model	Maximum payload	Z axis stroke	Tool flange	Hollow shaft/cap	Brake release switch	Cable	Controller / Number of controllable axes	Safety standard	Option A to E (OP.A to E)	Absolute battery
			No entry: None F: With tool flange	No entry: None S: With hollow shaft C: With hollow cap	No entry: None BS: With brake release switch	3L: 3.5m 5L: 5m 10L: 10m				

Specify various controller setting items.

RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		435 mm	275 mm	200 mm	-
	Rotation angle		+/-134 °	+/-152 °	-	+/-360 °
AC servo motor output			400 W	200 W	200 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled		Timing belt	
		Speed reducer to output	Direct-coupled			Timing belt
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.01 °
Maximum speed			9.5 m/sec		2 m/sec	2600 °/sec
Maximum payload			10 kg (Standard specification, Option specifications Note 4), 9 kg (Option specifications Note 5)			
Standard cycle time: with 2kg payload Note 2			0.42 sec			
R-axis tolerable moment of inertia Note 3			0.3 kgm^2			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			26 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions and performing the coarse positioning arch operation.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and offset amount for R-axis moment of inertia settings.
Note 4. Maximum payload of the standard or option specifications (brake release switch type, user wiring/tubing through cap type) is 10 kg.
Note 5. Maximum payload of the option specifications (tool flange mount type, user wiring/tubing through shaft type) is 9 kg.

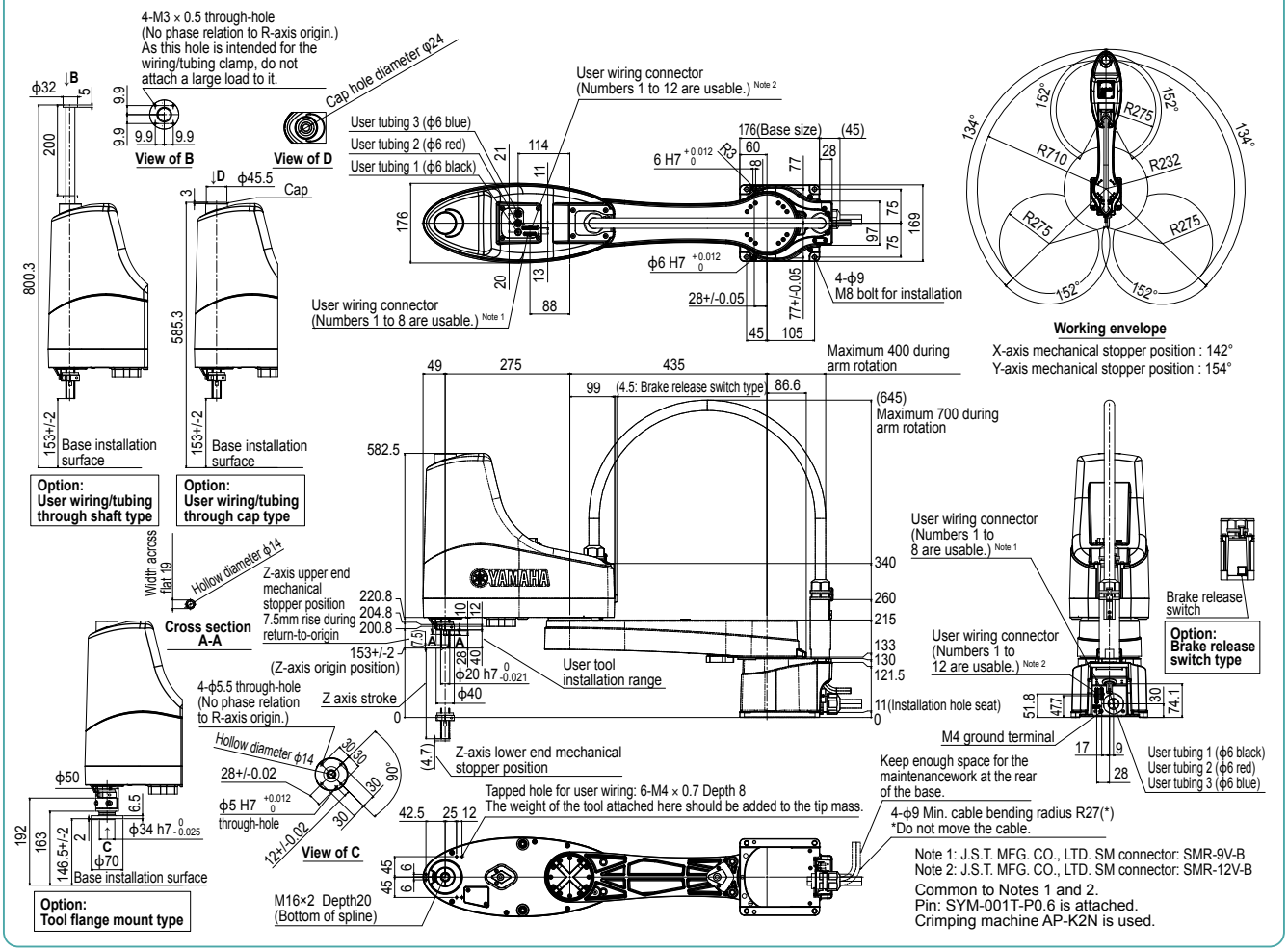
Controller

Controller	Power capacity (VA)	Operation method
RCX340	1700	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.) See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

YK710XE-10



YK700XG

Standard type: Large type

- Arm length 700mm
- Maximum payload 20kg

Ordering method

YK700XG -		-		-	RCX340-4 -								
Model	Z axis stroke		Tool flange		Cable		Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	200: 200mm 400: 400mm		No entry: None F: With tool flange		3L: 3.5m 5L: 5m 10L: 10m									

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		300 mm	400 mm	200 mm / 400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			8.4 m/sec		2.3 m/sec / 1.7 m/sec	920 °/sec
Maximum payload			20 kg (Standard type), 19 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload Note 2			0.42 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm^2			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 50 kg Z axis 400 mm: 52 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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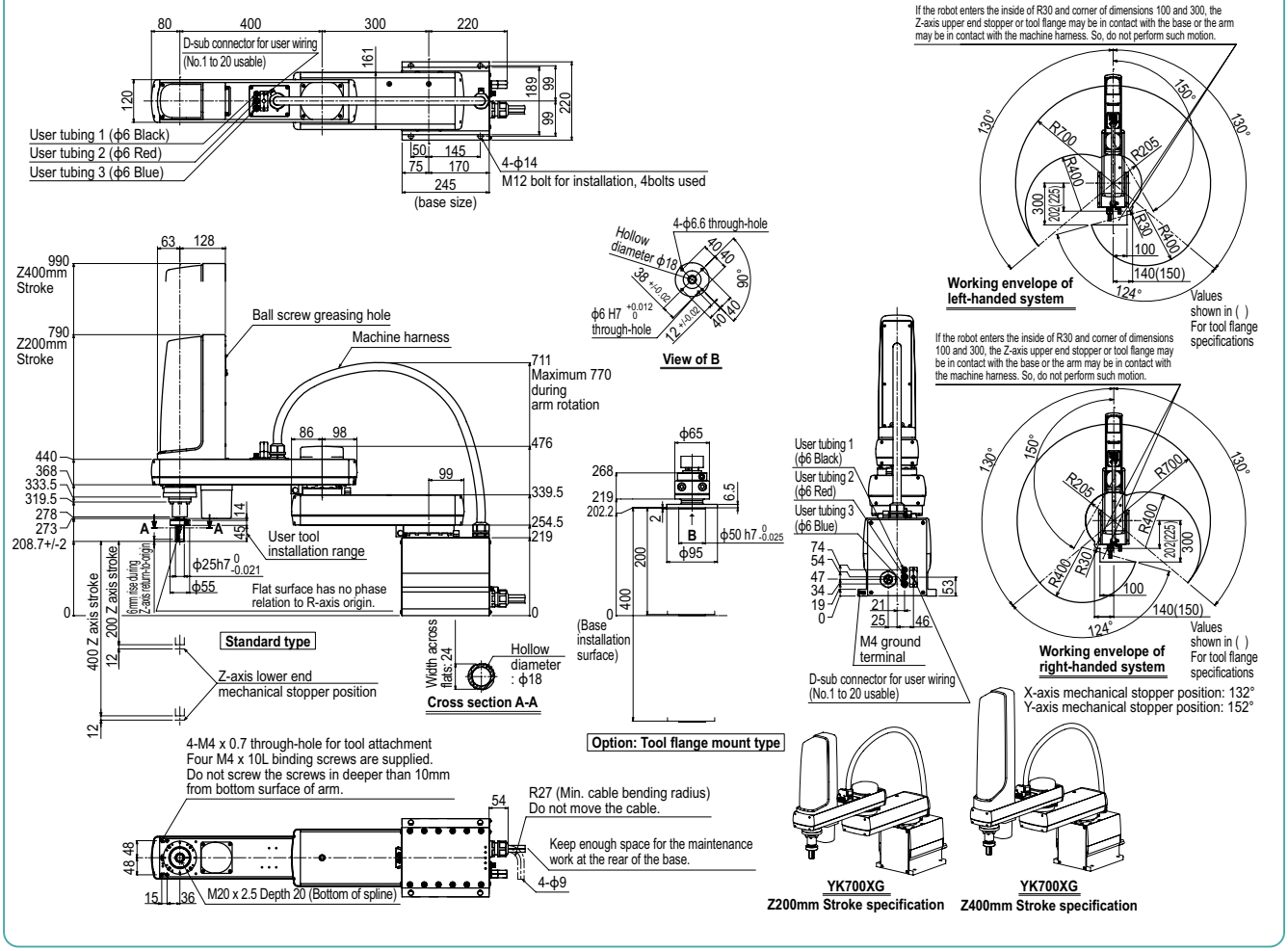
YK700XG



Controller RCX340 ▶ 636

YK800XG

Standard type: Large type

- Arm length 800mm
- Maximum payload 20kg

Ordering method

YK800XG				RCX340-4							
Model	Z axis stroke 200: 200mm 400: 400mm	Tool flange No entry: None F: With tool flange	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		400 mm	400 mm	200 mm / 400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			9.2 m/sec		2.3 m/sec / 1.7 m/sec	920 °/sec
Maximum payload			20 kg (Standard type), 19 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload Note 2			0.48 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm^2			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 52 kg Z axis 400 mm: 54 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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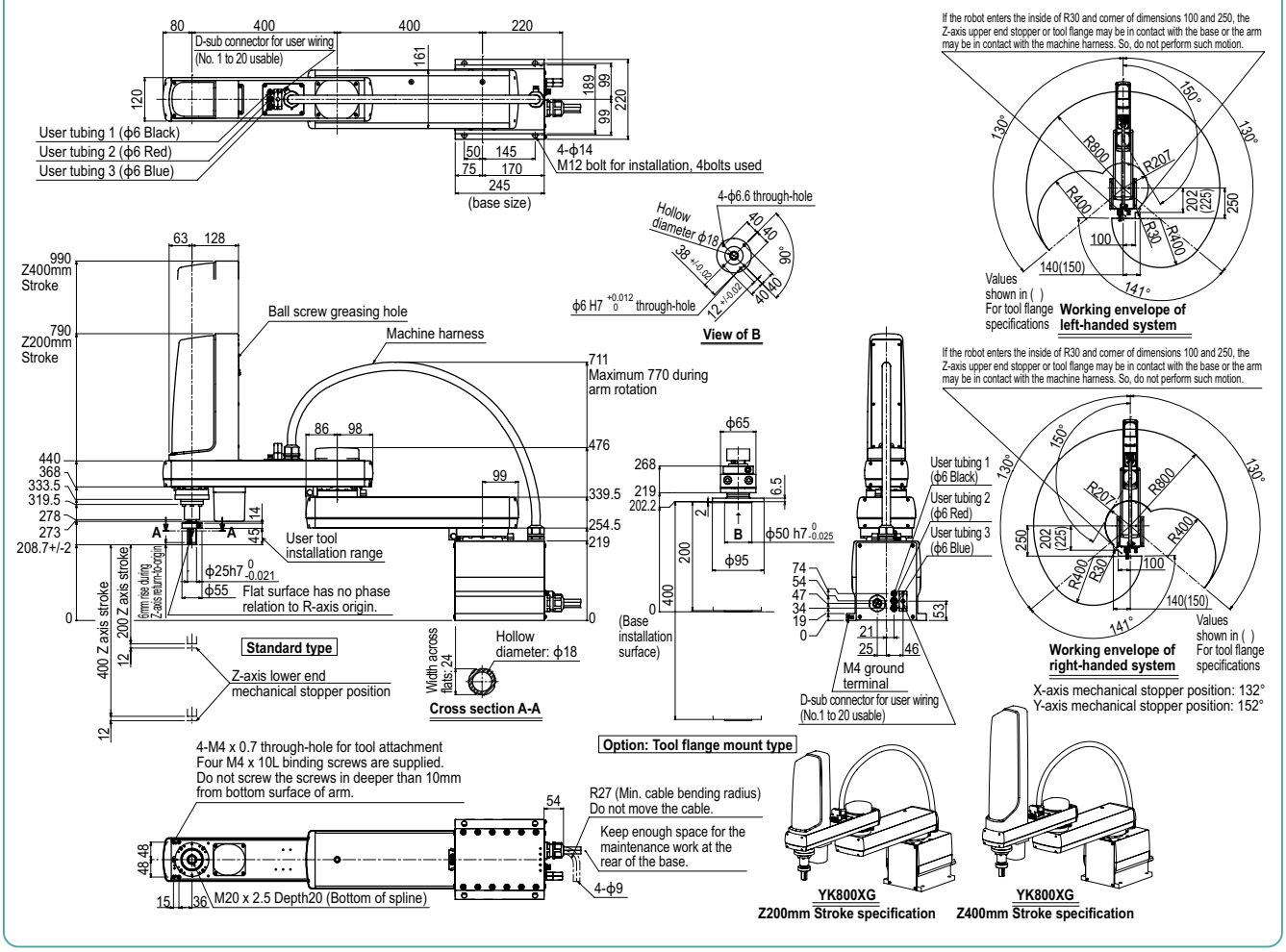
YK800XG



YK900XG

Standard type: Large type

- Arm length 900mm
- Maximum payload 20kg

Ordering method

YK900XG -		-		-	RCX340-4 -								
Model	Z axis stroke 200: 200mm 400: 400mm		Tool flange No entry: None F: With tool flange		Cable 3L: 3.5m 5L: 5m 10L: 10m		Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		500 mm	400 mm	200 mm / 400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			9.9 m/sec		2.3 m/sec / 1.7 m/sec	920 °/sec
Maximum payload			20 kg (Standard type), 19 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload Note 2			0.49 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm^2			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 54 kg Z axis 400 mm: 56 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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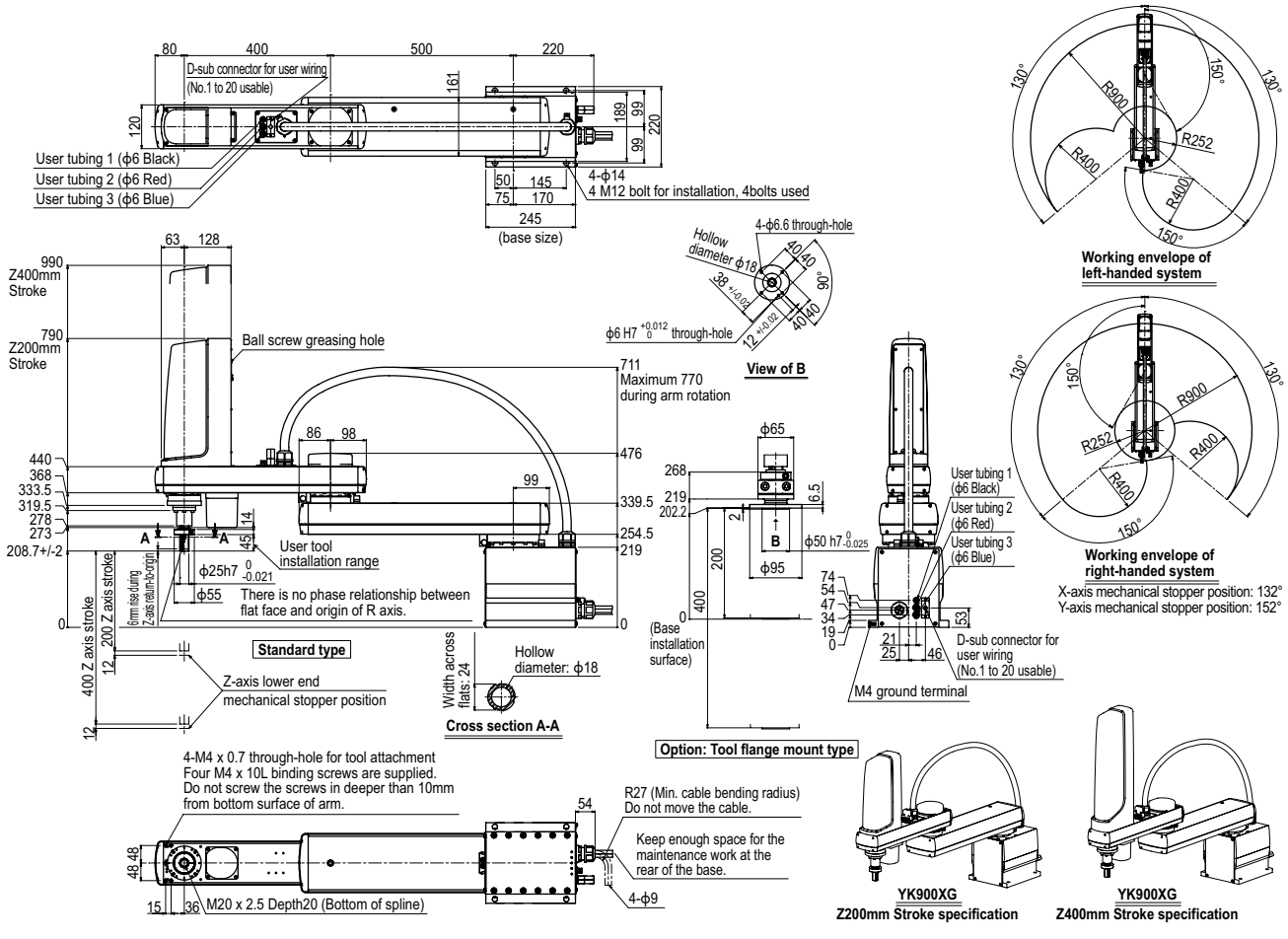
YK900XG

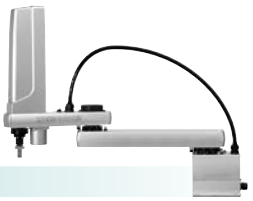


Controller RCX340 ▶ 636

YK1000XG

Standard type: Large type

- Arm length 1000mm
- Maximum payload 20kg



Ordering method

YK1000XG				RCX340-4							
Model	Z axis stroke 200: 200mm 400: 400mm	Tool flange No entry: None F: With tool flange	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		600 mm	400 mm	200 mm / 400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			10.6 m/sec		2.3 m/sec / 1.7 m/sec	920 °/sec
Maximum payload			20 kg (Standard type), 19 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload Note 2			0.49 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm²			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			φ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 56 kg Z axis 400 mm: 58 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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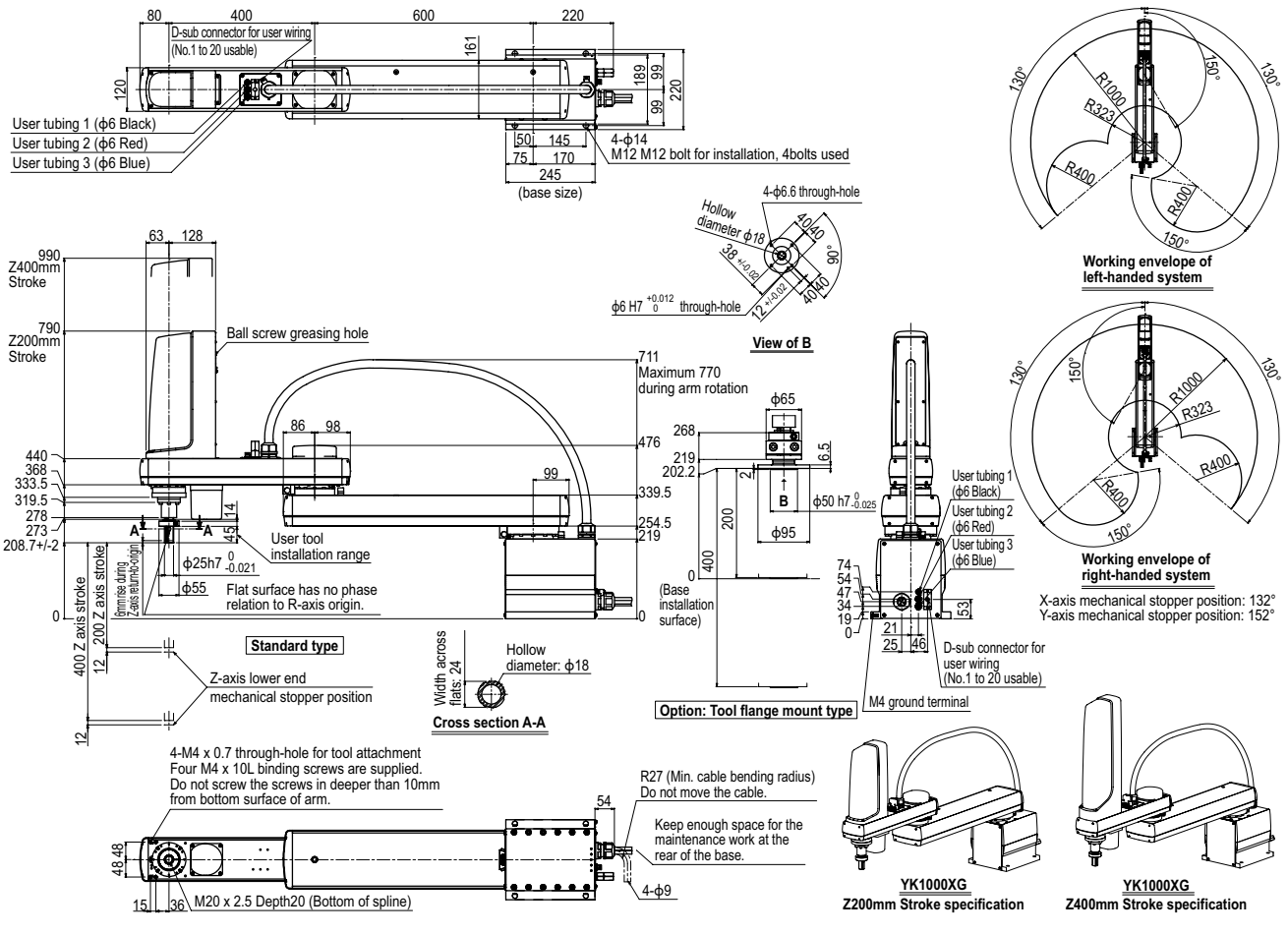
YK1000XG



YK1200X

Standard type: Large type

- Arm length 1200mm
- Maximum payload 50kg

Ordering method

YK1200X	- 400	-	- RCX340-4	-	-	-	-	-	-	-
Model	Z axis stroke	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Cable: 3L: 3.5m / 5L: 5m / 10L: 10m

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		600 mm	600 mm	400 mm	–
	Rotation angle		+/-125 °	+/-150 °	–	+/-180 °
AC servo motor output			900 W	800 W	600 W	400 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled		Timing belt transmission	Timing belt transmission
		Speed reducer to output	Direct-coupled		Direct-coupled	Direct-coupled
Repeatability Note 1			+/-0.05 mm		+/-0.02 mm	+/-0.005 °
Maximum speed			7.4 m/sec		0.75 m/sec	600 °/sec
Maximum payload			50 kg			
Standard cycle time: with 2kg payload Note 2			0.91 sec			
R-axis tolerable moment of inertia Note 3			2.45 kgm^2			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			124 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

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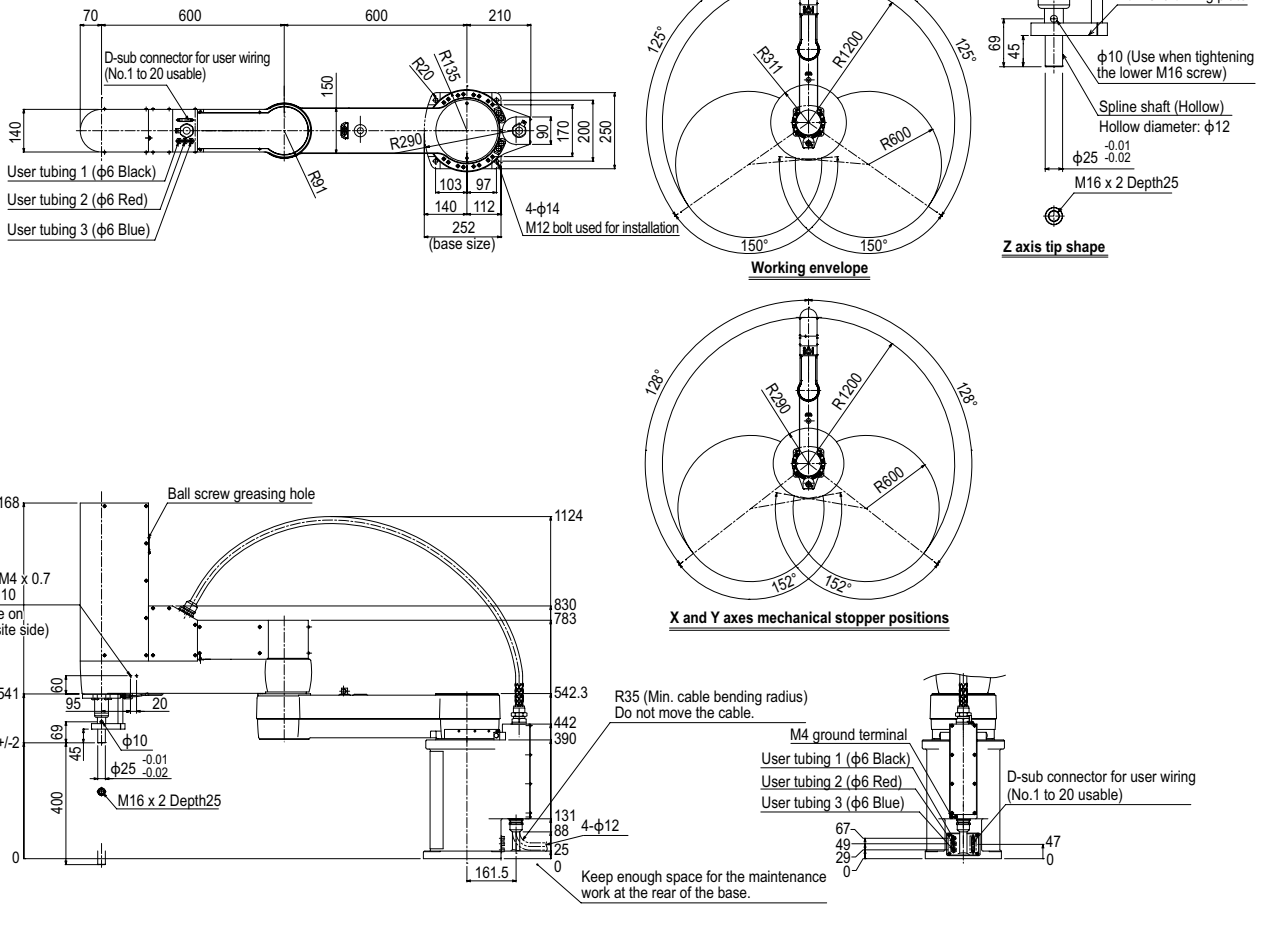
YK1200X



Controller RCX340 ▶ 636

YK1200XG

Standard type: Large type

- Arm length 1200mm
- Maximum payload 50kg

Ordering method

YK1200XG - 400					RCX341-4		R						
Model	Z axis stroke	Tool flange	User Wiring	Cable	Controller / Number of controllable axes	Safety standard	Regenerative unit	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
		No entry: None F: With tool flange	No entry: None UW: User Wiring Note.4	3L: 3.5m 5L: 5m 10L: 10m									

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		600 mm	600 mm	400 mm	–
	Rotation angle		+/-130 °	+/-150 °	+/-360 °	+/-360 °
AC servo motor output			950 W	400 W	750 W	400 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.05 mm		+/-0.02 mm	+/-0.005 °
Maximum speed			7.7 m/sec		1.6 m/sec	600 °/sec
Maximum payload			50 kg			
Standard cycle time: with 5kg payload Note 2			0.61 sec			
R-axis tolerable moment of inertia Note 3			2.45 kgm^2			
User wiring			0.2 sq × 12 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			96 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. User wiring stays (optional) are parts required for additional installation of user wiring. Installation on the robot must be performed by the customer.

Controller

Controller	Power capacity (VA)	Operation method
RCX341	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

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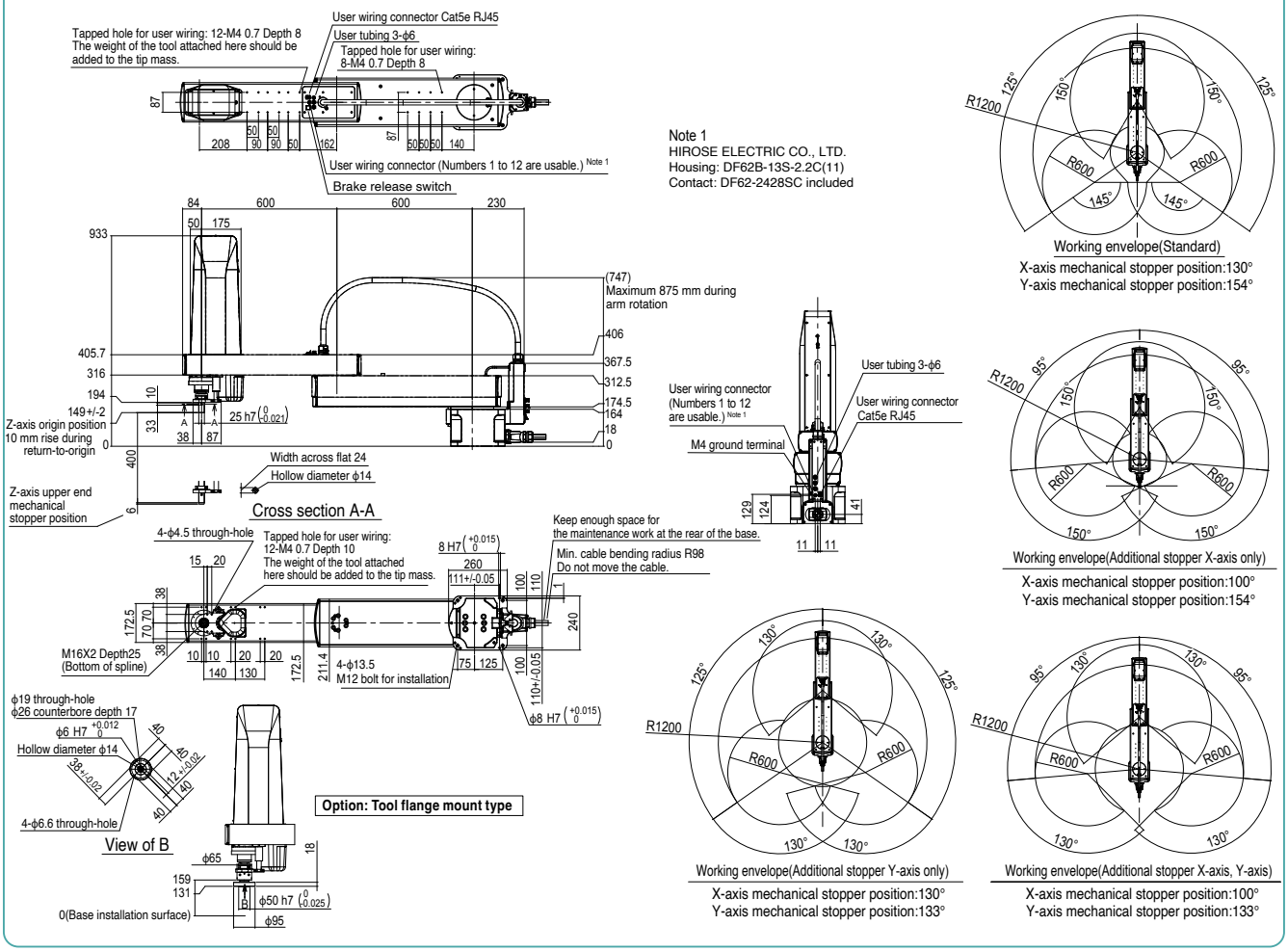
YK1200XG



YK300XGS

Wall mount / inverse type

Arm length 300mm **Maximum payload 5kg**

Note. Built-to-order product. Contact us for the delivery period.

Ordering method

YK300XGS -		- 150 -				- RCX340-4 -								
Model	Installation method Note1	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	W: Wall mount (same as per external view) U: Inverse wall mount (upside down)	150: 150mm	No entry: None F: With tool flange	No entry: None S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ P.636

Note 1. When installing the robot, always follow the specifications.
Do not install the ceiling-mount robot upside down or do not install the inverse type robot to a ceiling.
Incorrect installation can cause trouble or malfunction.

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		150 mm	150 mm	150 mm	–
	Rotation angle		+/-120 °	+/-130 °	–	+/-360 °
AC servo motor output			200 W	150 W	50 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			4.4 m/sec		1.0 m/sec	1020 °/sec (wall mount) 720 °/sec (inverse wall mount)
Maximum payload			5 kg (Standard specification), 4 kg (Option specifications Note 4)			
Standard cycle time: with 2kg payload Note 2			0.49 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm^2			
User wiring			0.2 sq × 10 wires			
User tubing (Outer diameter)			ϕ 4 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			19.5 kg			

Note 1. This is the value at a constant ambient temperature.
Note 2. When reciprocating 25mm horizontally and 300mm horizontally (with a 2kg payload in rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Maximum payload of option specifications (with tool flange attached or with user wiring and tubing routed through spline shaft) is 4kg.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the position of Y axis mechanical stopper. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
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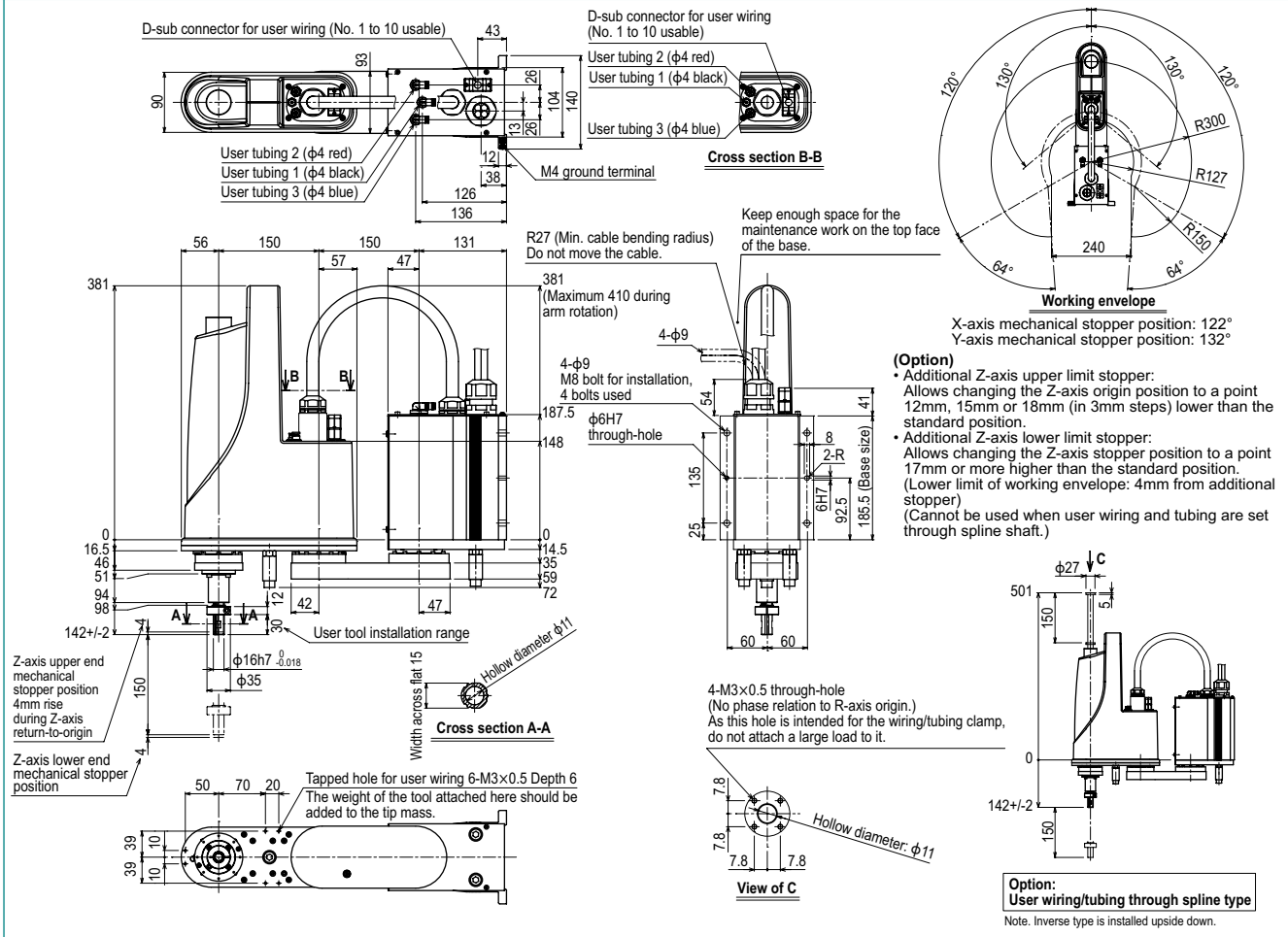
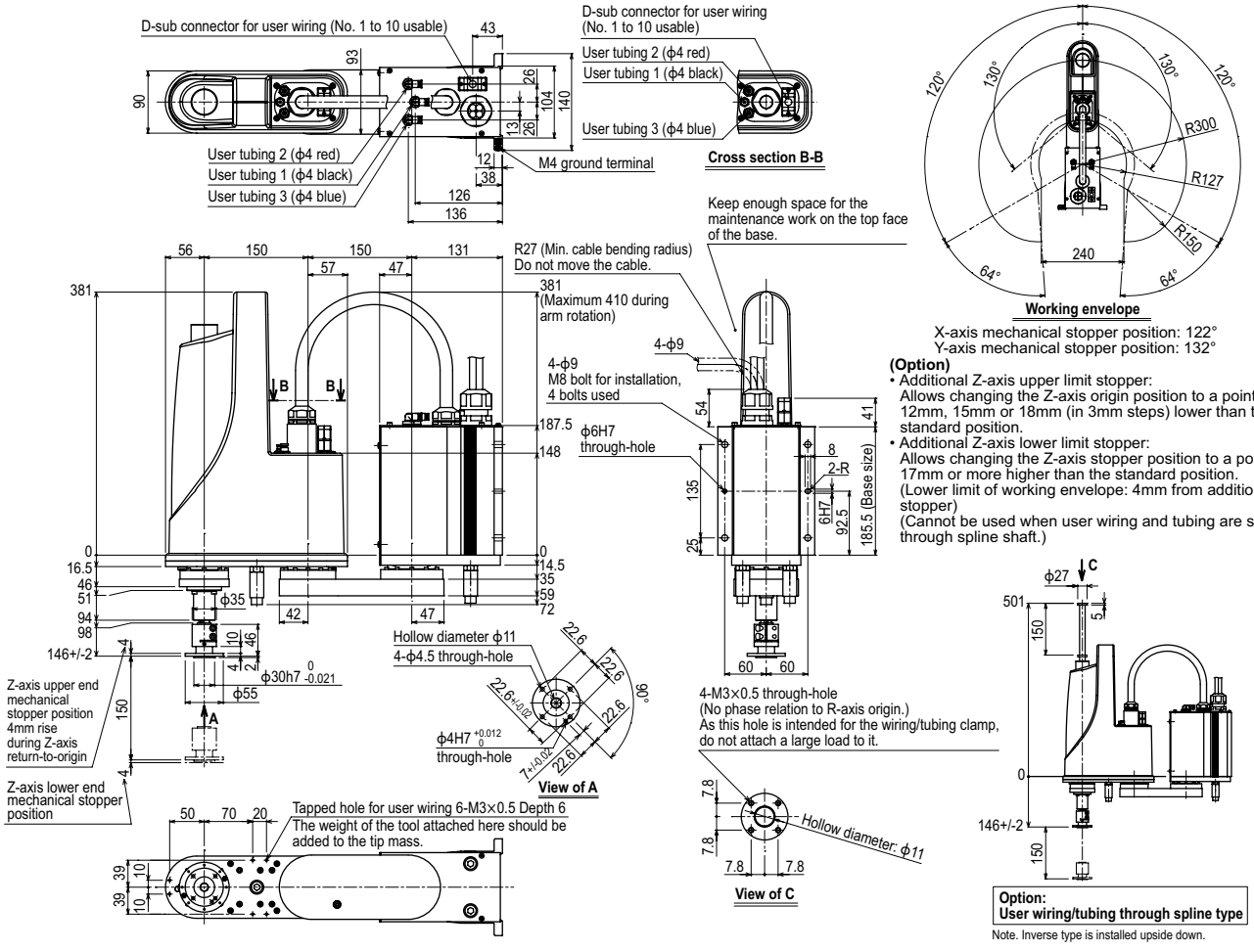
YK300XGS



Controller RCX340 ▶ 636

YK300XGS

YK300XGS Tool flange mount type



Note. Inverse type is installed upside down.

YK400XGS

Wall mount / inverse type

Arm length 400mm **Maximum payload 5kg** Note. Built-to-order product. Contact us for the delivery period.

Ordering method

YK400XGS -		- 150 -				- RCX340-4 -							
Model	Installation method Note1	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	W: Wall mount (same as per external view) U: Inverse wall mount (upside down)	150: 150mm	No entry: None F: With tool flange	No entry: None S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ P.636

Note 1. When installing the robot, always follow the specifications.
Do not install the ceiling-mount robot upside down or do not install the inverse type robot to a ceiling.
Incorrect installation can cause trouble or malfunction.

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		250 mm	150 mm	150 mm	–
	Rotation angle		+/-125 °	+/-144 °	–	+/-360 °
AC servo motor output			200 W	150 W	50 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			6.1 m/sec		1.1 m/sec	1020 °/sec (wall mount) 720 °/sec (inverse wall mount)
Maximum payload			5 kg (Standard specification), 4 kg (Option specifications Note 4)			
Standard cycle time: with 2kg payload Note 2			0.49 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm^2			
User wiring			0.2 sq × 10 wires			
User tubing (Outer diameter)			ϕ 4 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			20 kg			

Note 1. This is the value at a constant ambient temperature.
Note 2. When reciprocating 25mm horizontally and 300mm horizontally (with a 2kg payload in rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Maximum payload of option specifications (with tool flange attached or with user wiring and tubing routed through spline shaft) is 4kg.

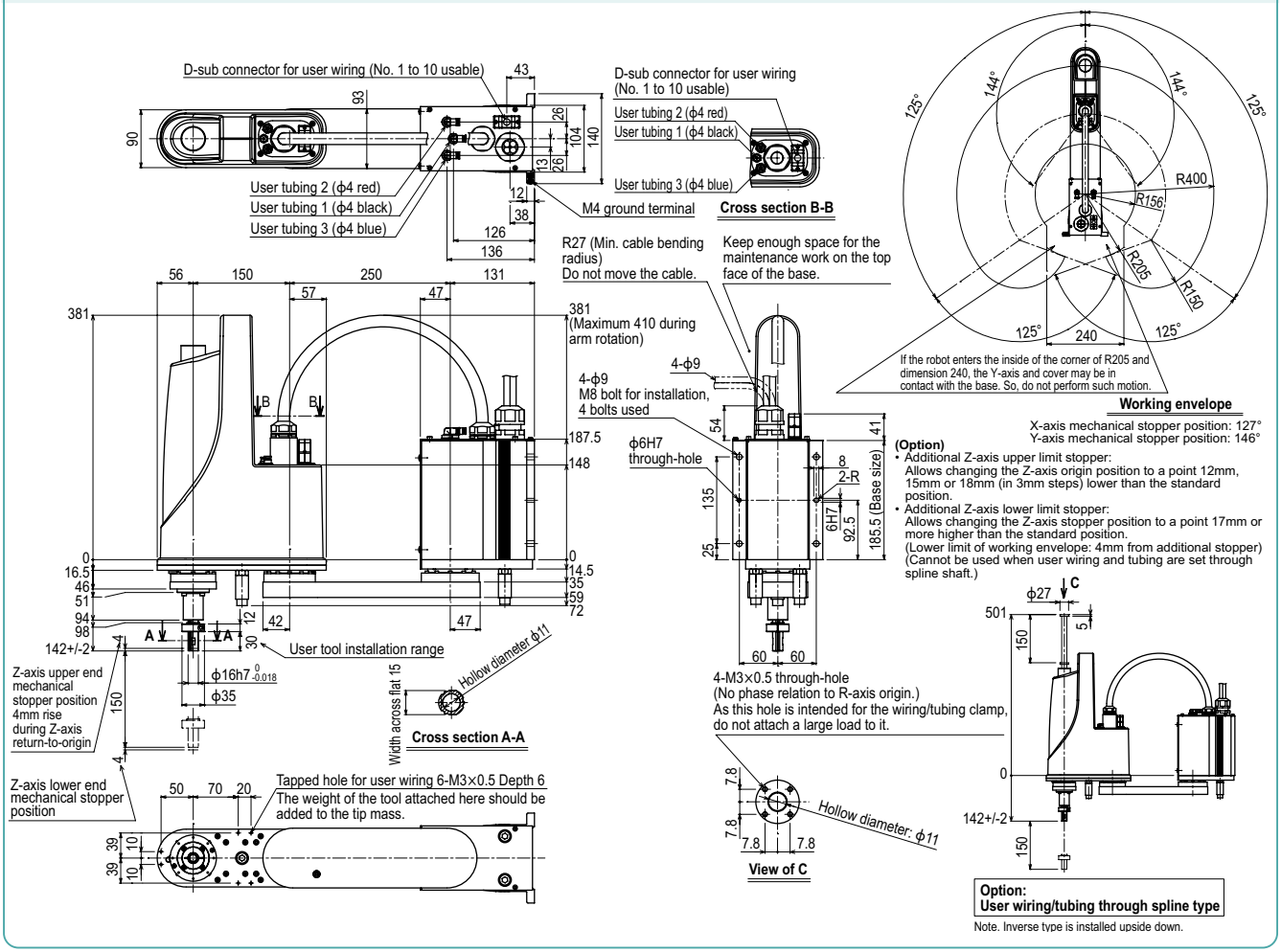
Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the position of Y axis mechanical stopper. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

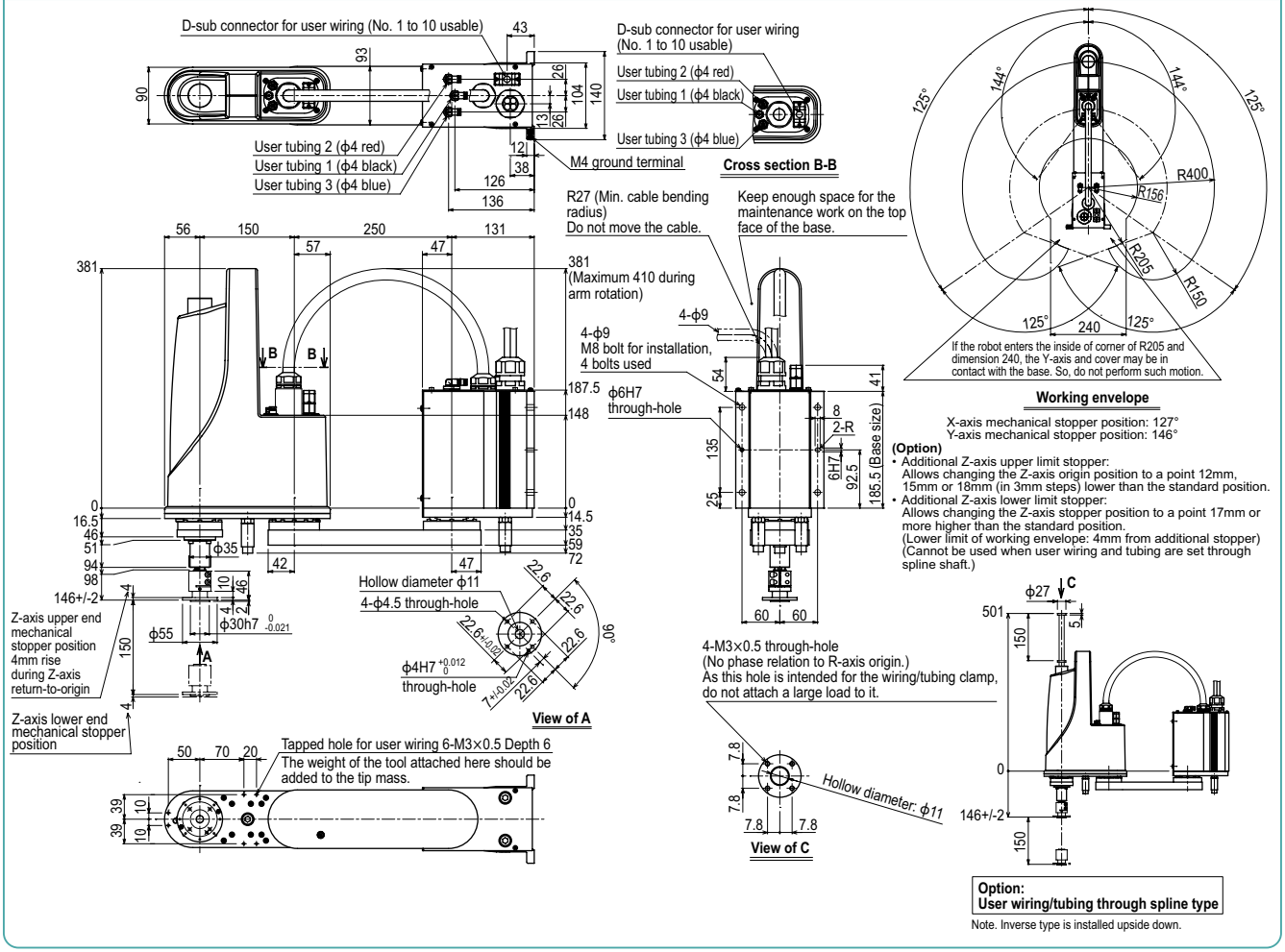
Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

YK400XGS



YK400XGS

YK400XGS Tool flange mount type



YK500XGS

Wall mount / inverse type

- Arm length 500mm
- Maximum payload 10kg

Ordering method

YK500XGS					RCX340-4							
Model	Installation method Note 1	Z axis stroke	Tool flange	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	W: Wall mount (same as per external view) U: Inverse wall mount (upside down)	200: 200mm 300: 300mm	No entry: None F: With tool flange	3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ P.636

Note 1. When installing the robot, always follow the specifications.
Do not install the ceiling-mount robot upside down or do not install the inverse type robot to a ceiling.
Incorrect installation can cause trouble or malfunction.

Specifications

			X-axis	Y-axis	Z-axis		R-axis
Axis specifications	Arm length		200 mm	300 mm	200 mm	300 mm	–
	Rotation angle		+/-105 °	+/-125 °	–		+/-360 °
AC servo motor output			400 W	200 W	200 W		200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled				
		Speed reducer to output	Direct-coupled				
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm		+/-0.004 °
Maximum speed			7.6 m/sec		2.3 m/sec	1.7 m/sec	1700 °/sec (wall mount) 800 °/sec (inverse wall mount)
Maximum payload			10 kg (Standard type), 9 kg (Tool flange mount type)				
Standard cycle time: with 2kg payload Note 2			0.45 sec				
R-axis tolerable moment of inertia Note 3			0.30 kgm²				
User wiring			0.2 sq × 20 wires				
User tubing (Outer diameter)			φ 6 × 3				
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)				
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m				
Weight			30 kg				

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

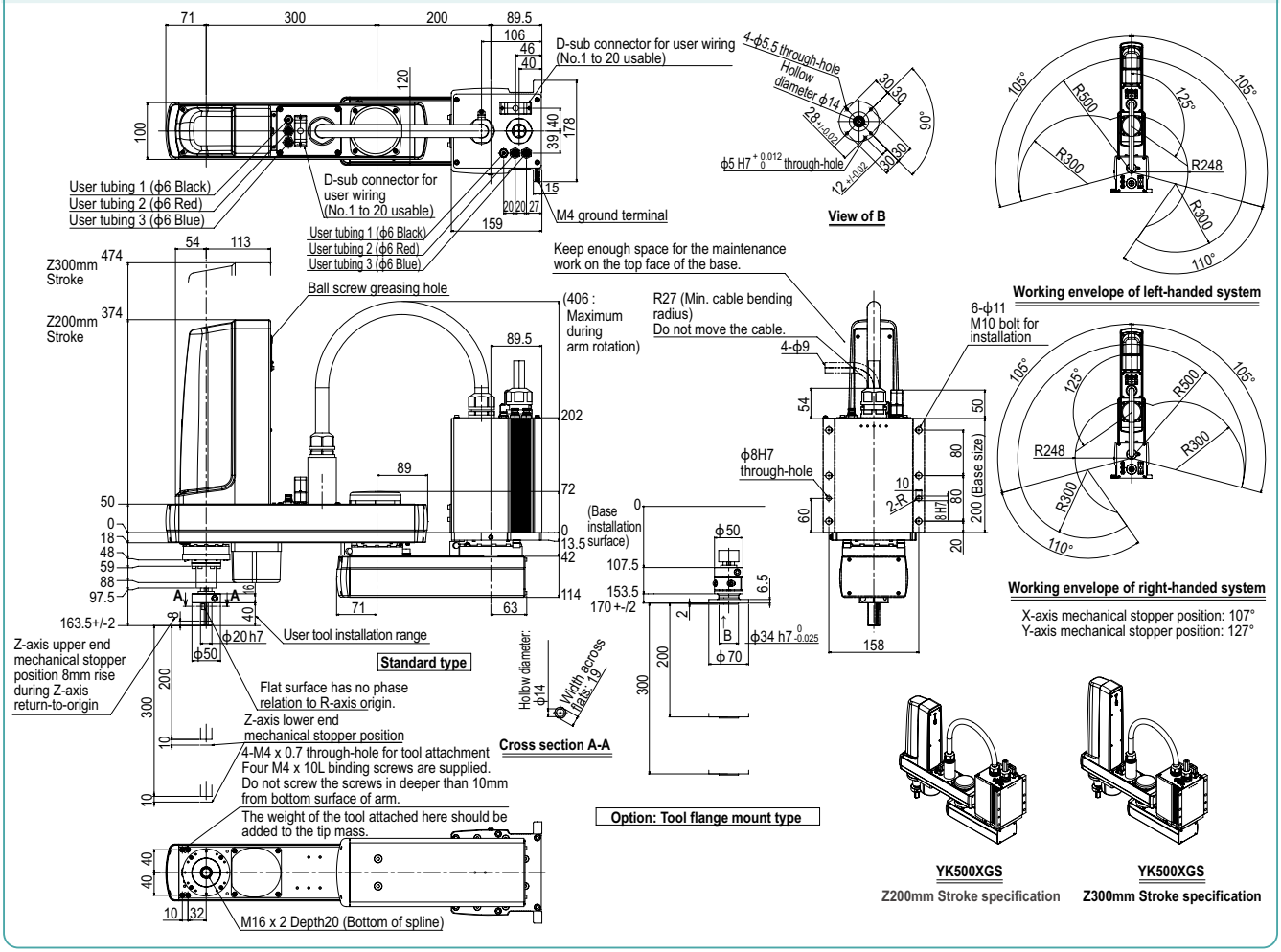
Controller

Controller	Power capacity (VA)	Operation method
RCX340	1700	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

YK500XGS



Controller RCX340 ▶ 636

YK600XGS

Wall mount / inverse type

- Arm length 600mm
- Maximum payload 10kg

Ordering method

YK600XGS - [ ] - [ ] - [ ] - [ ] - **RCX340-4** - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Installation method Note 1	Z axis stroke	Tool flange	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK600XGS	W: Wall mount (same as per external view) U: Inverse wall mount (upside down)	200: 200mm 300: 300mm	No entry: None F: With tool flange	3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Note 1. When installing the robot, always follow the specifications.
Do not install the ceiling-mount robot upside down or do not install the inverse type robot to a ceiling.
Incorrect installation can cause trouble or malfunction.

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		300 mm	300 mm	200 mm / 300 mm	–
	Rotation angle		+/-130 °	+/-145 °	–	+/-360 °
AC servo motor output			400 W	200 W	200 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			8.4 m/sec		2.3 m/sec / 1.7 m/sec	1700 °/sec (wall mount) / 800 °/sec (inverse wall mount)
Maximum payload			10 kg (Standard type), 9 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload Note 2			0.46 sec			
R-axis tolerable moment of inertia Note 3			0.30 kgm²			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			31 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

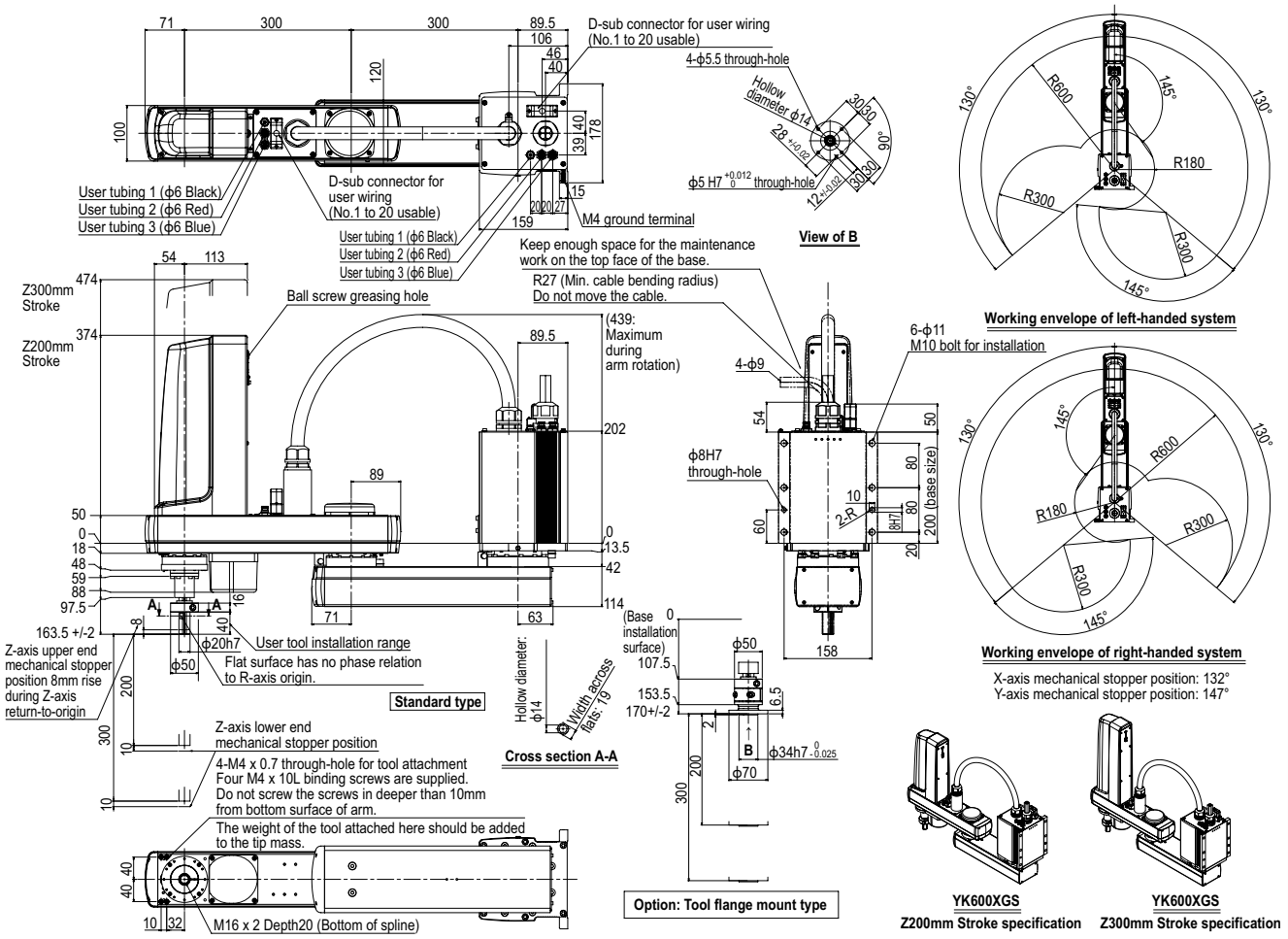
Controller

Controller	Power capacity (VA)	Operation method
RCX340	1700	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

YK600XGS



YK700XGS

Wall mount / inverse type

- Arm length 700mm
- Maximum payload 20kg

Ordering method

YK700XGS – [ ] – [ ] – [ ] – [ ] – RCX340-4 – [ ] – [ ] – [ ] – [ ] – [ ] – [ ] – [ ]

Model	Installation method Note 1	Z axis stroke	Tool flange	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK700XGS	W: Wall mount (same as per external view) U: Inverse wall mount (upside down)	200: 200mm 400: 400mm	No entry: None F: With tool flange	3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Note 1. When installing the robot, always follow the specifications.
Do not install the ceiling-mount robot upside down or do not install the inverse type robot to a ceiling.
Incorrect installation can cause trouble or malfunction.

Specifications

			X-axis	Y-axis	Z-axis		R-axis
Axis specifications	Arm length		300 mm	400 mm	200 mm	400 mm	–
	Rotation angle		+/-130 °	+/-130 °	–		+/-360 °
AC servo motor output			750 W	400 W	400 W		200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled				
		Speed reducer to output	Direct-coupled				
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm		+/-0.004 °
Maximum speed			8.4 m/sec		2.3 m/sec	1.7 m/sec	920 °/sec (wall mount) 480 °/sec (inverse wall mount)
Maximum payload			20 kg (Standard type), 19 kg (Tool flange mount type)				
Standard cycle time: with 2kg payload Note 2			0.42 sec				
R-axis tolerable moment of inertia Note 3			1.0 kgm²				
User wiring			0.2 sq × 20 wires				
User tubing (Outer diameter)			ϕ 6 × 3				
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)				
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m				
Weight			Z axis 200 mm: 50 kg Z axis 400 mm: 52 kg				

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

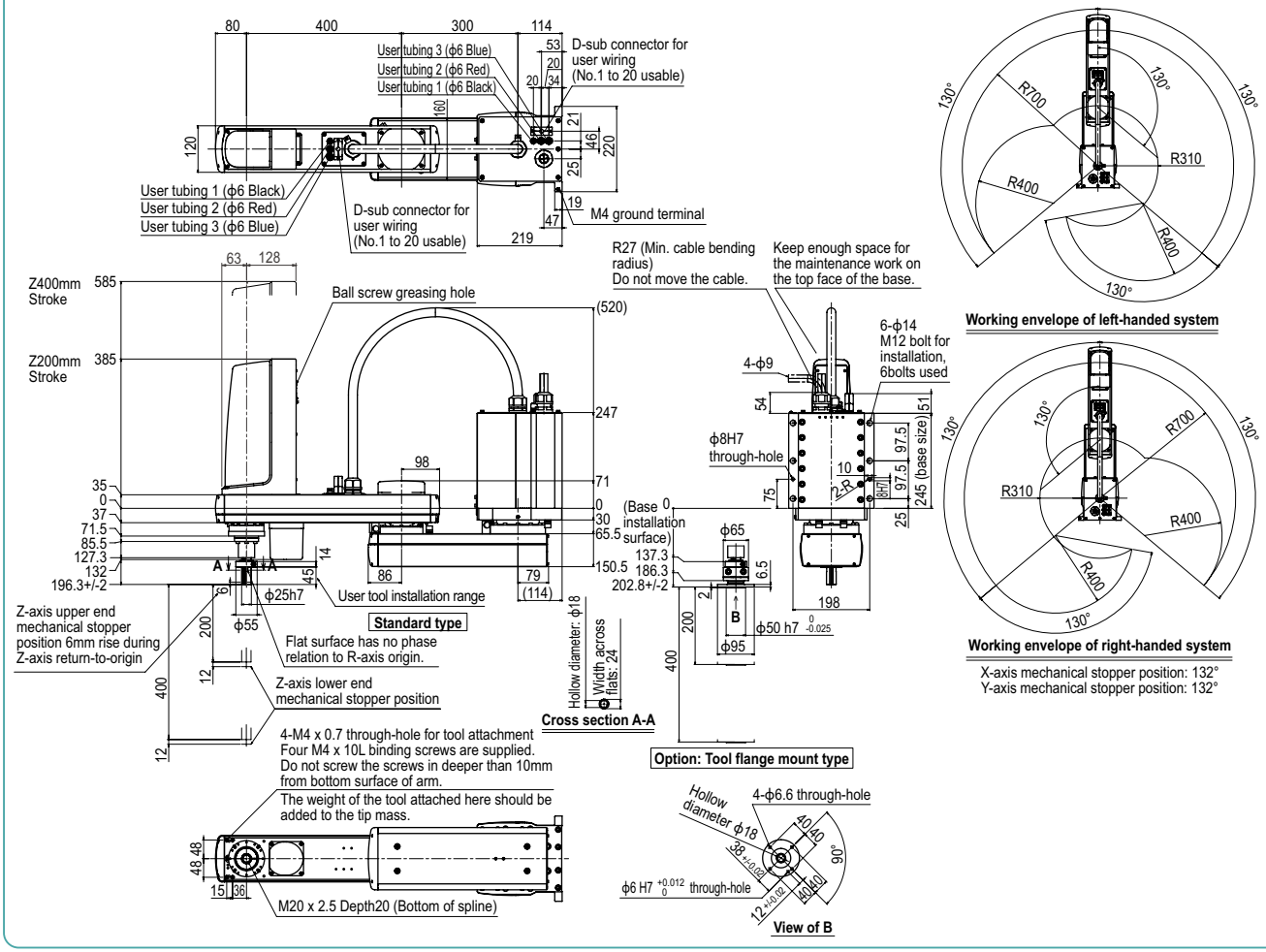
Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

YK700XGS



Controller RCX340 ▶ 636

YK800XGS

Wall mount / inverse type

- Arm length 800mm
- Maximum payload 20kg

Ordering method

YK800XGS – [ ] – [ ] – [ ] – [ ] – **RCX340-4** – [ ] – [ ] – [ ] – [ ] – [ ] – [ ] – [ ] – [ ]

Model	Installation method Note 1	Z axis stroke	Tool flange	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK800XGS	W: Wall mount (same as per external view) U: Inverse wall mount (upside down)	200: 200mm 400: 400mm	No entry: None F: With tool flange	3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Note 1. When installing the robot, always follow the specifications.
Do not install the ceiling-mount robot upside down or do not install the inverse type robot to a ceiling.
Incorrect installation can cause trouble or malfunction.

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		400 mm	400 mm	200 mm / 400 mm	–
	Rotation angle		+/-130 °	+/-145 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			9.2 m/sec		2.3 m/sec / 1.7 m/sec	920 °/sec (wall mount) / 480 °/sec (inverse wall mount)
Maximum payload			20 kg (Standard type), 19 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload Note 2			0.48 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm²			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			φ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 52 kg Z axis 400 mm: 54 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

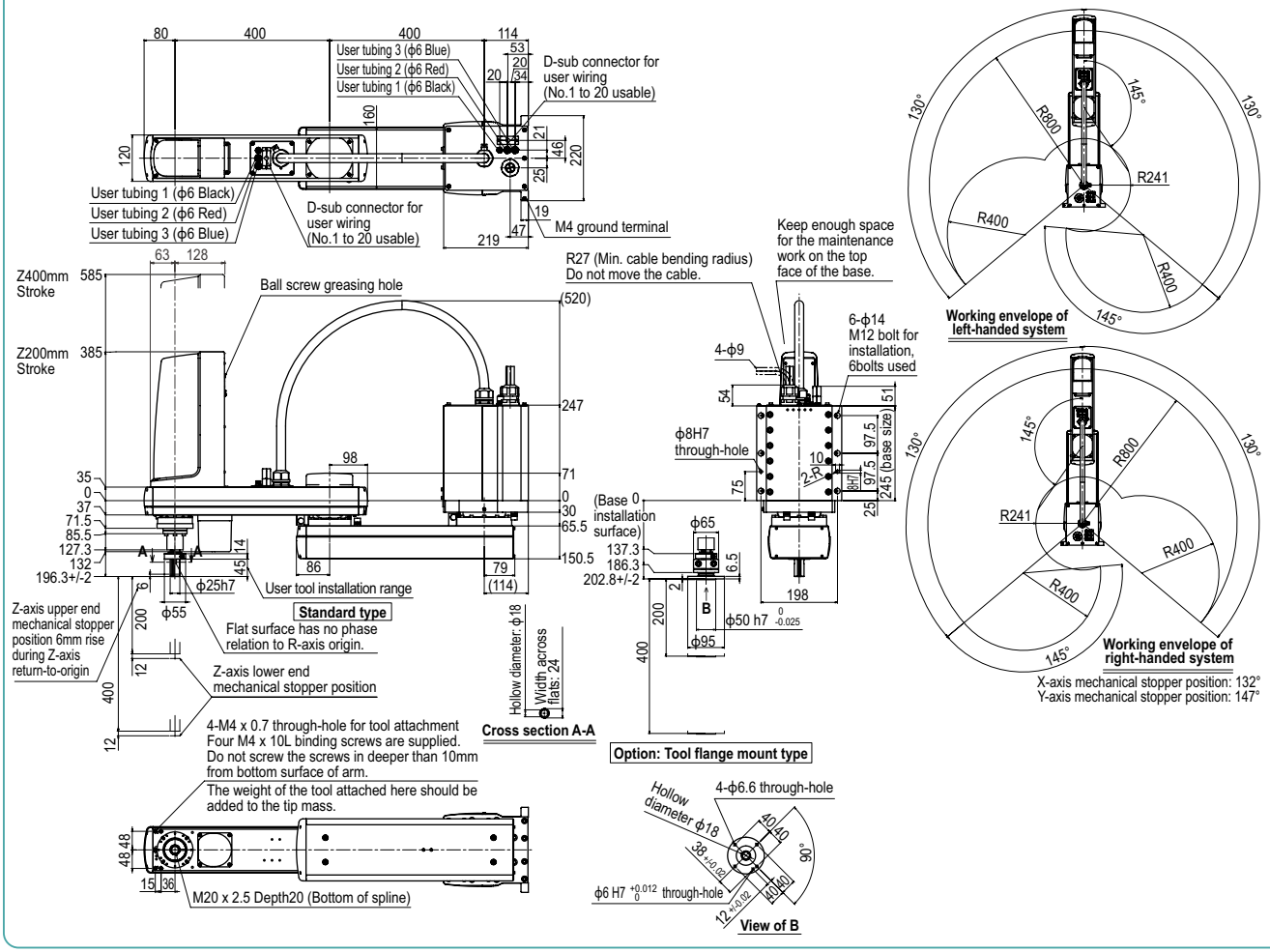
Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

YK800XGS



YK900XGS

Wall mount / inverse type

- Arm length 900mm
- Maximum payload 20kg

Ordering method

YK900XGS					RCX340-4							
Model	Installation method Note 1	Z axis stroke	Tool flange	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	W: Wall mount (same as per external view) U: Inverse wall mount (upside down)	200: 200mm 400: 400mm	No entry: None F: With tool flange	3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ P.636

Note 1. When installing the robot, always follow the specifications.
Do not install the ceiling-mount robot upside down or do not install the inverse type robot to a ceiling.
Incorrect installation can cause trouble or malfunction.

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		500 mm	400 mm	200 mm / 400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			9.9 m/sec		2.3 m/sec / 1.7 m/sec	920 °/sec (wall mount) / 480 °/sec (inverse wall mount)
Maximum payload			20 kg (Standard type), 19 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload Note 2			0.49 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm²			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 54 kg Z axis 400 mm: 56 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

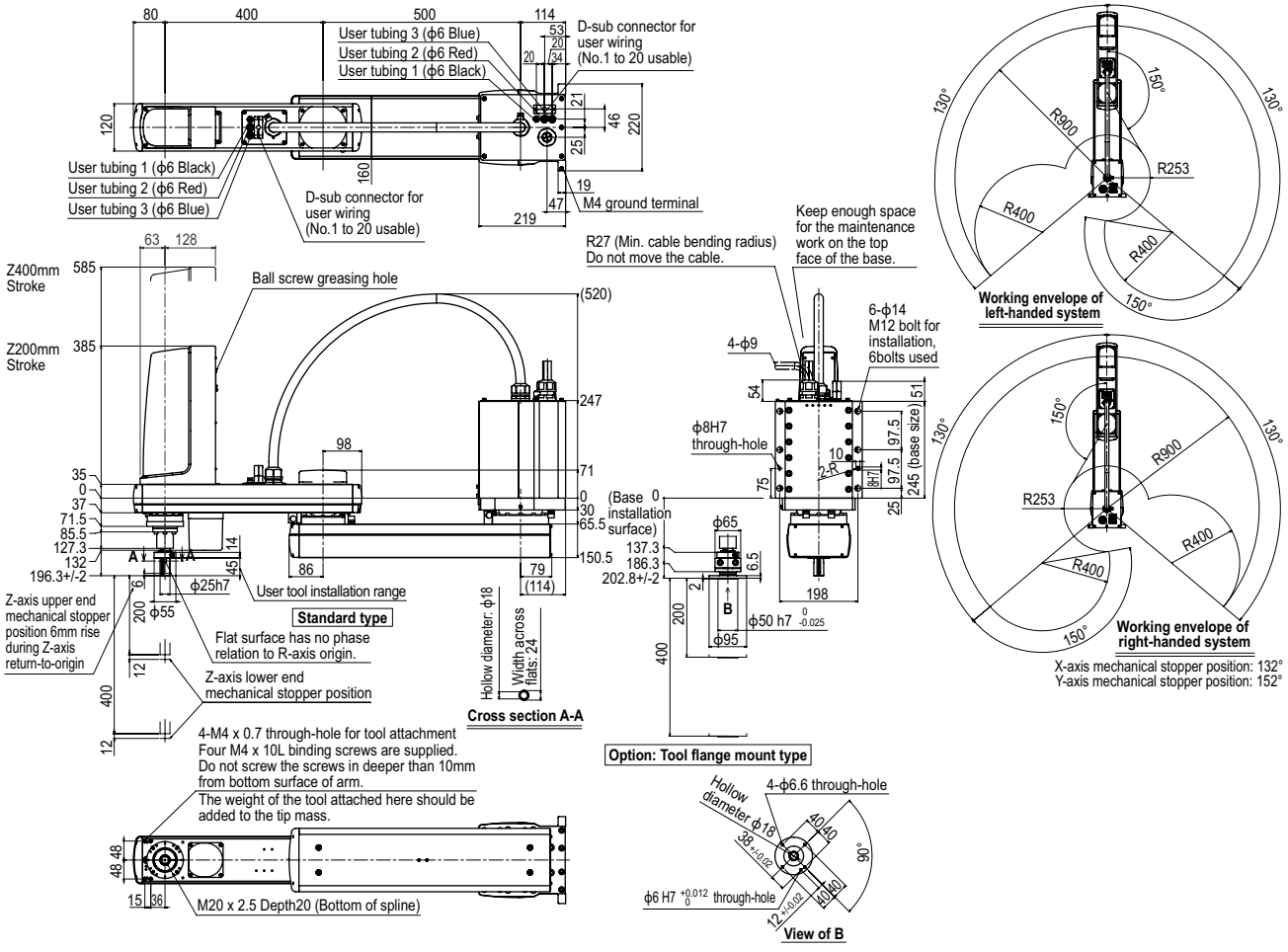
Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

YK900XGS



Controller RCX340 ▶ 636

YK1000XGS

Wall mount / inverse type

- Arm length 1000mm
- Maximum payload 20kg

Ordering method

YK1000XGS - [ ] - [ ] - [ ] - [ ] - **RCX340-4** - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Installation method Note 1	Z axis stroke	Tool flange	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	W: Wall mount (same as per external view) U: Inverse wall mount (upside down)	200: 200mm 400: 400mm	No entry: None F: With tool flange	3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ P.636

Note 1. When installing the robot, always follow the specifications.
Do not install the ceiling-mount robot upside down or do not install the inverse type robot to a ceiling.
Incorrect installation can cause trouble or malfunction.

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		600 mm	400 mm	200 mm / 400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			10.6 m/sec		2.3 m/sec / 1.7 m/sec	920 °/sec (wall mount) / 480 °/sec (inverse wall mount)
Maximum payload			20 kg (Standard type), 19 kg (Tool flange mount type)			
Standard cycle time: with 2kg payload Note 2			0.49 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm²			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 56 kg Z axis 400 mm: 58 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

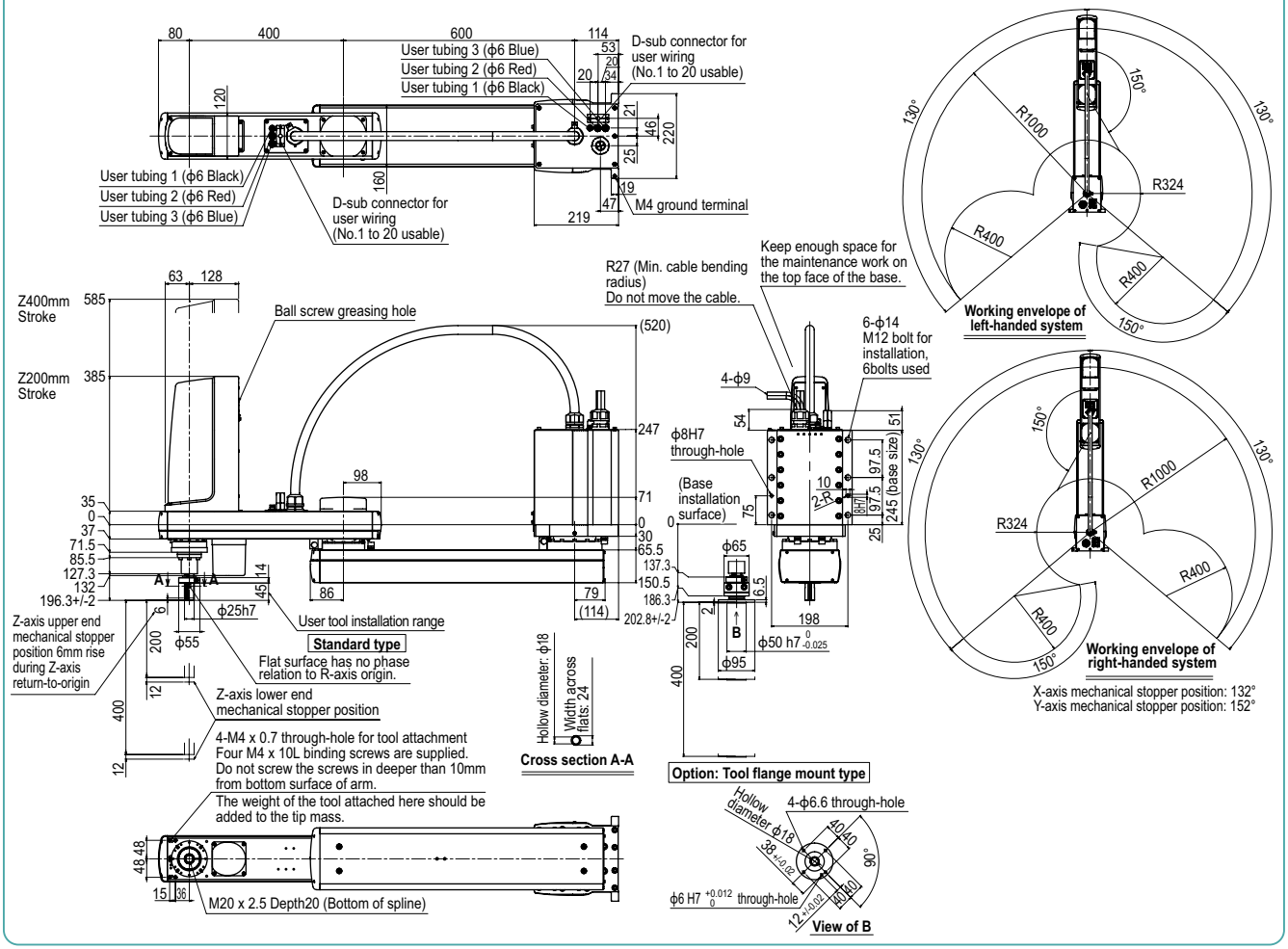
Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

YK1000XGS



YK250XGP

Dust-proof & drip-proof type

Arm length 250mm　Maximum payload 4kg

Ordering method

YK250XGP - 150 - [ ] - S - [ ] - RCX340-4 - [ ] [ ] [ ] [ ] [ ] [ ] [ ]

Model	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	150: 150mm	No entry: None F: With tool flange	S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		100 mm	150 mm	150 mm	–
	Rotation angle		+/-129 °	+/-134 °	–	+/-360 °
AC servo motor output			200 W	150 W	50 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			4.5 m/sec		1.1 m/sec	1020 °/sec
Maximum payload			4 kg			
Standard cycle time: with 2kg payload Note 2			0.50 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm^2			
Protection class Note 4			Equivalent to IP65 (IEC 60529)			
User wiring			0.2 sq × 10 wires			
User tubing (Outer diameter)			ϕ 4 × 4			
Travel limit			1.Soft limit　2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m　Option: 5 m, 10 m			
Weight			21.5 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

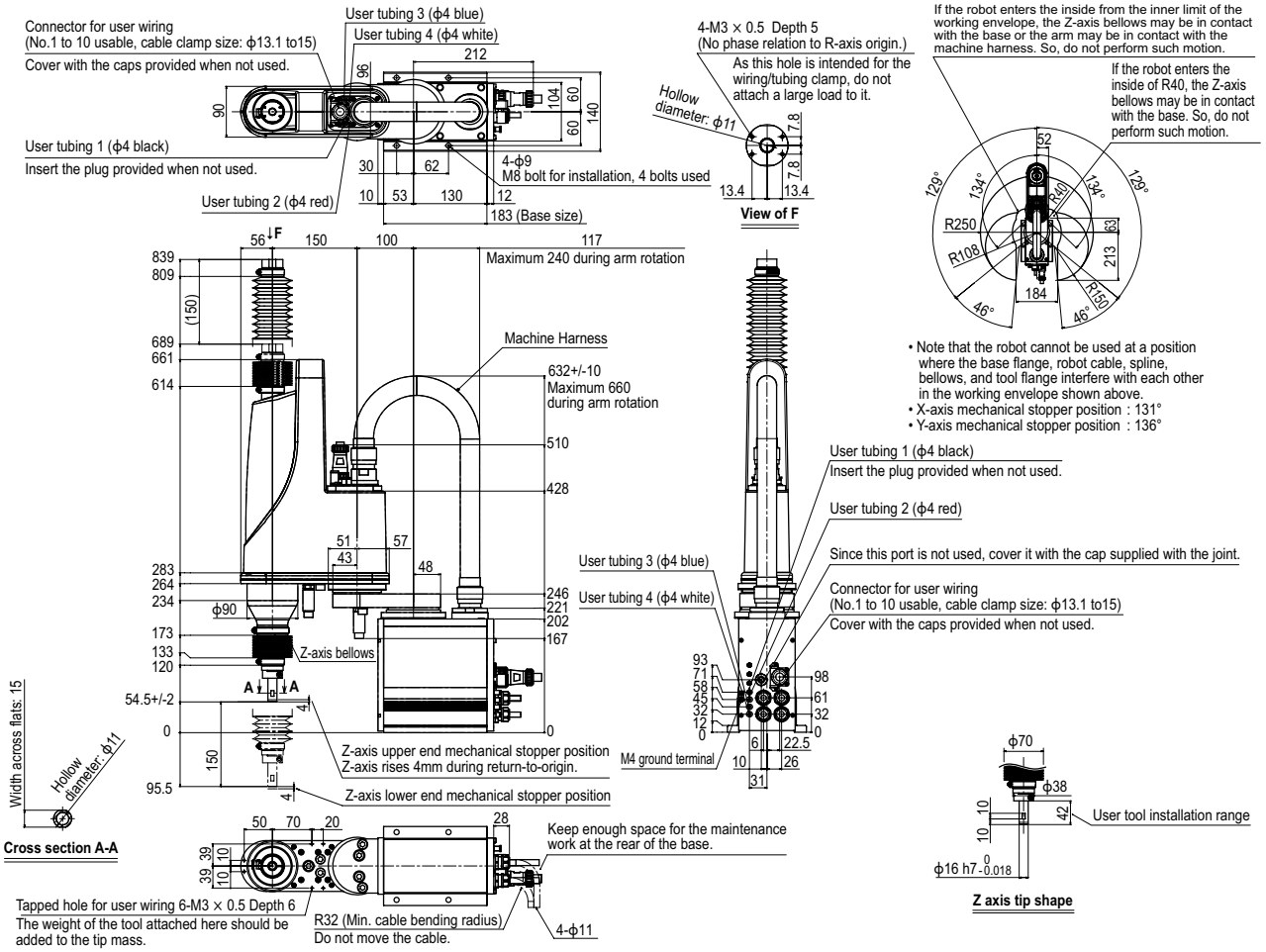
Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

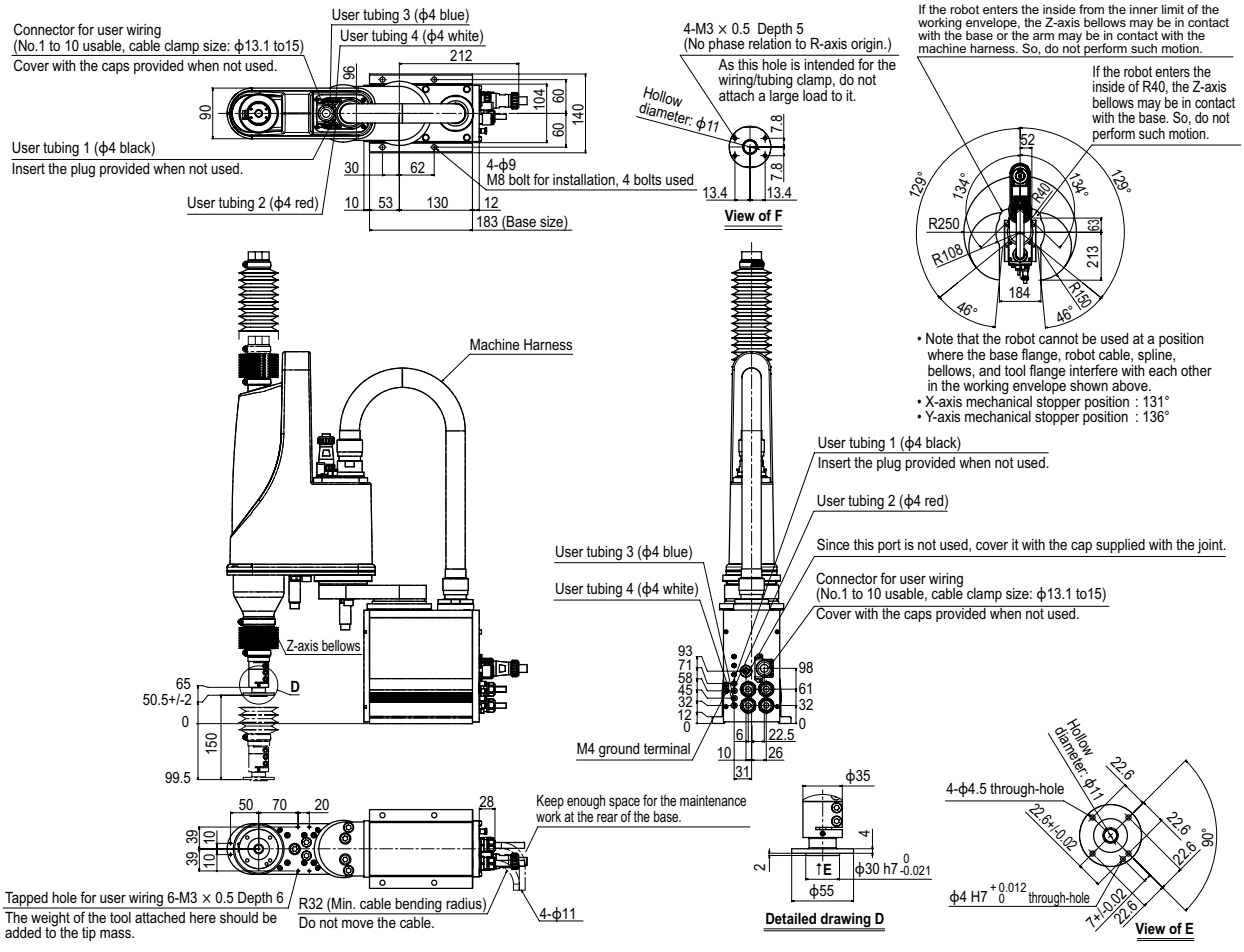
YK250XGP



Controller　RCX340 ▶ 636

YK250XGP

YK250XGP Tool flange mount type



YK350XGP

Dust-proof & drip-proof type

- Arm length 350mm
- Maximum payload 4kg

Ordering method

YK350XGP - 150 - [ ] - S - [ ] - RCX340-4 - [ ] [ ] [ ] [ ] [ ] [ ] [ ]

Model	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK350XGP	150: 150mm	No entry: None F: With tool flange	S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		200 mm	150 mm	150 mm	–
	Rotation angle		+/-129 °	+/-134 °	–	+/-360 °
AC servo motor output			200 W	150 W	50 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			5.6 m/sec		1.1 m/sec	1020 °/sec
Maximum payload			4 kg			
Standard cycle time: with 2kg payload Note 2			0.52 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm^2			
Protection class Note 4			Equivalent to IP65 (IEC 60529)			
User wiring			0.2 sq × 10 wires			
User tubing (Outer diameter)			ϕ 4 × 4			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			22 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.) See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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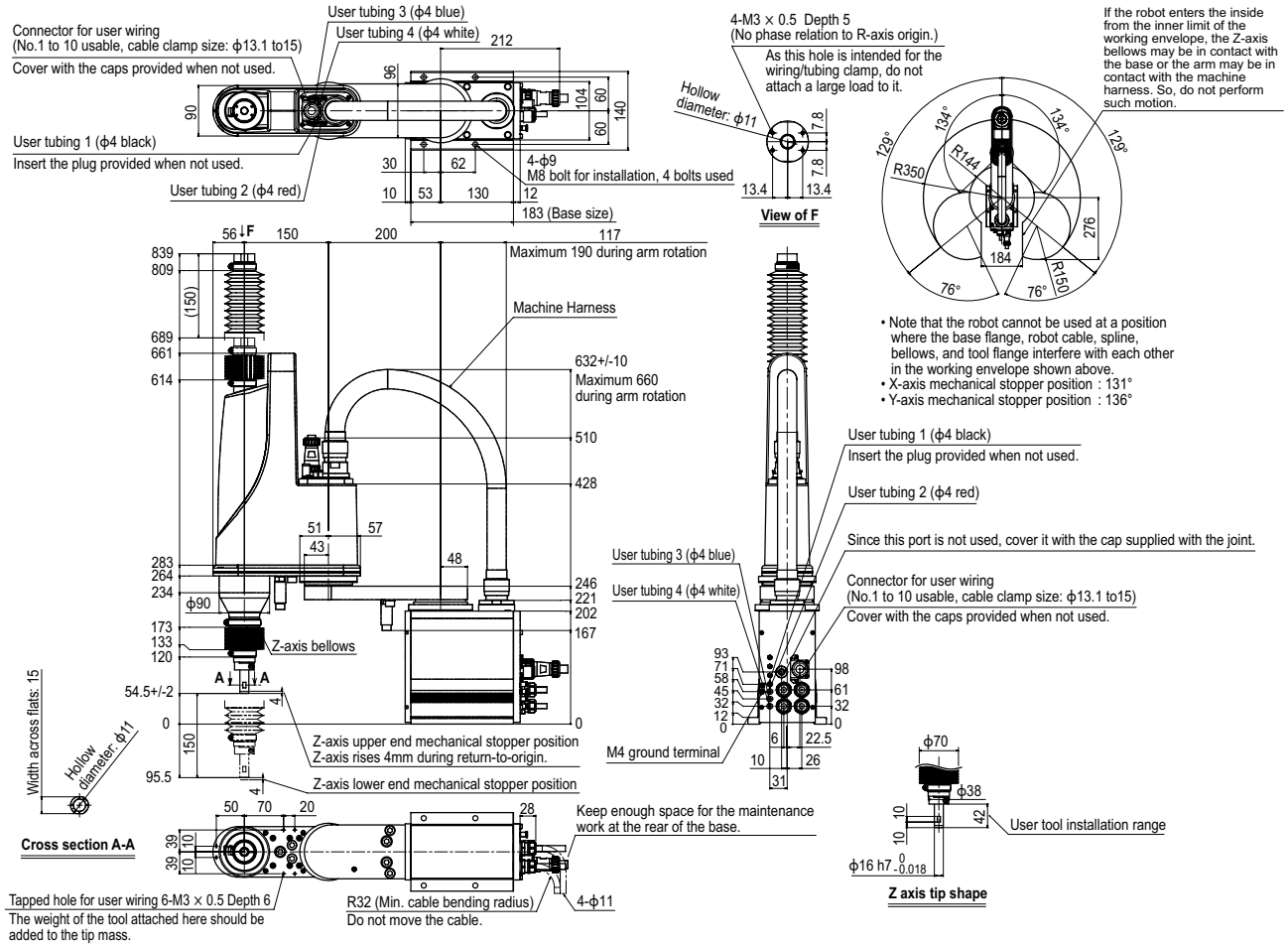
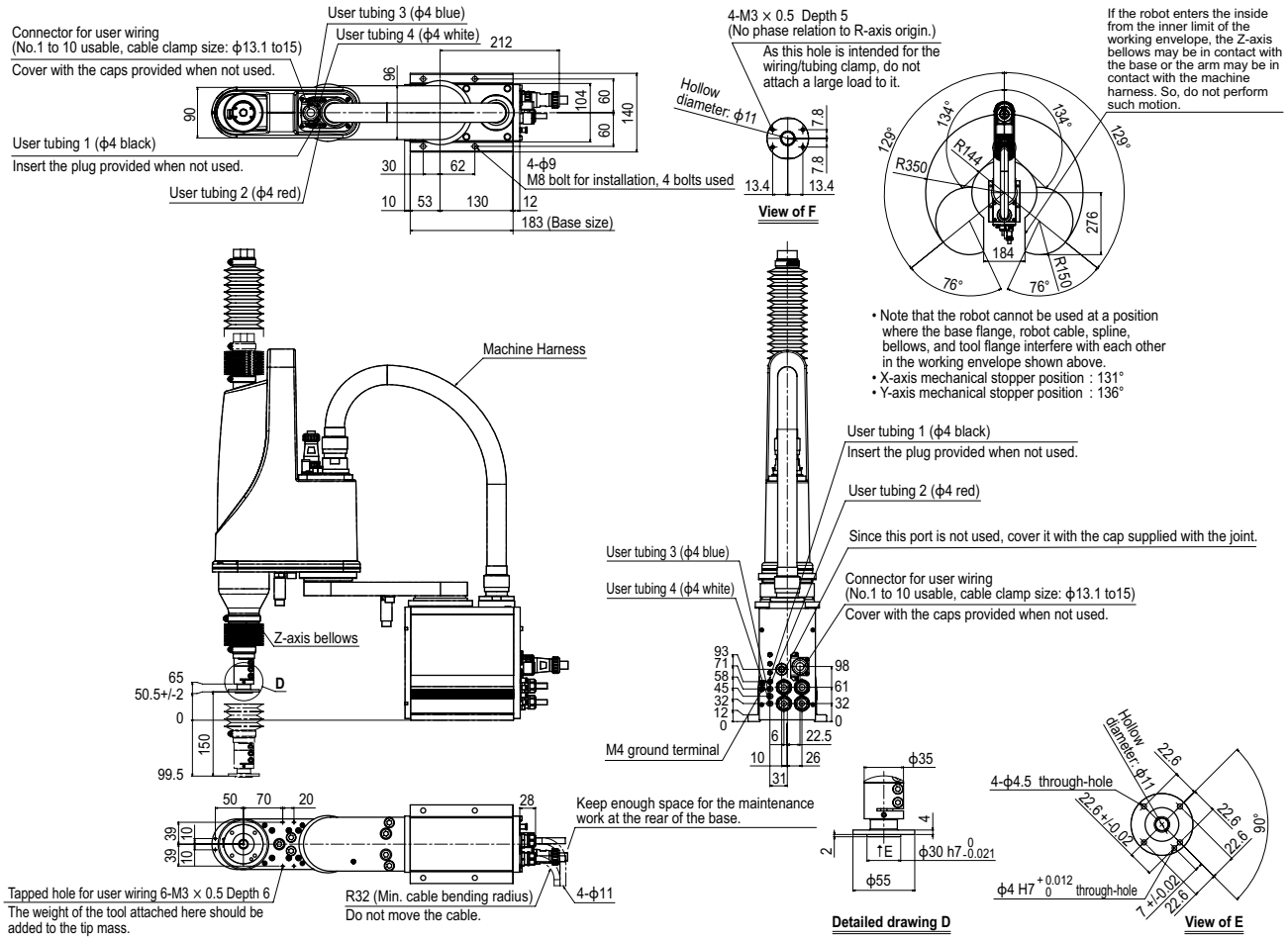
YK350XGP



YK350XGP Tool flange mount type



YK400XGP

Dust-proof & drip-proof type

- Arm length 400mm
- Maximum payload 4kg

Ordering method

YK400XGP	- 150	-	- S	-	- RCX340-4	-	-	-	-	-	-	-
Model	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
	150: 150mm	No entry: None F: With tool flange	S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		250 mm	150 mm	150 mm	–
	Rotation angle		+/-129 °	+/-144 °	–	+/-360 °
AC servo motor output			200 W	150 W	50 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			6.1 m/sec		1.1 m/sec	1020 °/sec
Maximum payload			4 kg			
Standard cycle time: with 2kg payload Note 2			0.50 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm^2			
Protection class Note 4			Equivalent to IP65 (IEC 60529)			
User wiring			0.2 sq × 10 wires			
User tubing (Outer diameter)			ϕ 4 × 4			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			22.5 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.) See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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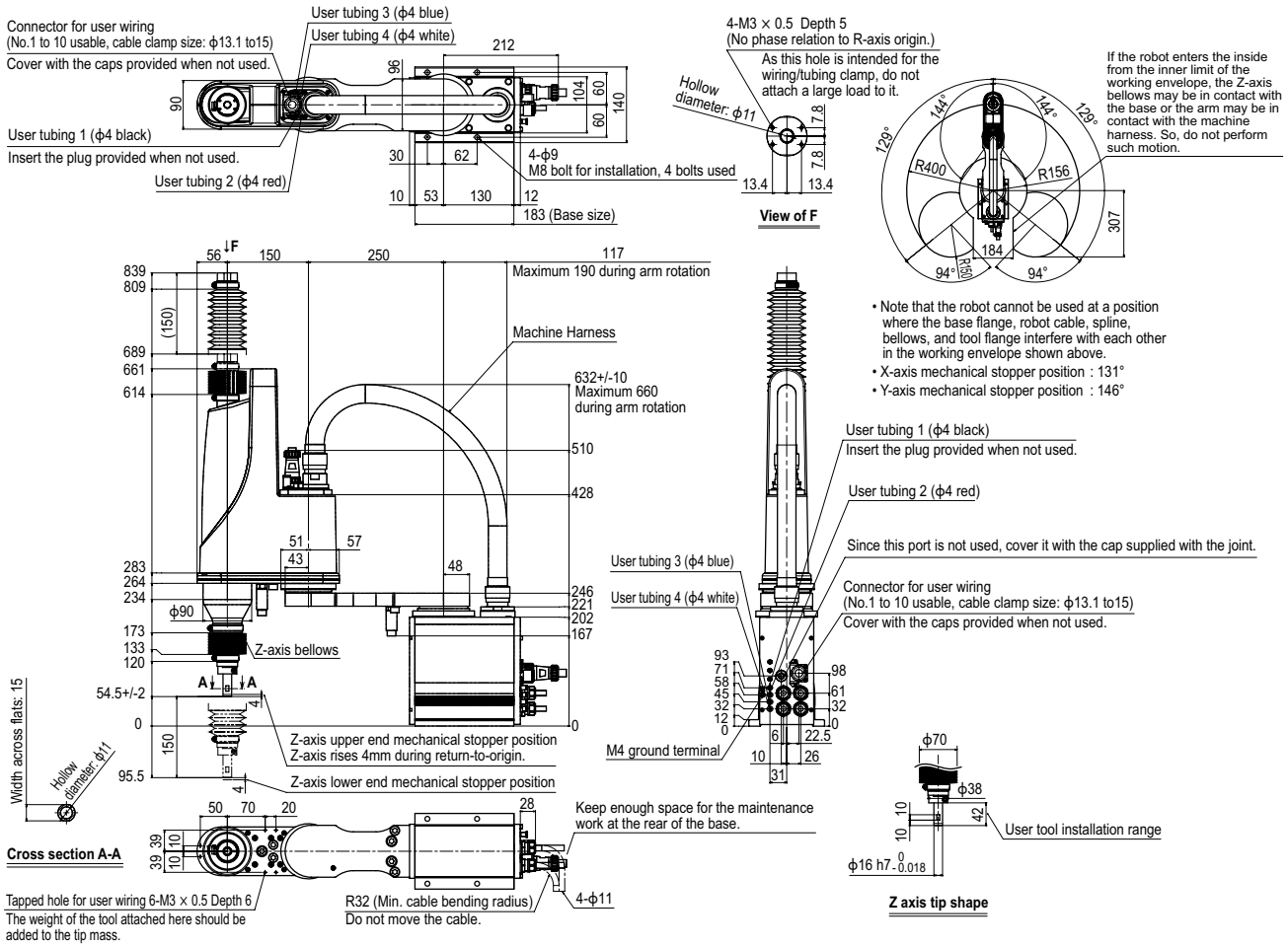
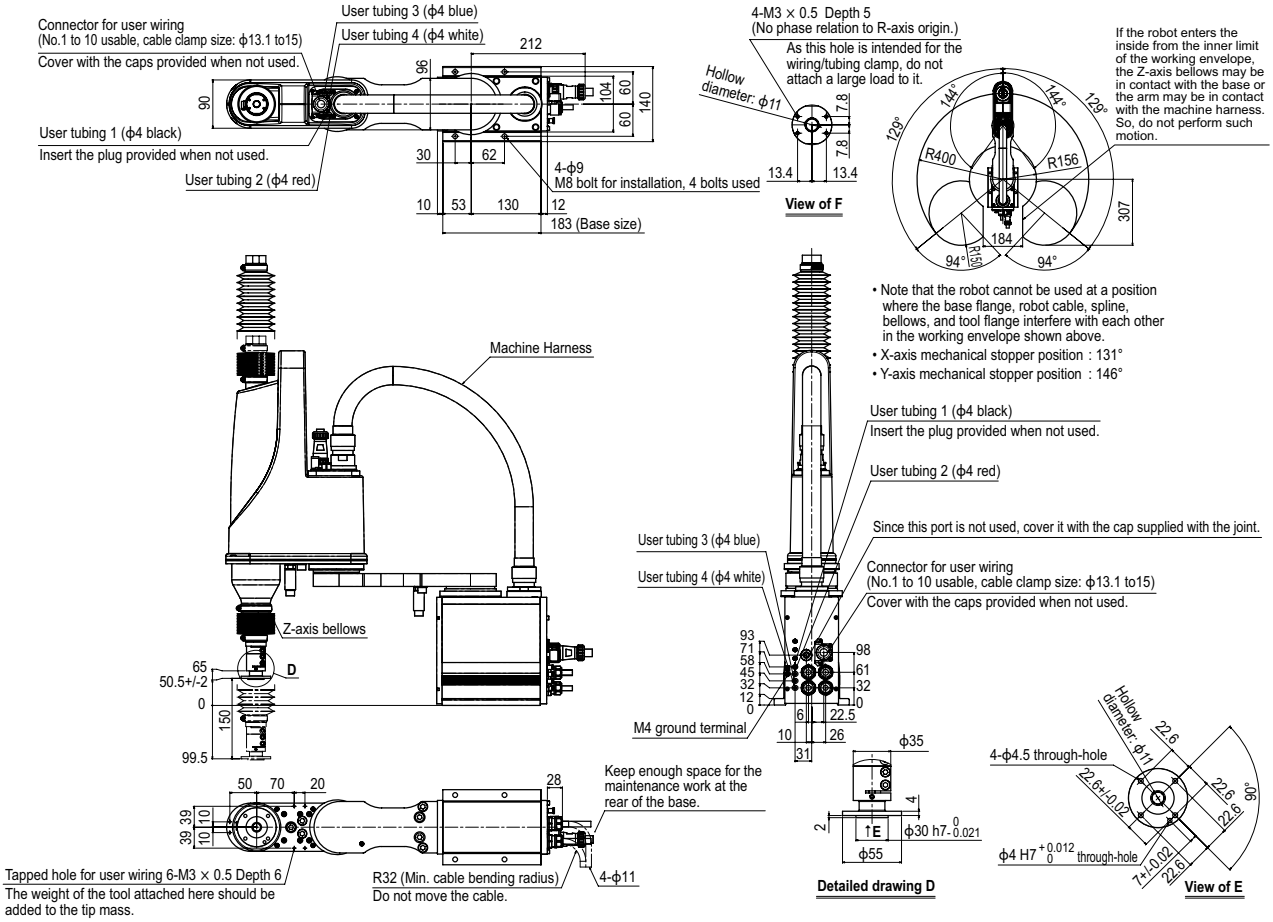
YK400XGP



Controller RCX340 ▶ 636

YK400XGP

YK400XGP Tool flange mount type



YK500XGLP

Dust-proof & drip-proof type

- Arm length 500mm
- Maximum payload 4kg

Ordering method

YK500XGLP - 150 -		- S -		- RCX340-4 -							
Model	Z axis stroke 150: 150mm	Tool flange No entry: None F: With tool flange	Hollow shaft S: With hollow shaft	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		250 mm	250 mm	150 mm	–
	Rotation angle		+/-129 °	+/-144 °	–	+/-360 °
AC servo motor output			200 W	150 W	50 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			5.1 m/sec		1.1 m/sec	1020 °/sec
Maximum payload			4 kg			
Standard cycle time: with 2kg payload Note 2			0.66 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm^2			
Protection class Note 4			Equivalent to IP65 (IEC 60529)			
User wiring			0.2 sq × 10 wires			
User tubing (Outer diameter)			ϕ 4 × 4			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			25 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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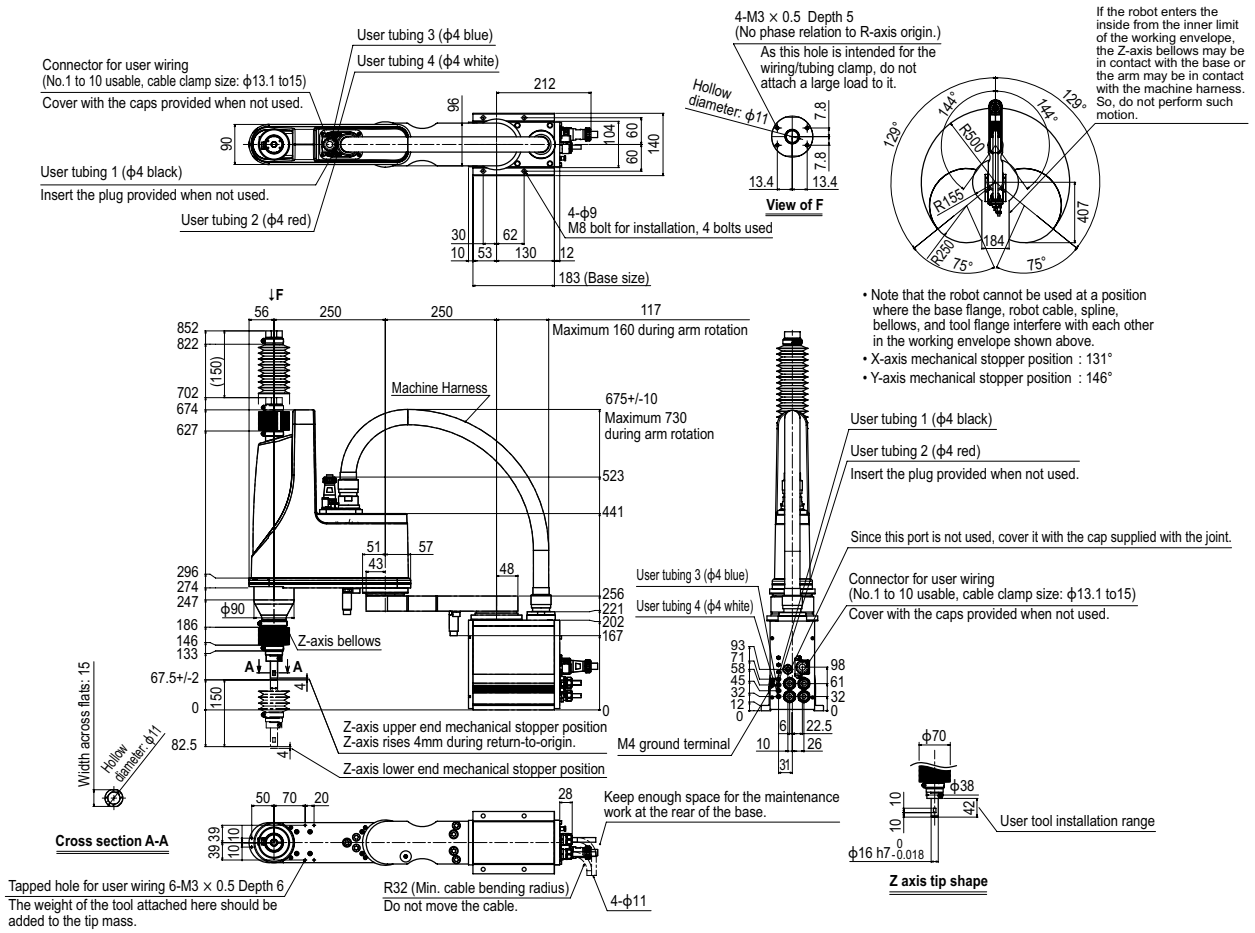
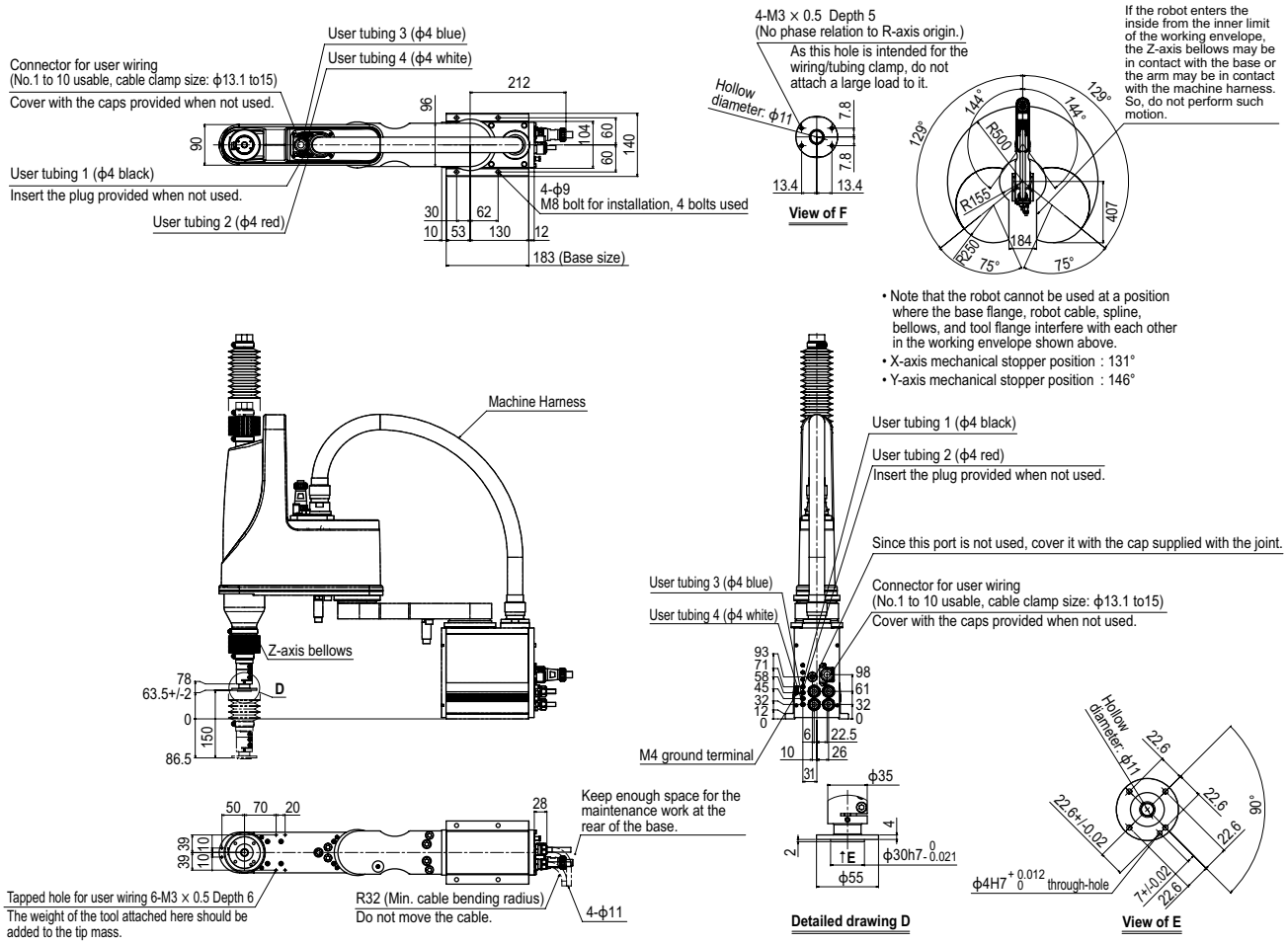
YK500XGLP



Controller RCX340 ▶ 636

YK500XGLP Tool flange mount type



YK500XGP

Dust-proof & drip-proof type

Arm length 500mm　Maximum payload 10kg

Ordering method

YK500XGP		F		RCX340-4							
Model	Z axis stroke 200: 200mm 300: 300mm	Tool flange F: With tool flange	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		200 mm	300 mm	200 mm / 300 mm	–
	Rotation angle		+/-130 °	+/-145 °	–	+/-360 °
AC servo motor output			400 W	200 W	200 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			7.6 m/sec		2.3 m/sec / 1.7 m/sec	1700 °/sec
Maximum payload			10 kg			
Standard cycle time: with 2kg payload Note 2			0.55 sec			
R-axis tolerable moment of inertia Note 3			0.3 kgm^2			
Protection class Note 4			Equivalent to IP65 (IEC 60529)			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit　2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m　Option: 5 m, 10 m			
Weight			Z axis 200 mm: 32 kg　Z axis 300 mm: 33 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1700	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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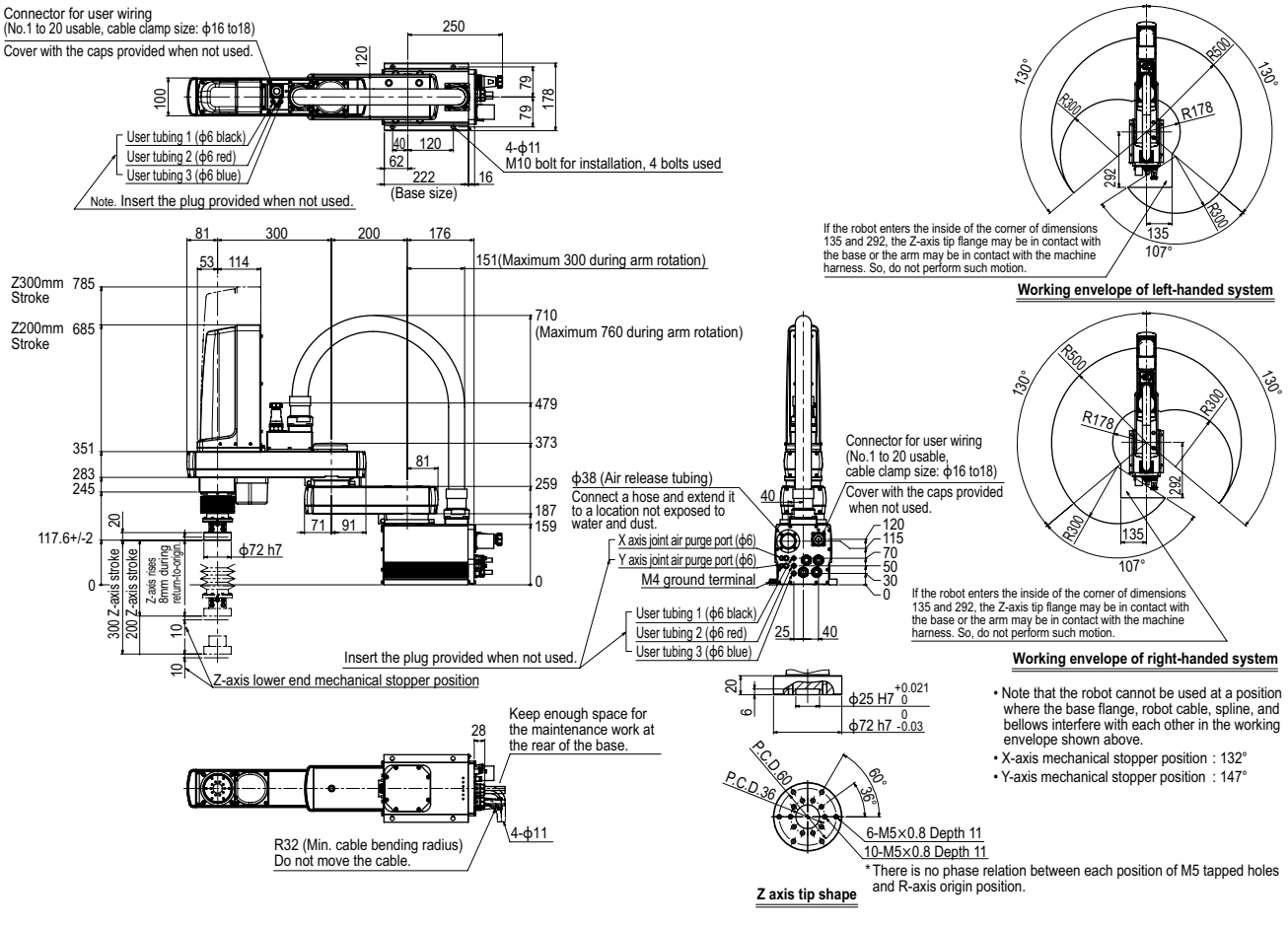
YK500XGP



Controller　RCX340 ▶ 636

YK600XGLP

Dust-proof & drip-proof type

- Arm length 600mm
- Maximum payload 4kg

Ordering method

YK600XGLP - 150 - [ ] - S - [ ] - RCX340-4 - [ ] - [ ] - [ ] - [ ] - [ ] - [ ] - [ ]

Model	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
YK600XGLP	150: 150mm	No entry: None F: With tool flange	S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m	RCX340-4							

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		350 mm	250 mm	150 mm	–
	Rotation angle		+/-129 °	+/-144 °	–	+/-360 °
AC servo motor output			200 W	150 W	50 W	100 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			4.9 m/sec		1.1 m/sec	1020 °/sec
Maximum payload			4 kg			
Standard cycle time: with 2kg payload Note 2			0.71 sec			
R-axis tolerable moment of inertia Note 3			0.05 kgm^2			
Protection class Note 4			Equivalent to IP65 (IEC 60529)			
User wiring (sq × wires)			0.2 × 10			
User tubing (Outer diameter)			ϕ 4 × 4			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			26 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.) See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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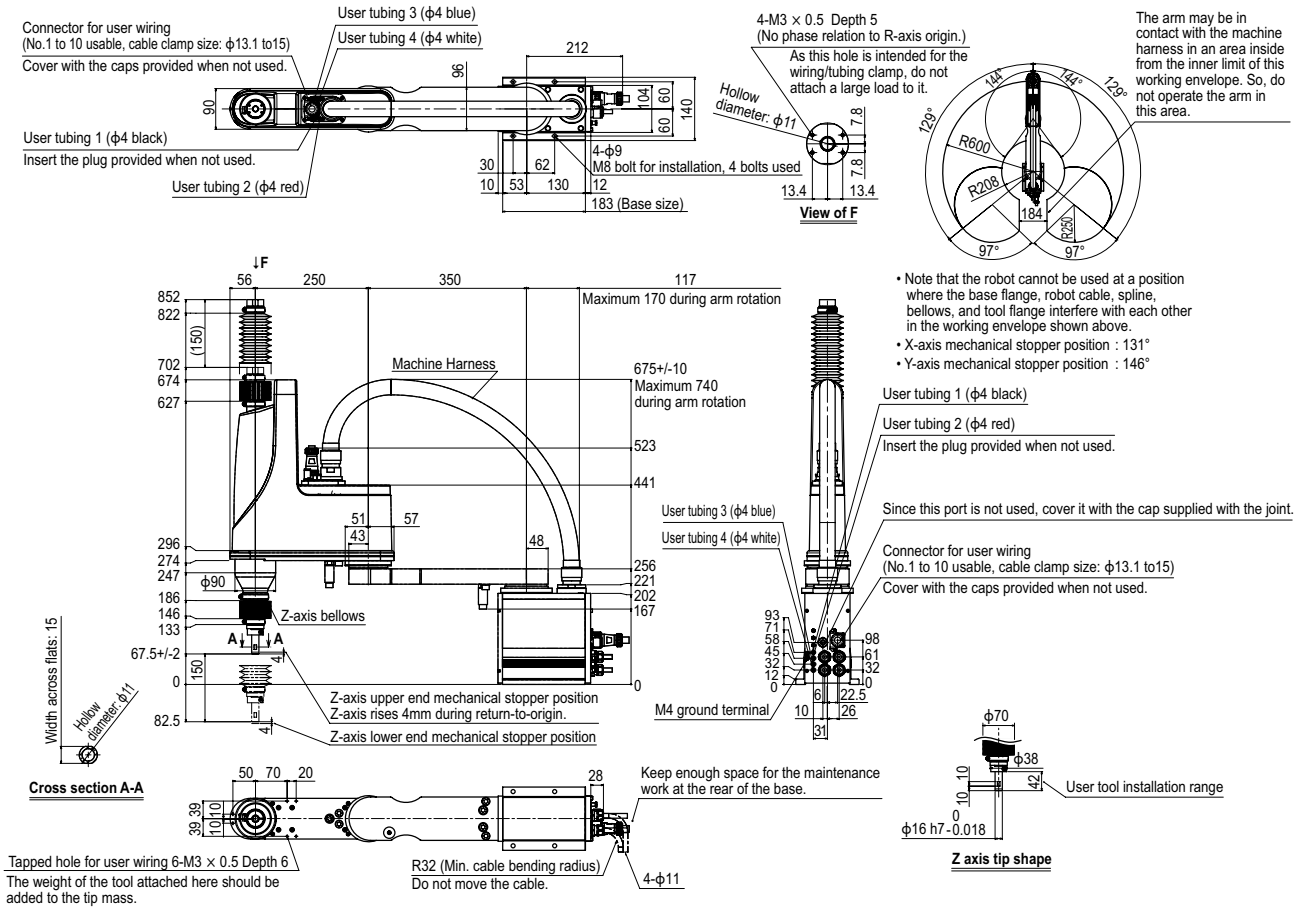
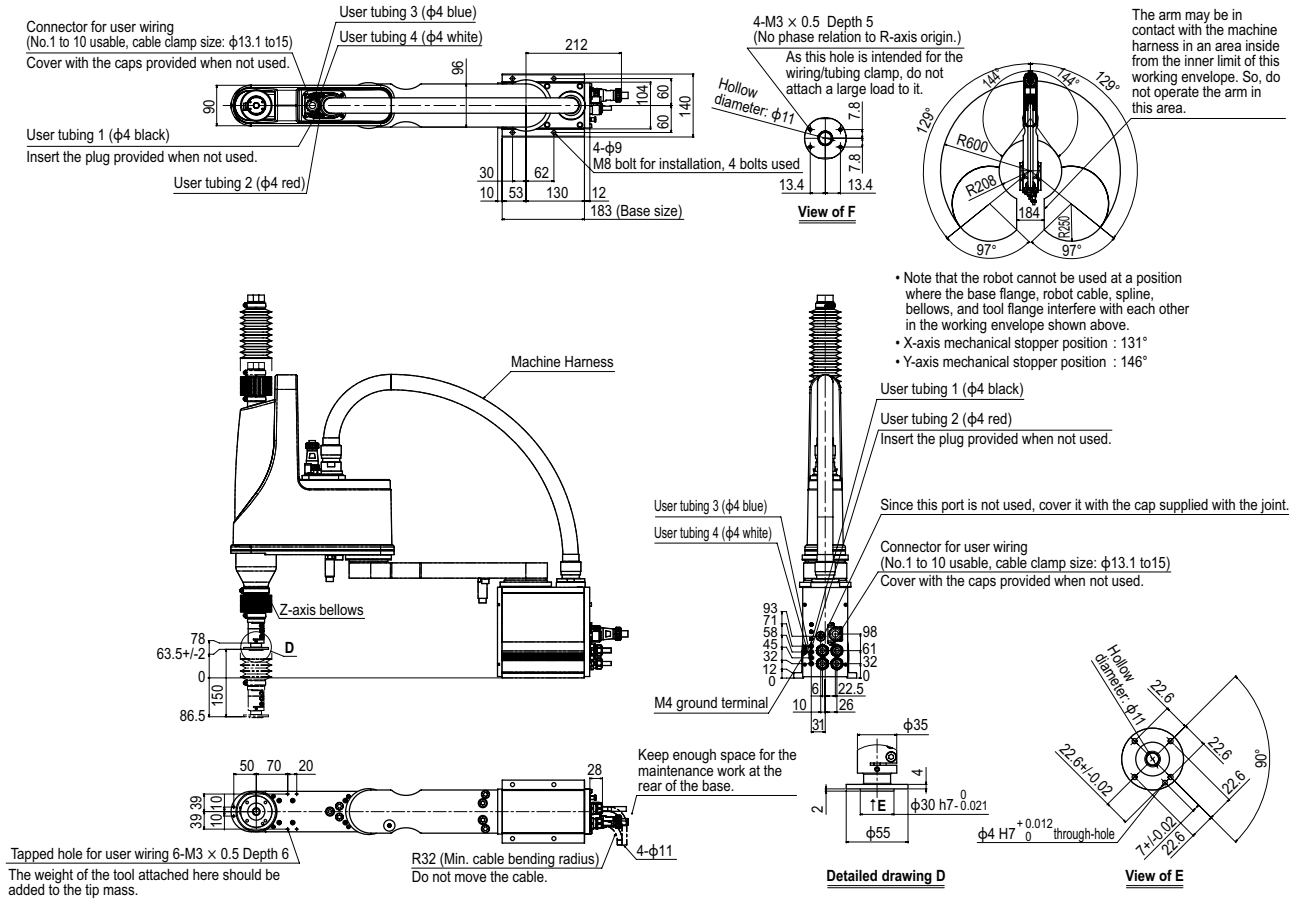
YK600XGLP



YK600XGLP Tool flange mount type



YK600XGP

Dust-proof & drip-proof type

Arm length 600mm **Maximum payload 10kg**

Ordering method

YK600XGP		F		RCX340-4							
Model	Z axis stroke 200: 200mm 300: 300mm	Tool flange F: With tool flange	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		300 mm	300 mm	200 mm / 300 mm	–
	Rotation angle		+/-130 °	+/-145 °	–	+/-360 °
AC servo motor output			400 W	200 W	200 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			8.4 m/sec		2.3 m/sec / 1.7 m/sec	1700 °/sec
Maximum payload			10 kg			
Standard cycle time: with 2kg payload Note 2			0.56 sec			
R-axis tolerable moment of inertia Note 3			0.3 kgm²			
Protection class Note 4			Equivalent to IP65 (IEC 60529)			
User wiring (sq × wires)			0.2 × 20			
User tubing (Outer diameter)			φ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 33 kg Z axis 300 mm: 34 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1700	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.) See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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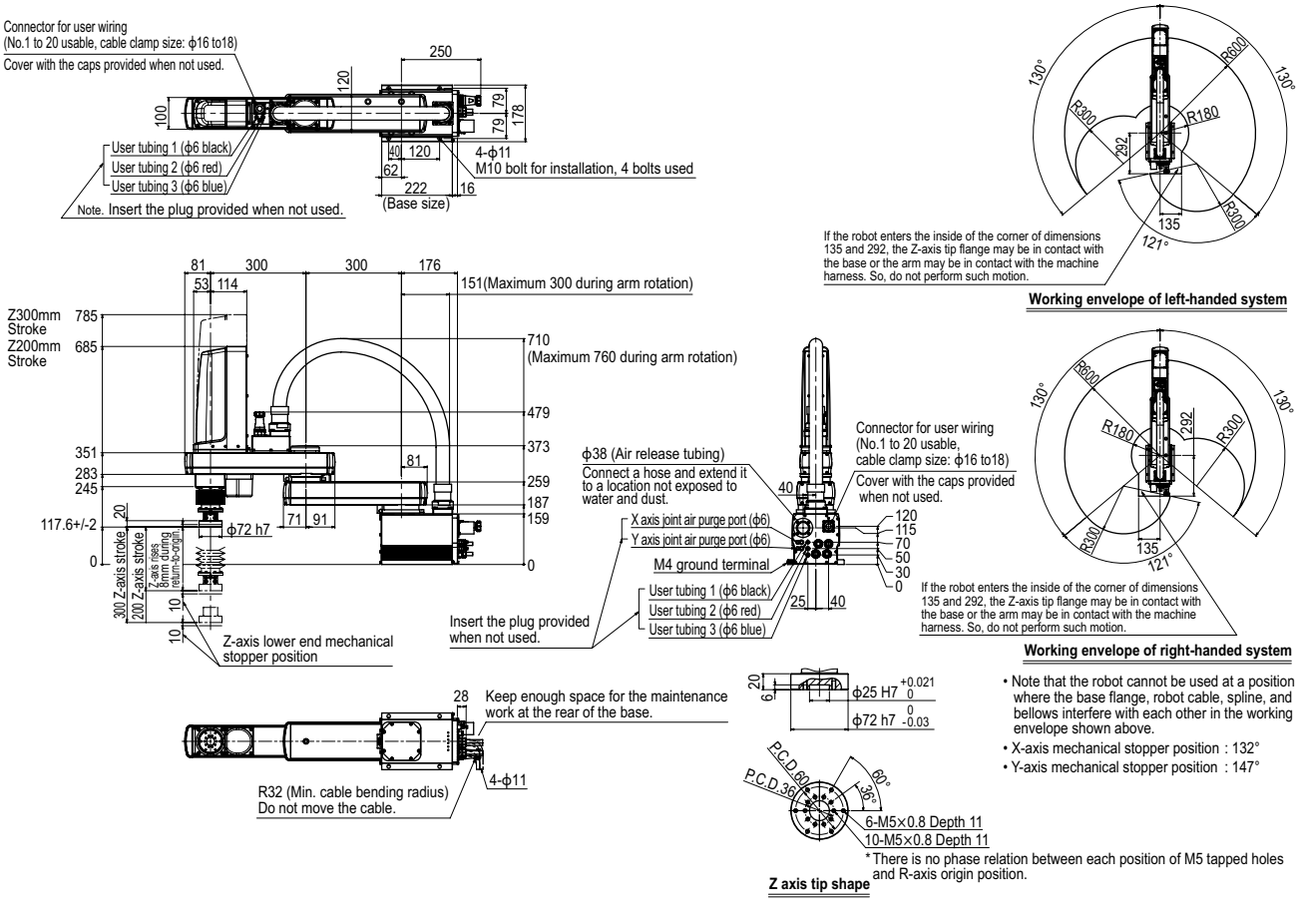
YK600XGP



- Note that the robot cannot be used at a position where the base flange, robot cable, spline, and bellows interfere with each other in the working envelope shown above.
- X-axis mechanical stopper position : 132°
- Y-axis mechanical stopper position : 147°

YK600XGHP

Dust-proof & drip-proof type

- Arm length 600mm
- Maximum payload 20kg

Ordering method

YK600XGHP		F		RCX340-4							
Model	Z axis stroke 200: 200mm 400: 400mm	Tool flange F: With tool flange	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		200 mm	400 mm	200 mm / 400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			7.7 m/sec		2.3 m/sec / 1.7 m/sec	920 °/sec
Maximum payload			20 kg			
Standard cycle time: with 2kg payload Note 2			0.57 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm^2			
Protection class Note 4			Equivalent to IP65 (IEC 60529)			
User wiring (sq × wires)			0.2 × 20			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 52 kg Z axis 400 mm: 54 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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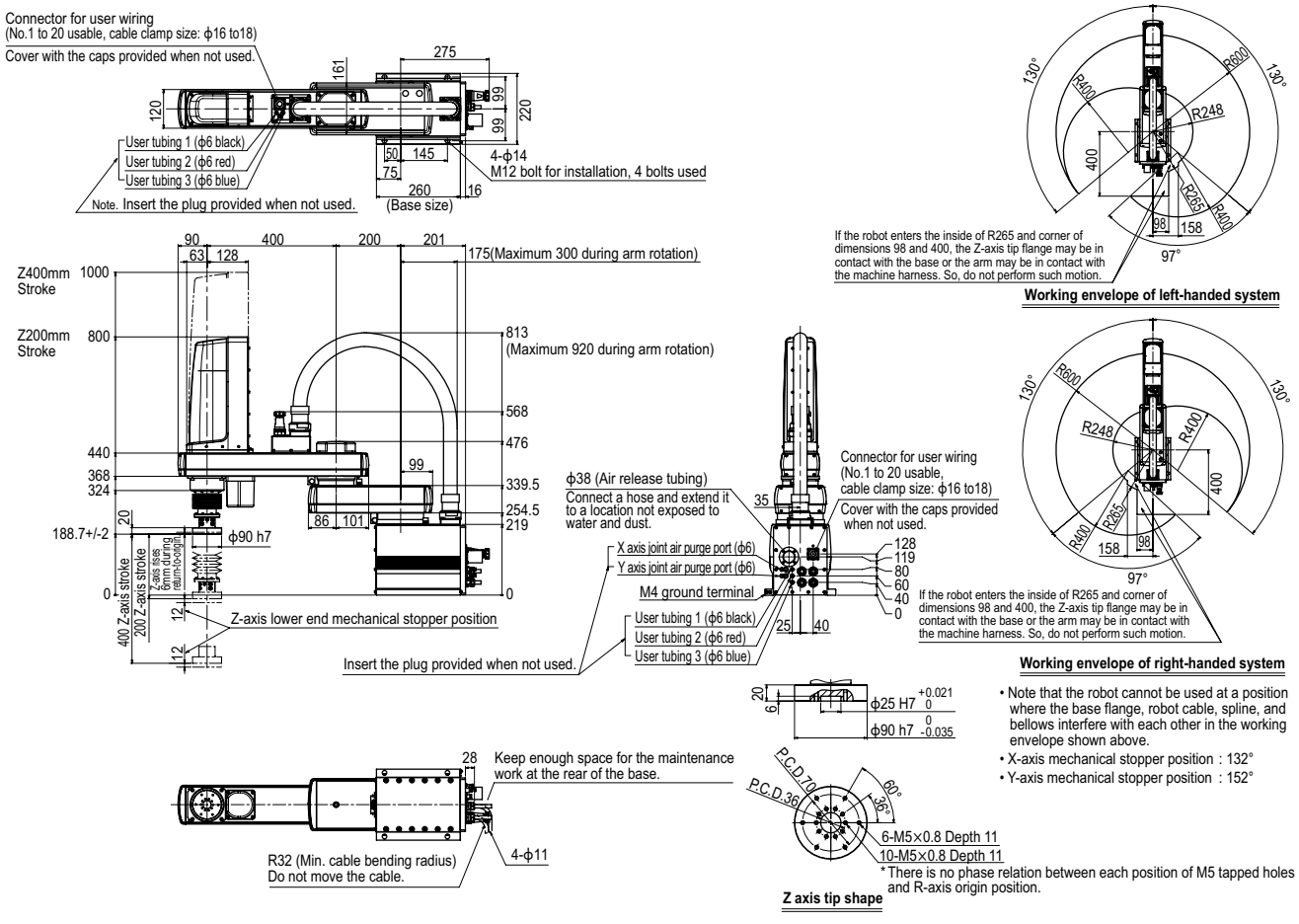
YK600XGHP



- Note that the robot cannot be used at a position where the base flange, robot cable, spline, and bellows interfere with each other in the working envelope shown above.
- X-axis mechanical stopper position : 132°
- Y-axis mechanical stopper position : 152°

Controller RCX340 ▶ 636

YK700XGP

Dust-proof & drip-proof type

- Arm length 700mm
- Maximum payload 20kg

Ordering method

YK700XGP -		F	-	RCX340-4							
Model	Z axis stroke 200: 200mm 400: 400mm	Tool flange F: With tool flange	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		300 mm	400 mm	200 mm / 400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			8.4 m/sec		2.3 m/sec / 1.7 m/sec	920 °/sec
Maximum payload			20 kg			
Standard cycle time: with 2kg payload Note 2			0.52 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm²			
Protection class Note 4			Equivalent to IP65 (IEC 60529)			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			φ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 54 kg Z axis 400 mm: 56 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.) See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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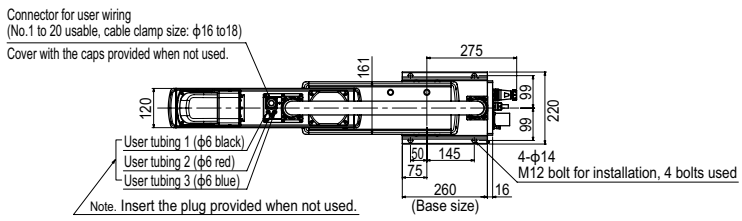
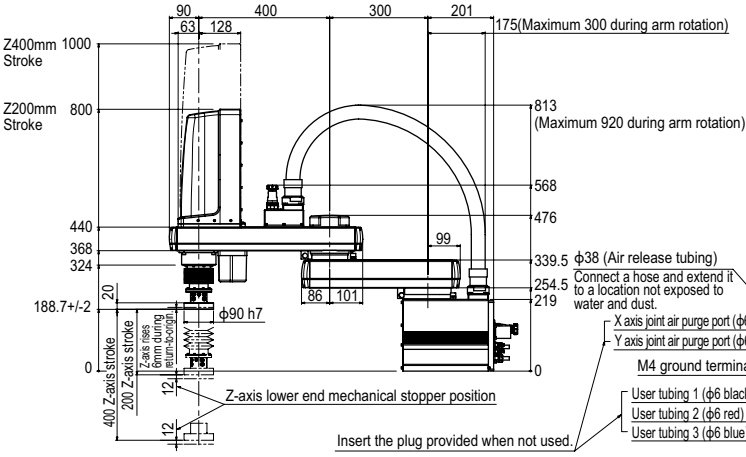
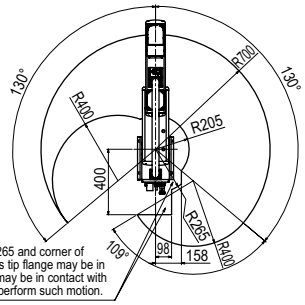
YK700XGP

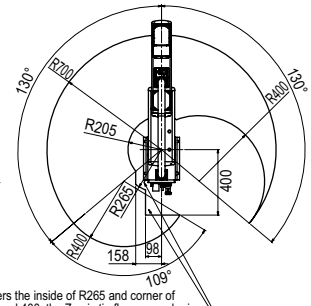






If the robot enters the inside of R265 and corner of dimensions 98 and 400, the Z-axis tip flange may be in contact with the base or the arm may be in contact with the machine harness. So, do not perform such motion.

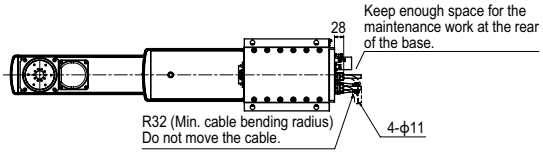
Working envelope of left-handed system

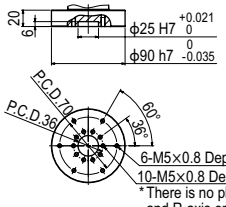


If the robot enters the inside of R265 and corner of dimensions 98 and 400, the Z-axis tip flange may be in contact with the base or the arm may be in contact with the machine harness. So, do not perform such motion.

Working envelope of right-handed system

- Note that the robot cannot be used at a position where the base flange, robot cable, spline, and bellows interfere with each other in the working envelope shown above.
- X-axis mechanical stopper position : 132°
- Y-axis mechanical stopper position : 152°





Z axis tip shape

* There is no phase relation between each position of M5 tapped holes and R-axis origin position.

YK800XGP

Dust-proof & drip-proof type

- Arm length 800mm
- Maximum payload 20kg

Ordering method

YK800XGP -		- F -		- RCX340-4 -							
Model	Z axis stroke 200: 200mm 400: 400mm	Tool flange F: With tool flange	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		400 mm	400 mm	200 mm / 400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			9.2 m/sec		2.3 m/sec / 1.7 m/sec	920 °/sec
Maximum payload			20 kg			
Standard cycle time: with 2kg payload Note 2			0.58 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm^2			
Protection class Note 4			Equivalent to IP65 (IEC 60529)			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 56 kg Z axis 400 mm: 58 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

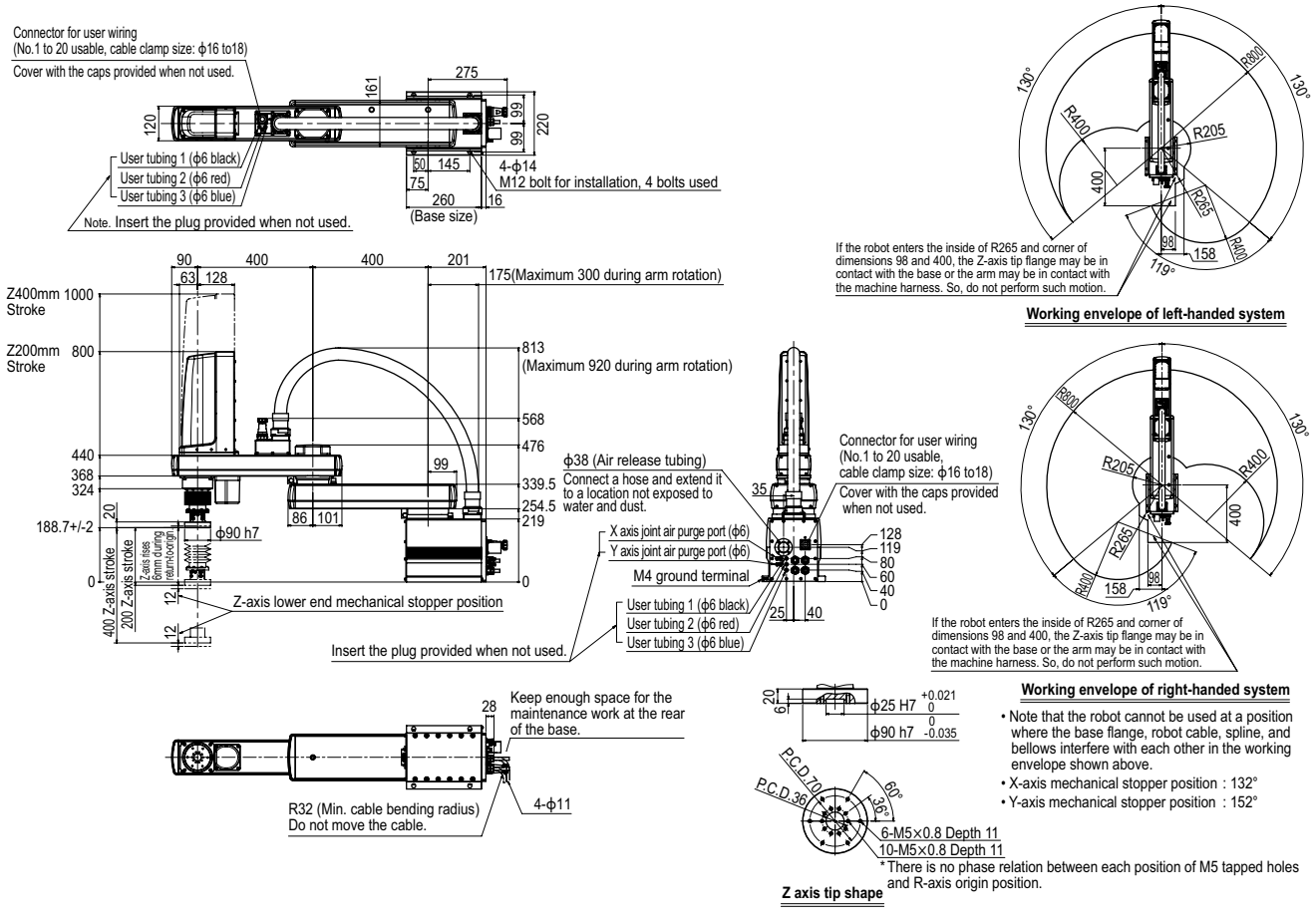
Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

YK800XGP



Controller RCX340 ▶ 636

YK900XGP

Dust-proof & drip-proof type

Arm length 900mm **Maximum payload 20kg**

Ordering method

YK900XGP -		F	-		-	RCX340-4								
Model	Z axis stroke 200: 200mm 400: 400mm	Tool flange F: With tool flange	Cable 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		500 mm	400 mm	200 mm / 400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			9.9 m/sec		2.3 m/sec / 1.7 m/sec	920 °/sec
Maximum payload			20 kg			
Standard cycle time: with 2kg payload Note 2			0.59 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm²			
Protection class Note 4			Equivalent to IP65 (IEC 60529)			
User wiring (sq × wires)			0.2 × 20			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 58 kg Z axis 400 mm: 60 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.) See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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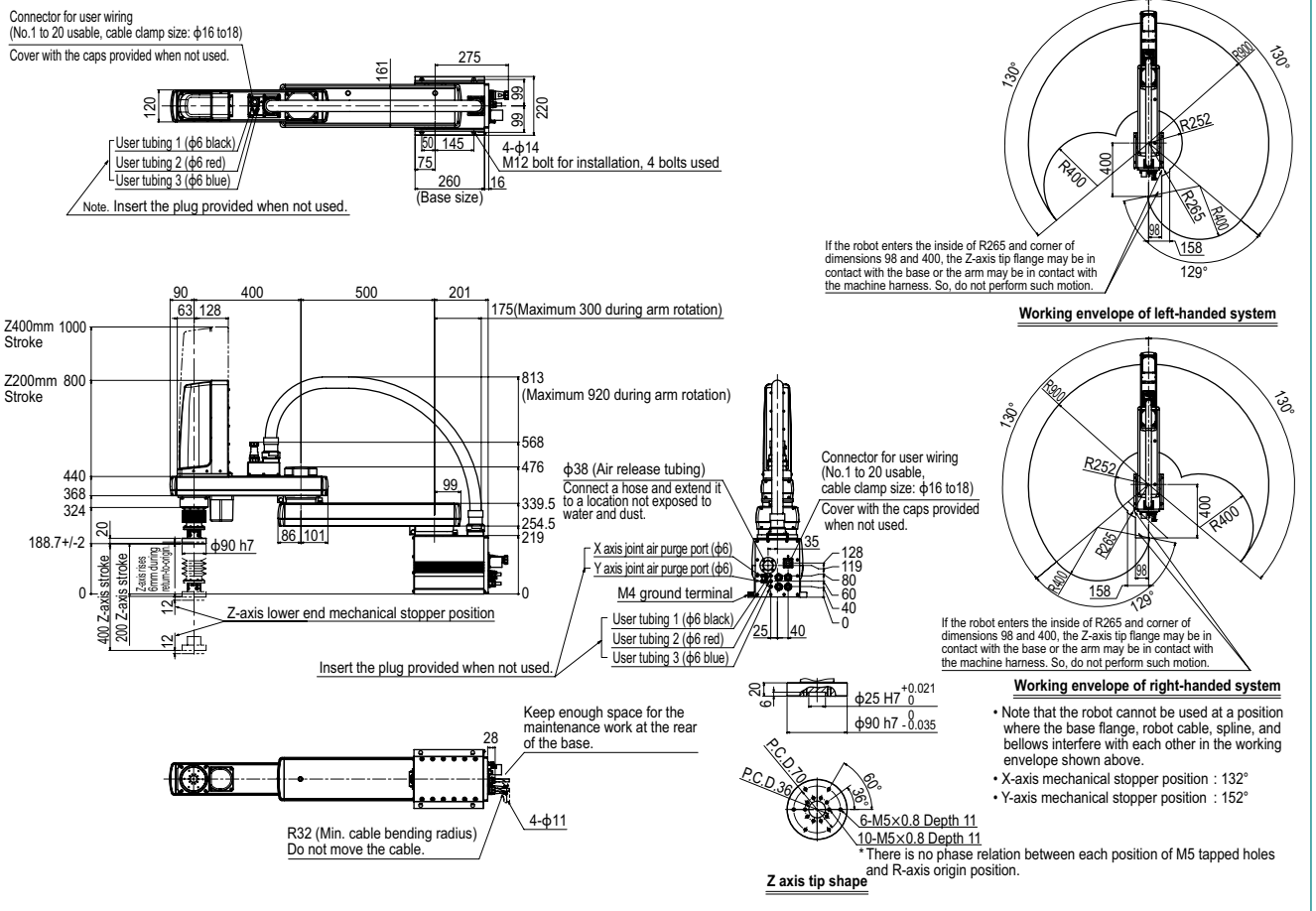
YK900XGP



- Note that the robot cannot be used at a position where the base flange, robot cable, spline, and bellows interfere with each other in the working envelope shown above.
- X-axis mechanical stopper position : 132°
- Y-axis mechanical stopper position : 152°

* There is no phase relation between each position of M5 tapped holes and R-axis origin position.

YK1000XGP

Dust-proof & drip-proof type

- Arm length 1000mm
- Maximum payload 20kg

Ordering method

YK1000XGP	–		–	F	–		–	RCX340-4	–		–		–		–		–		–		–	
Model		Z axis stroke		Tool flange		Cable		Controller / Number of controllable axes		Safety standard		Option A (OP.A)		Option B (OP.B)		Option C (OP.C)		Option D (OP.D)		Option E (OP.E)		Absolute battery
		200: 200mm 400: 400mm		F: With tool flange		3L: 3.5m 5L: 5m 10L: 10m																

Specify various controller setting items. RCX340 ▶ P.636

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		600 mm	400 mm	200 mm / 400 mm	–
	Rotation angle		+/-130 °	+/-150 °	–	+/-360 °
AC servo motor output			750 W	400 W	400 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled			
		Speed reducer to output	Direct-coupled			
Repeatability Note 1			+/-0.02 mm		+/-0.01 mm	+/-0.004 °
Maximum speed			10.6 m/sec		2.3 m/sec / 1.7 m/sec	920 °/sec
Maximum payload			20 kg			
Standard cycle time: with 2kg payload Note 2			0.59 sec			
R-axis tolerable moment of inertia Note 3			1.0 kgm^2			
Protection class Note 4			Equivalent to IP65 (IEC 60529)			
User wiring (sq × wires)			0.2 × 20			
User tubing (Outer diameter)			ϕ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			Z axis 200 mm: 60 kg Z axis 400 mm: 62 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.
Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	2500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.) See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

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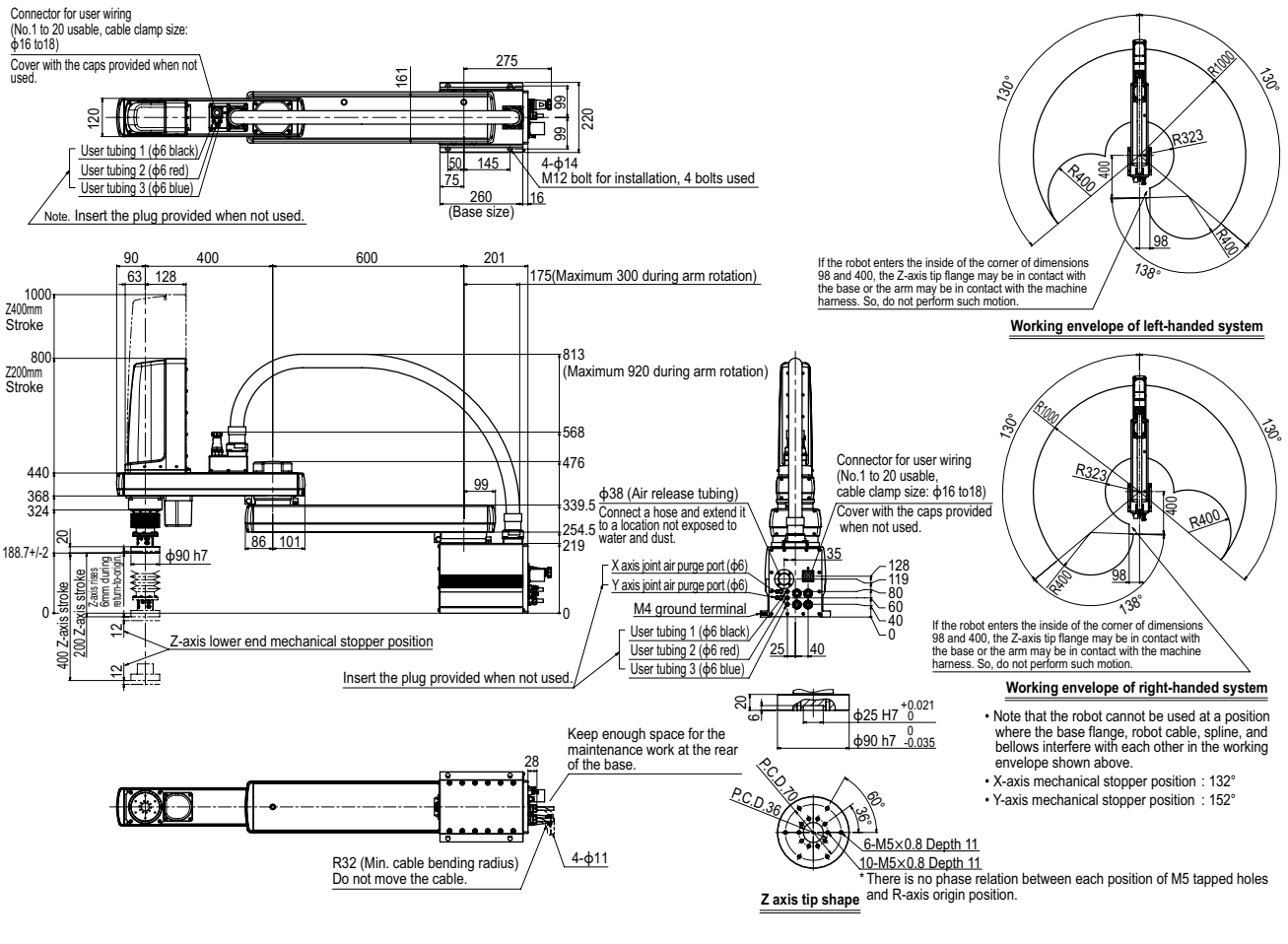
YK1000XGP



- Note that the robot cannot be used at a position where the base flange, robot cable, spline, and bellows interfere with each other in the working envelope shown above.
- X-axis mechanical stopper position : 132°
- Y-axis mechanical stopper position : 152°