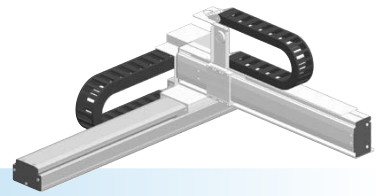
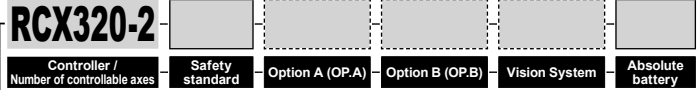
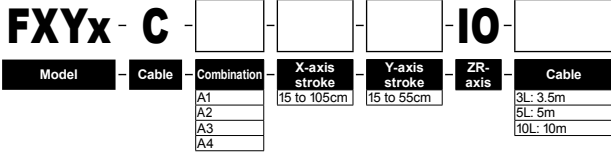


FXYx 2 axes / IO

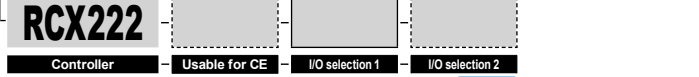
- Arm type
- Cable carrier
- Type with Y-axis I/O cable carrier added



Ordering method



Specify various controller setting items. RCX320 ▶ **P.660**



Specify various controller setting items. RCX222 ▶ **P.670**

Specification

	X-axis	Y-axis
Axis construction	-	-
AC servo motor output (W)	100	60
Repeatability ^{Note 1} (mm)	+/-0.01	+/-0.02
Drive system	Ball screw φ15	Ball screw φ12
Ball screw lead ^{Note 2} (Deceleration ratio) (mm)	20	12
Maximum speed ^{Note 3} (mm/sec)	1200	800
Moving range (mm)	150 to 1050	150 to 550
Robot cable length (m)	Standard: 3.5 Option: 5, 10	

Note 1. Positioning repeatability in one direction.
 Note 2. Leads not listed in the catalog are also available. Contact us for details.
 Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

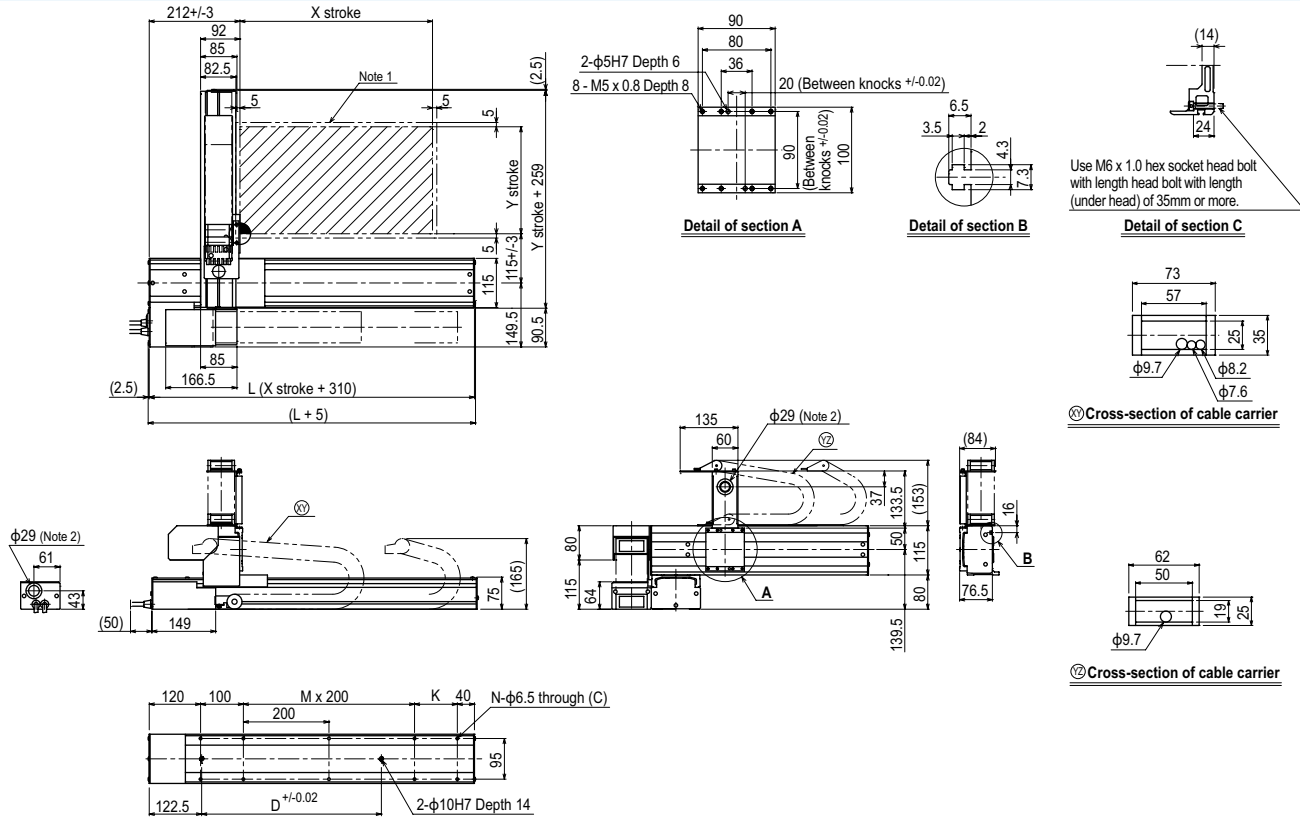
Maximum payload (kg)

Y stroke (mm)	XY 2 axes
150	12
250	12
350	11
450	9
550	7

Controller

Controller	Operation method
RCX320	Programming / I/O point trace / Remote command / Operation using RS-232C communication
RCX222	

FXYx 2 axes / IO A1



X stroke	Y stroke												
	150	250	350	450	550	650	750	850	950	1050			
L	460	560	660	760	860	960	1060	1160	1260	1360			
K	200	100	200	100	200	100	200	100	200	100			
D	240	240	420	420	600	600	780	960	960	1140			
M	0	1	1	2	2	3	3	4	4	5			
N	6	8	8	10	10	12	12	14	14	16			
Y stroke	150	250	350	450	550								
Maximum speed for each stroke (mm/sec) ^{Note 3}	X-axis		1200			960		780		600		540	
	Speed setting		-			80%		65%		50%		45%	

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.
 Note 2. User cable extraction port.
 Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.