

NEW

3D simulator function
Program template function
Custom window creation function



RCX 3 Series CONTROLLER PROGRAMMING SOFTWARE

RCX-Studio 2020

Robot operation from start up to maintenance

New features to greatly reduce startup time

Programming software for RCX 3 series controllers

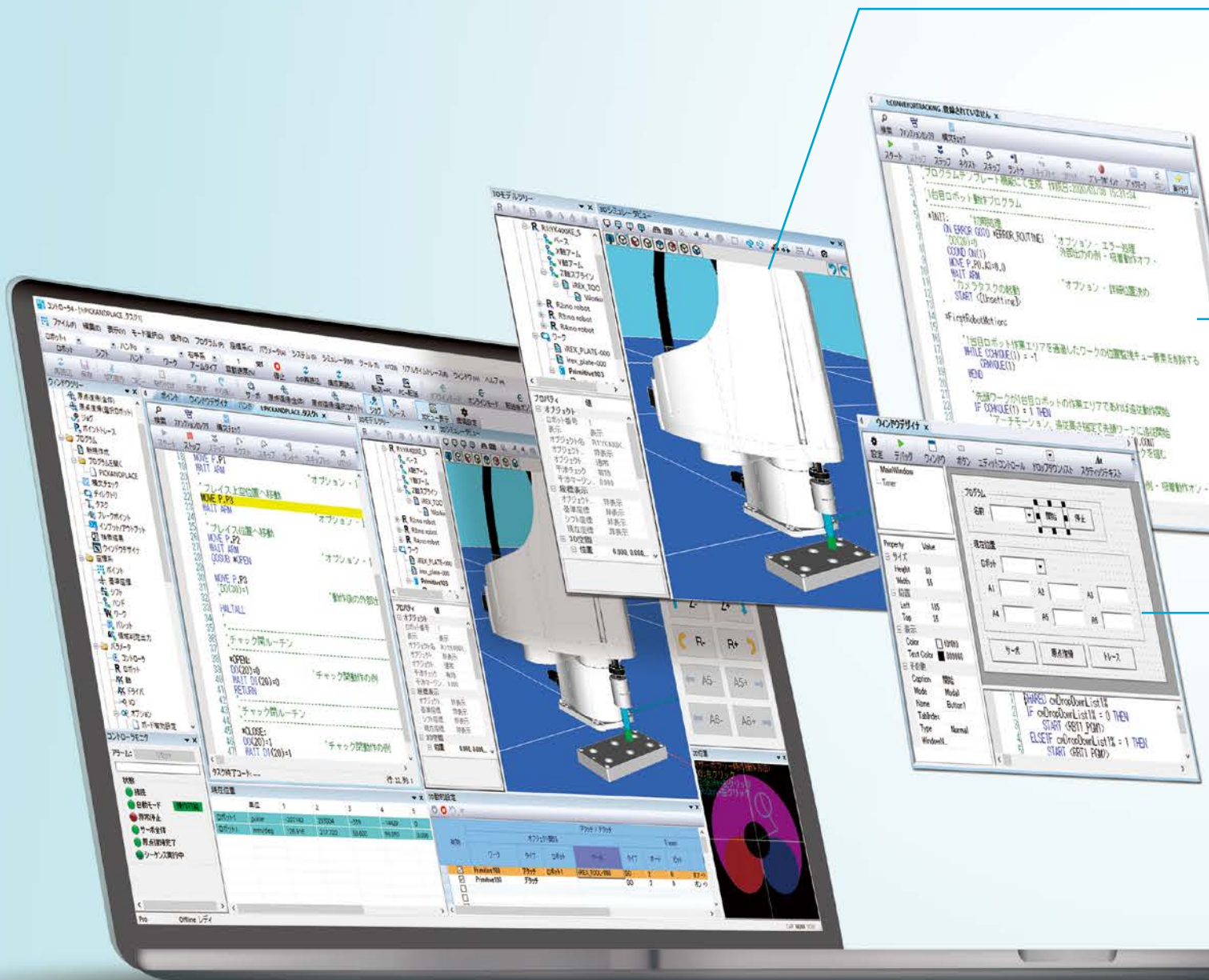
RCX-Studio 2020

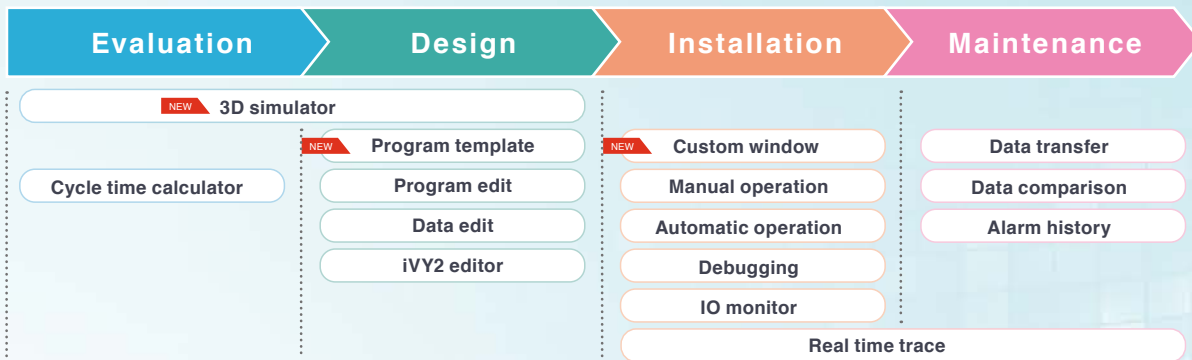


Improves production startup time

Start programming before robot delivery

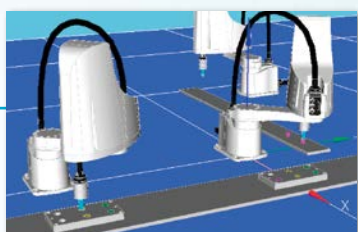
New functions such as 3D simulator function and program template (program template automatic creation function) are added for ease of user operation.





NEW 3D simulator

See 04P.



Layout can be verified beforehand without connecting robot.

Robots and peripheral devices are displayed in 3D, and the robot operation is simulated on PC.

- ▶ Robot layout, teaching, and debugging can be performed.
- ▶ Interference between the robot and peripheral units can be checked without any actual machine. This contributes to reducing the time until the equipment operates.

NEW Program template (Program template automatic creation function)

See 06P.

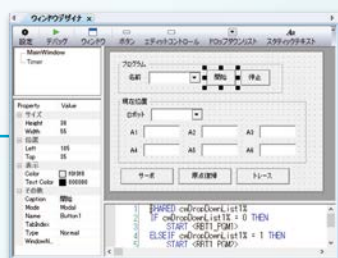


Program creation time can be shortened greatly.

Program templates for 10 types of applications are incorporated. Just following the steps to perform the operation creates a program template automatically.

NEW Custom window creation

See 08P.



Operation screens suitable for the customer's equipment can be created.

GUIs for operators that are displayed on the panel computer can be created.

Other existing functions

See 09P.



All useful features from RCX-Studio Pro are succeeded to help supporting from startup to maintenance.

Cycle time calculator

Real time trace

Data comparison

Layout verification, teaching, and debugging without connecting robots

NEW

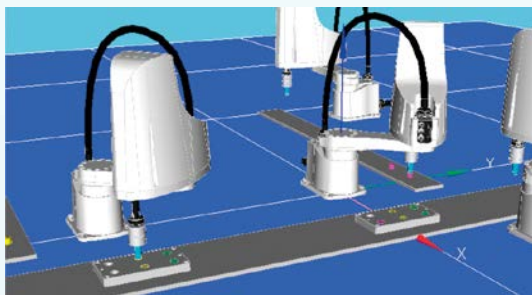
3D simulator

Robots and peripheral devices are displayed in 3D, and the robot operation is simulated.



3D CAD Data imported

- Multiple robots are supported (up to 4 robots).

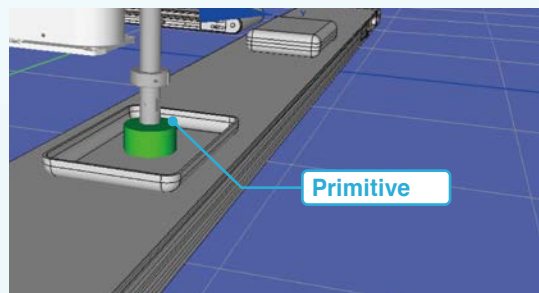


Importable data **STL, Wavefront OBJ, VRML2.0, STEP***

* Only Pro version is supported. Supported format: AP204, AP214

Peripheral devices are displayed using primitives.

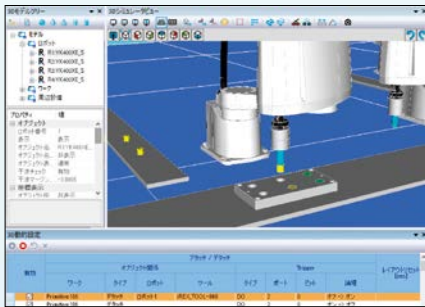
- Peripheral devices and workpieces can be displayed using simple shapes (primitives).



Primitive

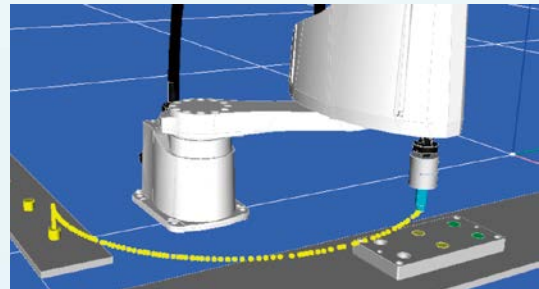
Teaching virtual robot on screen

- Teaching of the current position can be performed by moving virtual robots using the jog or mouse operation.



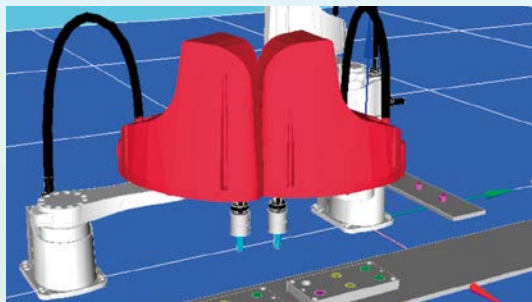
Operation area is verified by tracing the movement of end-of-arm effector and parts

- Visually tracing robot move
- Movement of workpiece and end effector can be displayed.



Interference with the production units is checked to avoid collision with other devices.

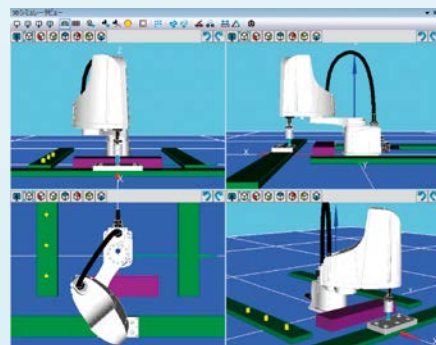
- Interference between the robot and peripheral device is checked.



* Interference check is performed at the screen drawing timing. Therefore, the interference may not be detected depending on the execution environment and operation status of the software. To perform the accurate check, it is recommended to decrease the operation speed of the robot and perform the check several times.

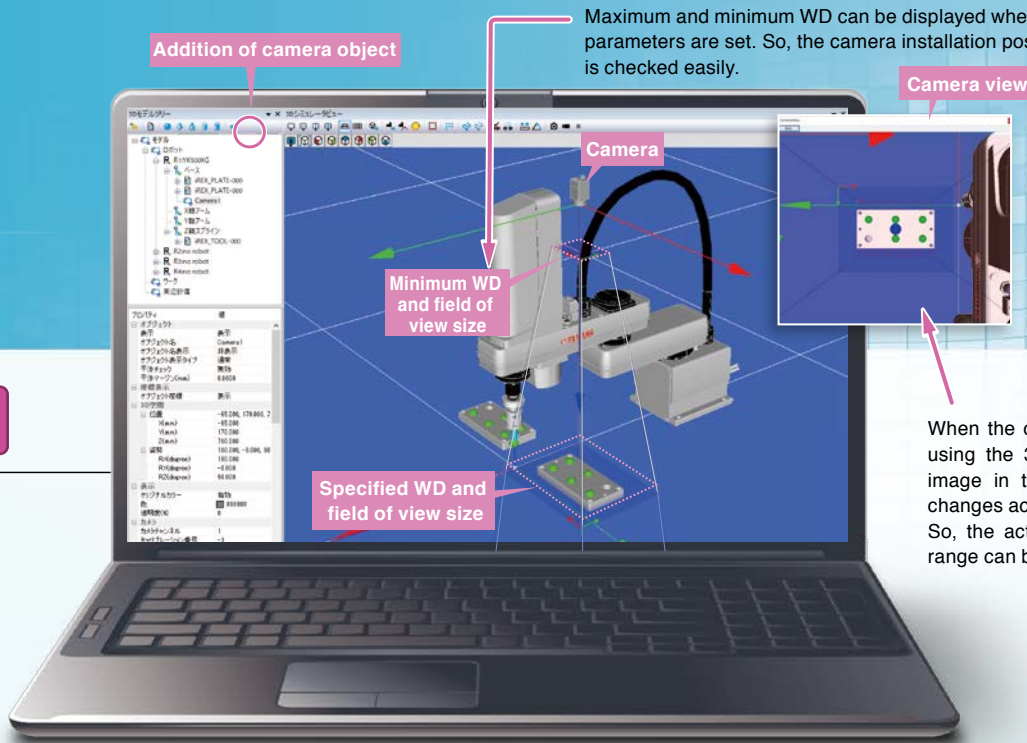
Multi-angle View (Screen division function)

- Layout can be checked from multiple viewpoints at the same time.



Video capture

- The simulation results are output as a video.



Maximum and minimum WD can be displayed when the parameters are set. So, the camera installation position is checked easily.

RCX-Studio 2020
Basic

RCX-Studio 2020
Pro

When the camera is moved using the 3D emulator, the image in the camera view changes accordingly. So, the actual field of view range can be checked.

From camera layout examination to operation verification can be performed on the 3D emulator.

Camera layout can be examined.

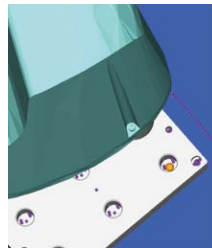
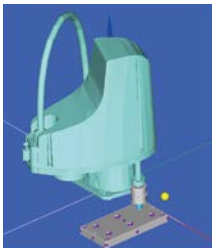
- Camera object can be placed on the 3D emulator. Maximum and minimum WD (work distance), and field of view range are displayed depending on the combination of camera, lens, and close-up ring. Pre-verification of optimal combination and installation position can be performed.

Program simulation containing vision commands can be performed.

- Test execution of programs containing vision commands can be performed.
* Supported from Ver. 3.2.0

RCX-Studio 2020
Pro

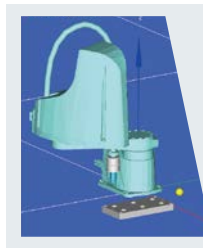
STEP data file can be imported.



Pro

Characteristic points with STEP file data are displayed.

For the STEP data, characteristic points of the 3D CAD data are displayed. Clicking the characteristic point moves the robot.

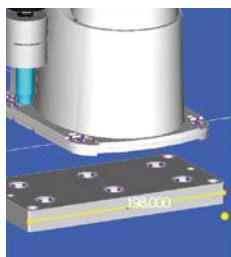


For Basic

For data other than the STEP data, characteristic points of the 3D CAD data are not displayed.

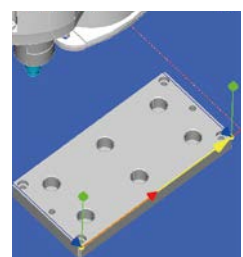
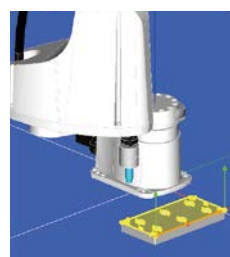
Measurement of distance and angle

With STEP file data the distance and angle can be measured using the characteristic points on the edge.



Creation of edge point data

With STEP file data the characteristic points on the edge can be converted into the point data.



Easy programming with wizards.

NEW

Program template

Program templates of ten types of applications



Just following the steps to perform the operation creates a program automatically.

Robot application selection
Application is selected from the dialog box.

Setting with wizards

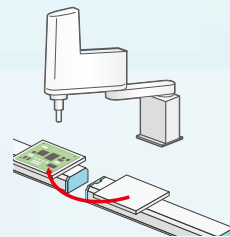
Option function selection

```

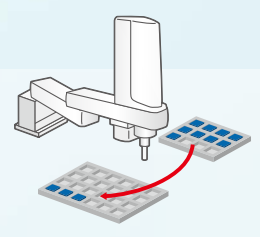
Main routine
ON ERROR: GOTO *ERROR_ROUTINE *Option - Error handling
SERVO ON *Option - Automatic servo on
ORIGIN 1,0 *Option - Automatic return-to-origin
RESET T-COUNTER *Option - Time measurement
9 Move to a position above the pick *Option - Debug information display
10 PRINT Move to pick point
11 MOVE P,P1 *Option - Detailed positioning
12 WAIT ASM *Prepare a tip tool
13 GOSUB *PLACE
14
15 Move to pick position *External input wait example
16 WAIT DI(30)+1
17 MOVE P,P0 *Option - Detailed positioning
18 WAIT ASM
19 GOSUB *PICK
20
21 Move to a position above the pick *Option - Detailed positioning
22 MOVE P,P1
23 WAIT ASM
24
25 Move to a place above the place *Option - Detailed positioning
26 MOVE P,P2
27 WAIT ASM
    
```

Supported applications

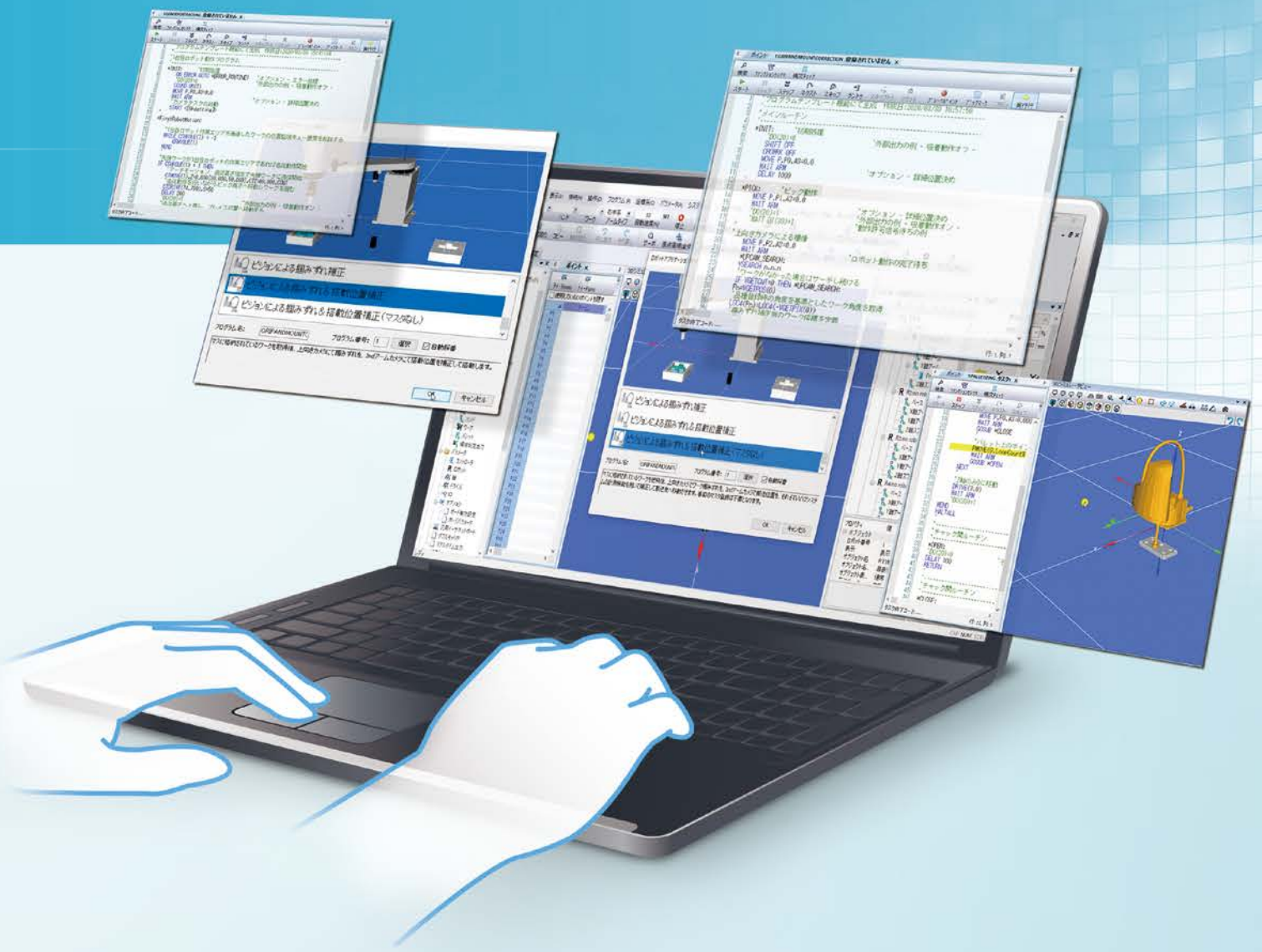
- Pick & place
- Palletizing
- Dispensing work
- Execution program switching
- Conveyor tracking
- Pallet picking using vision
- Dispensing with vision
- Gripping deviation correction using vision
- Parts orientation adjustment on the fly with vision
- Parts orientation adjustment on the fly with vision (without master)



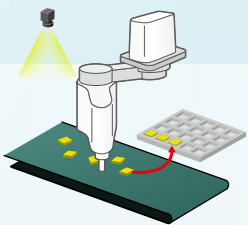
Pick & place



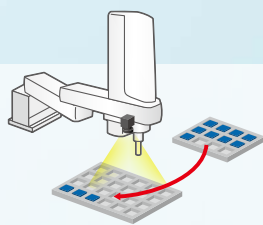
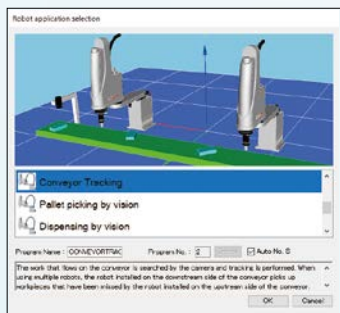
Palletizing



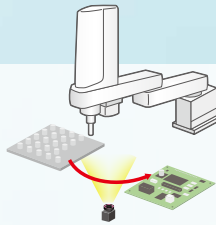
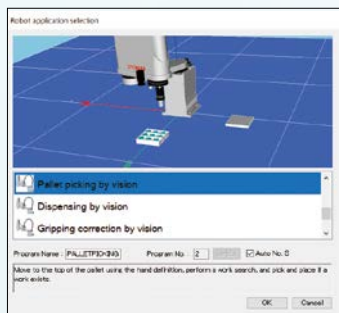
Programming process without command input to save time



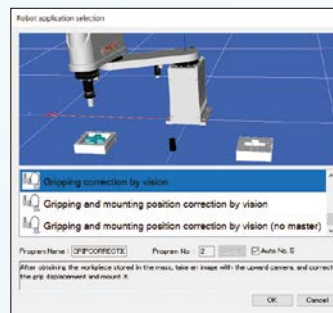
● Conveyor tracking



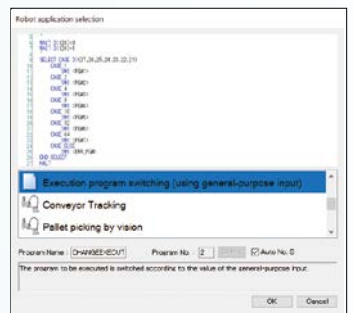
● Pallet picking using vision



● Parts orientation adjustment on the fly with vision



● Switching execution program



Customizing operation screen

NEW

Custom window creation

Easy creation of GUI for operators on PC



Creating customized display on PC for operators

Existing window can be displayed.

- Servo
- Return-to-origin
- Point trace

Button press and timer cycle processes are described in robot language.



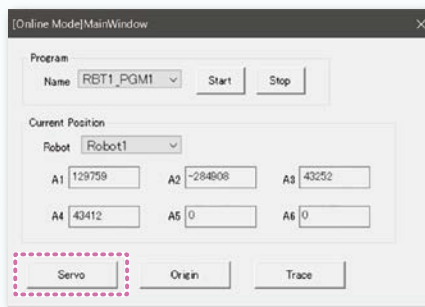
Shortcut is created using "Save".

Operation screens for operators

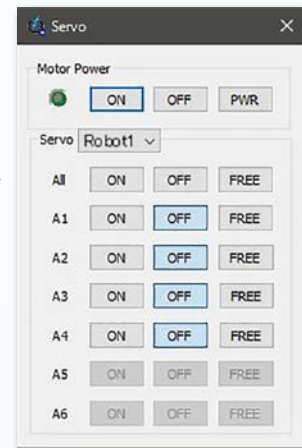
Start by touching the dedicated shortcut.



Screen is started instead of Studio.



Studio's existing window display



Functions necessary for operation can be narrowed down. Operation screens suitable for the customer's equipment can be created to prevent troubles such as data erasing or rewriting due to misoperation.

Abundant functions that are succeeded from “RCX-Studio Pro” support the YAMAHA robot operation from the startup to the maintenance work.

Pre-investigation before purchase

Preceding start before delivery

Software improvement investigation after operation start

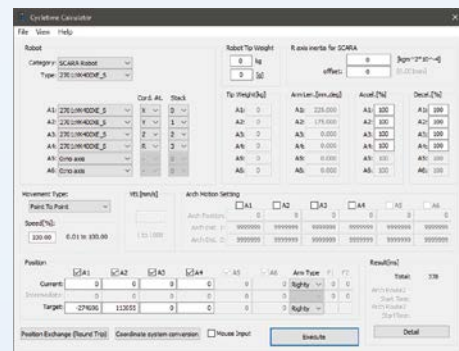


Functions succeeded from “RCX-Studio Pro”.

► Cycle time calculation

Cycle time between two points is calculated simply only with two steps. By entering a robot model and position data, it will calculate the cycle time.

Parameter	A1	A2	A3	A4
Motor Number	320	320	320	320
Lead(0.01mm/0.01deg)	30000	30000	12000	30000
Gear ratio(0.01)	30000	30000	3000	12000
Acceleration(rad/s ² mm/s)	1200	1200	4000	1200
Deceleration(rad/s ² mm/s)	2000	2000	10000	2000
Origin method	1	1	3	3
Origin direction	0	0	0	0
Origin return pulse	1	2	3	1

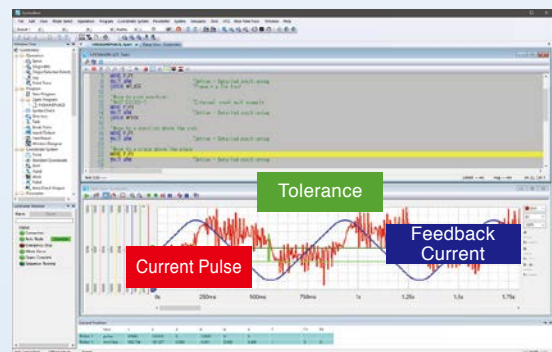


► Real time trace

Internal information on the controller is output continuously. Robot status can be checked in real time.

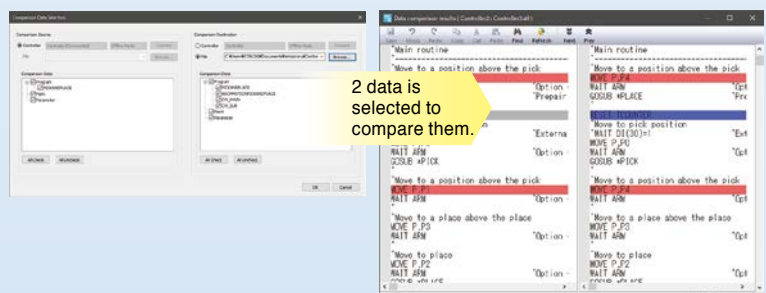
Obtainable data

- I/O status
 - Programming task status
 - Task number being executed
 - Controller temperature
 - Driver status
- Tolerance, out effective position, reference pulse, current pulse, command speed, current speed, command current, present current, motor load factor, driver load factor



► Data comparison

Difference between two specified data is displayed visually. Direct comparison with the online data can be performed to greatly reduce the maintenance time.



◆ Specifications

Software

Software can be downloaded from YAMAHA's WEB site together with RCX-Studio 2020 Basic or RCX-Studio 2020 Pro.



Basic specifications

Product name	RCX-Studio 2020 Basic	RCX-Studio 2020 Pro
Type ^{Note1}	KCX-M4990-40	KCX-M4990-50
License management	USB key (blue) ^{Note2}	USB key (purple)
Supported language	Japanese, English, Chinese	
OS ^{Note3}	Microsoft Windows 7 SP1(32/64bit) / 8.1 (32 bit / 64 bit) / 10 (32 bit / 64 bit)	
Execution environment	.NET Framework 4.5 or more	
CPU	Recommended: Intel Core i5 2 GHz or more, Minimum: Intel Celeron 2 GHz or more, 3D-SIM is invalid.: Intel Core 2 Duo 2 GHz or more	
Memory	Recommended: 8 GB or more, Minimum: 4 GB or more, 3D-SIM is invalid: 1 GB or more	
Hard disk capacity	1GB of available space required on installation drive	
Communication Port	Communication cable: Serial communication port, Ethernet port, or USB port	
Others	Dedicated commutation cable (For D-Sub or USB) Ethernet cable (category 5 or better) USB port: 1 port (For USB key)	
Applicable controller	RCX340/RCX320	
Applicable robot	YAMAHA robot that can be connected to the RCX340, RCX320.	

Note1. This shows the software package type. The software is common to two products and can be downloaded from YAMAHA's WEB site.

Note2. Common to the conventional model RCX-Studio Pro.

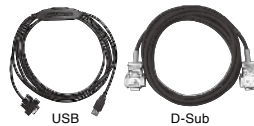
Note3. Microsoft, Windows 7, Windows 8.1, and Windows 10 are either registered trademarks or trademarks of Microsoft Corporation in the United States and/or other countries.

Other company names and product names listed in this manual may be the trademarks or registered trademarks of their respective companies.

Data cables (5m)

Communication cable for RCX-Studio 2020.
Select from USB cable or D-sub cable.

Model	USB type (5m)	KBG-M538F-00
	D-Sub type 9pin-9pin (5m)	KAS-M538F-10



**Ethernet cable
(category 5 or higher)
is also supported.**

Note. This USB cable supports Windows 2000/XP or later.

Note. The communication cable is common to POPCOM+, VIP+, RCX-Studio Pro, and RCX-Studio 2020.

Note. USB driver for communication cable can also be downloaded from our website.

USB key

To use the functions of RCX-Studio 2020 without restrictions, a dedicated USB key is required.
There will be limitations of software functions (see below chart):

Functions	When the USB key is not connected	RCX-Studio 2020 Basic (blue) ^{Note.2}	RCX-Studio 2020 Pro (purple) ^{Note.2}
Backup/restore by data transfer with controller	Valid ^{Note1.}	Valid	Valid
Controller operation in online mode	Invalid	Valid	Valid
File read (opening data)	Invalid	Valid	Valid
File save	Invalid	Valid	Valid
Real Time Trace	Only data save is invalid.	Valid	Valid
Cycletime Calculator	Invalid	Valid	Valid
iVY2 editor	Invalid	Valid	Valid
Data Difference	Except data saving	Valid	Valid
3D simulator function	Only capturing is invalid.	Valid	Valid
Custom window	Valid	Valid	Valid
Program template	Only file output is invalid.	Valid	Valid
CAD data read	STL, OBJ, VRML	Valid	Valid
	STEP	Invalid	Valid
CAD to point conversion	Invalid	Invalid	Valid

Note1. USB key connection is required for backup when connected in offline mode.

Note2. USB key color

MEMO



Safety Precautions

Read the instruction manual thoroughly to operate the robot in a correct manner.



YAMAHA

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