2 axes / ZFL20

XZ typeCable carrier

Ordering method **RCX320-2** SXYx-C

3L: 3.5m 5L: 5m 10L: 10m Specify various controller setting items. RCX320 ▶ P.626

Z-axis: clamped base / moving table type (200W)

Note 1. RCX320 uses the YHX-RU regenerative unit. The RCX222 uses the RG2.

■ Specification						
	X-axis	Z-axis				
Axis construction Note 1	F14	F10H-BK				
AC servo motor output (W)	100	200				
Repeatability Note 2 (mm)	+/-0.01	+/-0.01				
Drive system	Ball screw ф15	Ball screw φ15				
Ball screw lead Note 3 (Deceleration ratio) (mm)	20	20				
Maximum speed Note 4 (mm/sec)	1200	1200				
Moving range (mm)	150 to 1050	150 to 350				
Robot cable length (m)	Standard: 3.5 Option: 5,10					

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots'.

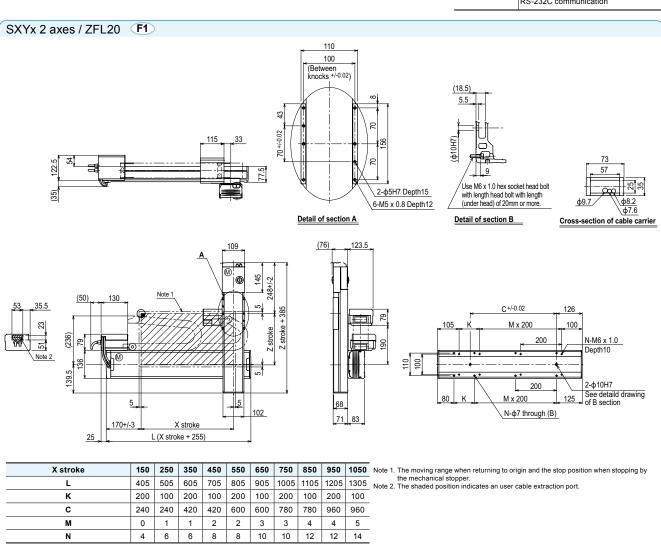
Note 2. Positioning repeatability in one direction.

Note 3. Leads not listed in the catalog are also available. Contact us for details.

Note 4. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

■ Maximum payload		
	Z stroke (mm)	
X stroke (mm)	150 to 350	
150 to 1050	8	

■ Controller					
Controller	Operation method				
RCX320-R	Programming / I/O point trace / Remote command / Operation using RS-232C communication				



X stroke		150	250	350	450	550	650	750	850	950	1050	١
L		405	505	605	705	805	905	1005	1105	1205	1305	1
К		200	100	200	100	200	100	200	100	200	100	
С		240	240	420	420	600	600	780	780	960	960	
М		0	1	1	2	2	3	3	4	4	5	
N		4	6	6	8	8	10	10	12	12	14	
Z stroke		150	250	350								1
Maximum speed for each stroke (mm/sec) Note 3	X-axis			12	00			960	780	600	540	
	Speed setting							80%	65%	50%	45%	

Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.