

SXYx

4 axes / ZRS



● Arm type ● Cable carrier

● ZR axis integrated type

Ordering method

SXYx - C					15		RCX340-4								
Model	Cable	Combination	X-axis stroke	Y-axis stroke	ZR-axis	Z-axis stroke	Cable	Controller / Number of controllable axes	Safety standard	Option A (O.P.A)	Option B (O.P.B)	Option C (O.P.C)	Option D (O.P.D)	Option E (O.P.E)	Absolute battery
A1			15 to 105cm	15 to 65cm	ZRS12		3L: 3.5m 5L: 5m 10L: 10m								
A2					ZRS6										
A3															
A4															

Specify various controller setting items. RCX340 ▶ P.636

Specification

	X-axis	Y-axis	Z-axis: ZRS12	Z-axis: ZRS6	R-axis
Axis construction Note 1	F14H	F14	—	—	—
AC servo motor output (W)	200	100	60	100	
Repeatability Note 2 (XYZ: mm) (R: °)	+/-0.01	+/-0.01	+/-0.02	+/-0.005	
Drive system	Ball screw φ15	Ball screw φ15	Ball screw φ12	Harmonic gear	
Ball screw lead Note 3 (Deceleration ratio) (mm)	20	20	12	6	(1/50)
Maximum speed Note 4 (XYZ: mm/sec) (R: °/sec)	1200	1200	1000	500	1020
Moving range (XYZ: mm) (R: °)	150 to 1050	150 to 650	150	360	
Robot cable length (m)	Standard: 3.5 Option: 5, 10				

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots.

Note 2. Positioning repeatability in one direction.

Note 3. Leads not listed in the catalog are also available. Contact us for details.

Note 4. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

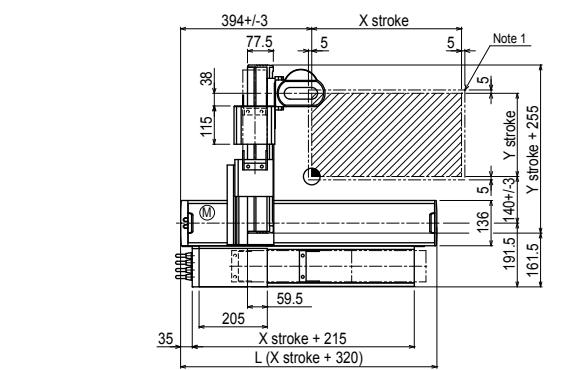
Maximum payload

Y stroke (mm)	ZRS12	ZRS6
150	3	5
250	3	5
350	3	5
450	3	5
550	3	5
650	3	4

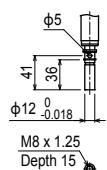
Controller

Controller	Operation method
RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication

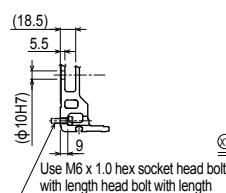
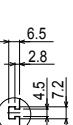
SXYx 4 axes / ZRS A1



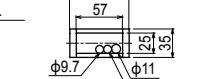
Detail of section A



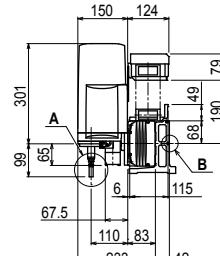
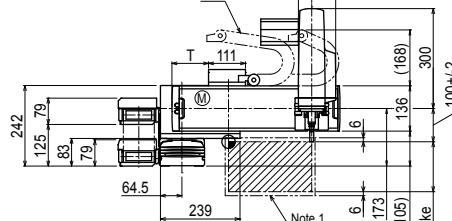
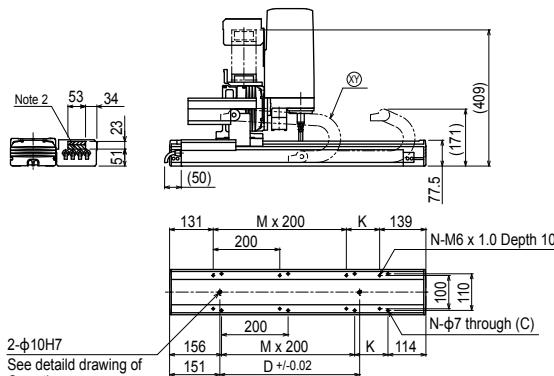
Detail of section B



◎ Cross-section of cable carrier



◎ Cross-section of cable carrier



X stroke	150	250	350	450	550	650	750	850	950	1050
L	470	570	670	770	870	970	1070	1170	1270	1370
K	200	100	200	100	200	100	200	100	200	100
D	240	240	420	420	600	600	780	960	960	1140
M	0	1	1	2	2	3	3	4	4	5
N	4	6	6	8	8	10	10	12	12	14

Y stroke	150	250	350	450	550	650
T	55	110	165	220	275	330

Z stroke	150
Speed setting	—

Maximum speed for each stroke (mm/sec) Note 3	X-axis	1200	960	780	600	540
Speed setting		—	80%	65%	50%	45%

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.

Note 2. The shaded position indicates an user cable extraction port.

Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.