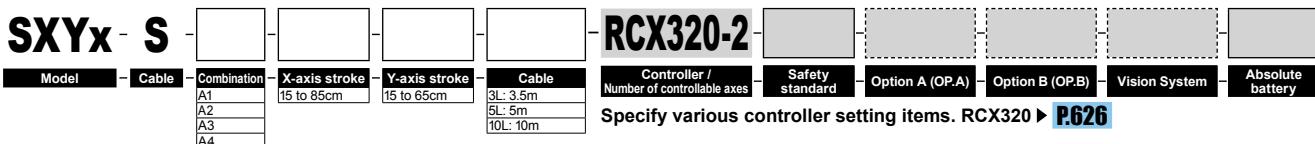


SXYx

2 axes

● Arm type ● Whipover

Ordering method



Specify various controller setting items. RCX320 ▶ P.626

Specification

| | X-axis | Y-axis |
|---|----------------------------|----------------|
| Axis construction Note 1 | F14H | F14 |
| AC servo motor output (W) | 200 | 100 |
| Repeatability Note 2 (mm) | +/-0.01 | +/-0.01 |
| Drive system | Ball screw φ15 | Ball screw φ15 |
| Ball screw lead Note 3 (Deceleration ratio) (mm) | 20 | 20 |
| Maximum speed Note 4 (mm/sec) | 1200 | 1200 |
| Moving range (mm) | 150 to 850 | 150 to 650 |
| Robot cable length (m) | Standard: 3.5 Option: 5.10 | |

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots'.

Note 2. Positioning repeatability in one direction.

Note 3. Leads not listed in the catalog are also available. Contact us for details.

Note 4. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

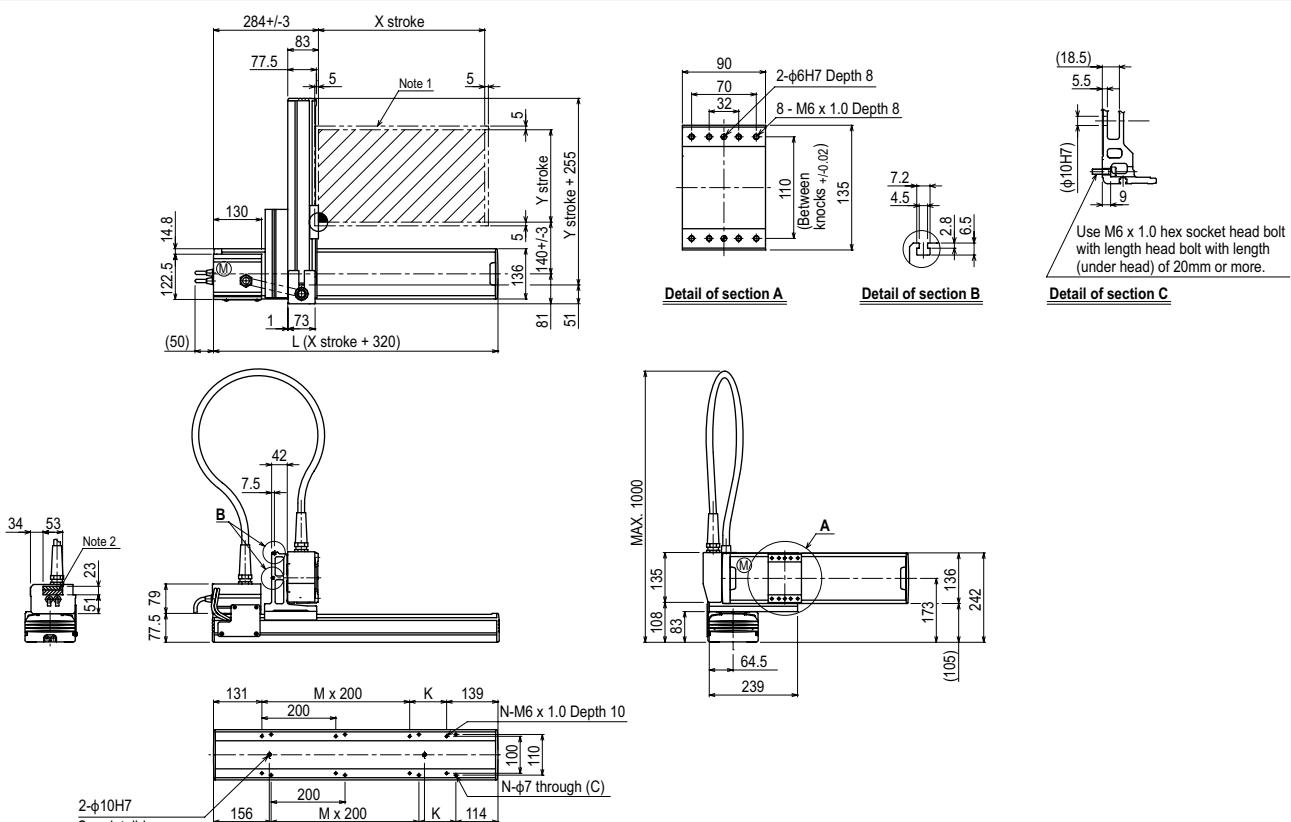
Maximum payload

| Y stroke (mm) | XY 2 axes |
|----------------------|------------------|
| 150 | 20 |
| 250 | 17 |
| 350 | 15 |
| 450 | 13 |
| 550 | 11 |
| 650 | 9 |

Controller

| Controller | Operation method |
|-------------------|--|
| RCX320 | Programming / I/O point trace / Remote command / Operation using RS-232C communication |

SXYx 2 axes A1



| X stroke | 150 | 250 | 350 | 450 | 550 | 650 | 750 | 850 |
|-----------------|-----|-----|-----|-----|-----|-----|------|------|
| L | 470 | 570 | 670 | 770 | 870 | 970 | 1070 | 1170 |
| K | 200 | 100 | 200 | 100 | 200 | 100 | 200 | 100 |
| D | 240 | 240 | 420 | 420 | 600 | 600 | 780 | 960 |
| M | 0 | 1 | 1 | 2 | 2 | 3 | 3 | 4 |
| N | 4 | 6 | 6 | 8 | 8 | 10 | 10 | 12 |

| Y stroke | 150 | 250 | 350 | 450 | 550 | 650 |
|--|-----------------------|-----|--------------------------|-----|-----|-----|
| Maximum speed for each stroke (mm/sec) Note 3 | X-axis 1200 | | Y-axis 960 780 | | | |
| Speed setting | - | | 80% 65% | | | |

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.

Note 2. The shaded position indicates an user cable extraction port.

Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

Linear conveyor modules
LCMR200

Single-axis robots
GX

Linear conveyor modules
LCM100

SCARA robots
YK-X

Single-axis robots
Robonity

Linear motor
PHASER

Single-axis robots
FLIP-X

Compact
single-axis robots
TRANSEROV

Cartesian robots
XY-X

Pick & place
Y-P-X

CLEAN

CONTROLLER INFORMATION

Arm type

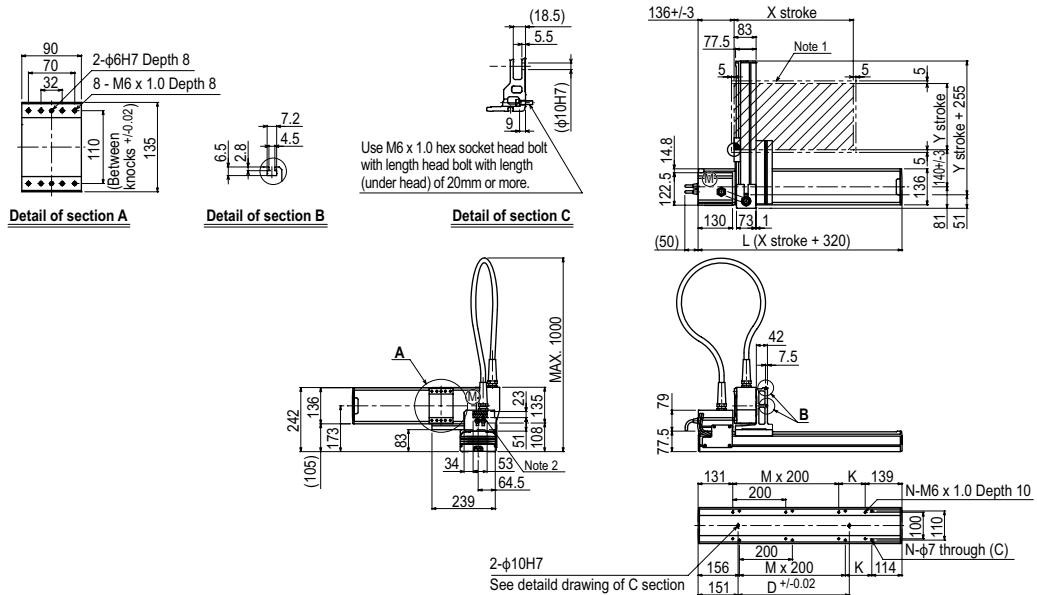
Gantry type

Moving arm type

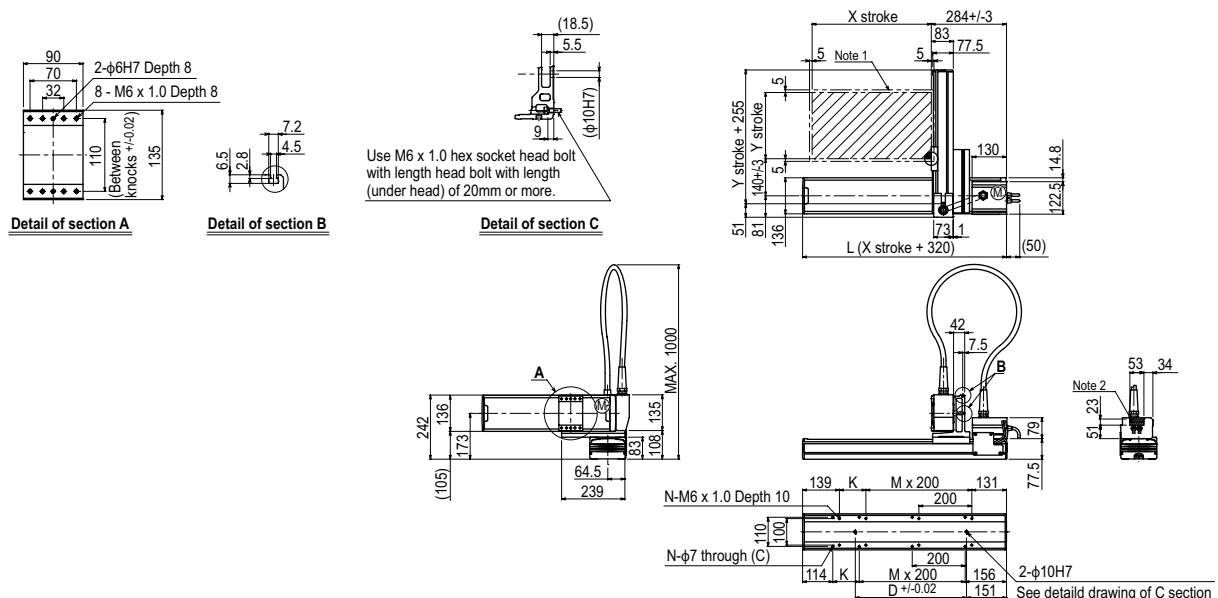
Pole type

XZ type

SXYx 2 axes A2



SXYx 2 axes A3



SXYx 2 axes A4

