

Arm type Cable carrier

Ordering method

RCX320-2 SXYx-C 10 - Option A (OP.A) - Option B (OP.B) -Specify various controller setting items. RCX320 ▶ P.626

■ Specification		
	X-axis	Y-axis
Axis construction Note 1	F14H	F14
AC servo motor output (W)	200	100
Repeatability Note 2 (mm)	+/-0.01	+/-0.01
Drive system	Ball screw φ15	Ball screw ф15
Ball screw lead Note 3 (Deceleration ratio) (mm)	20	20
Maximum speed Note 4 (mm/sec)	1200	1200
Moving range (mm)	150 to 1050	150 to 650
Robot cable length (m)	Standard: 3.5	Option: 5,10

Y stroke (mm)	XY 2 axes
150	19
250	16
350	14
450	12
550	10
650	8

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots'.

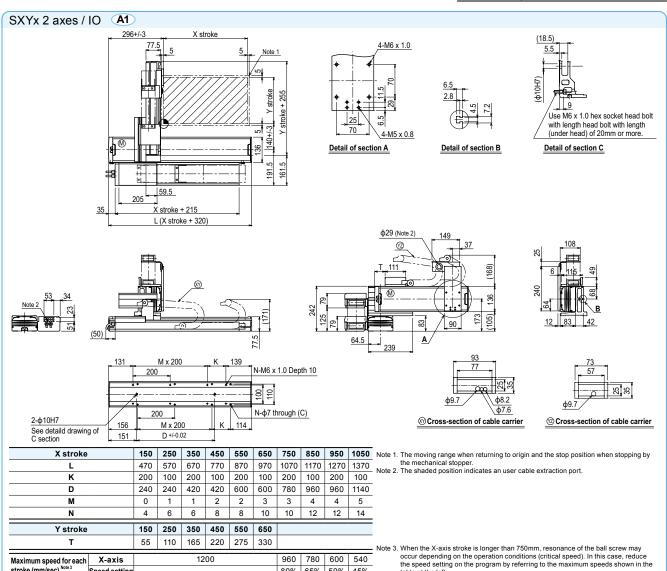
Note 2. Positioning repeatability in one direction.

Note 3. Leads not listed in the catalog are also available. Contact us for details.

Note 4. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

■ Maximum payload (kg	
Y stroke (mm)	XY 2 axes
150	19
250	16
350	14
450	12
550	10
650	8
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■ Controller		
Controller	Operation method	
RCX320	Programming / I/O point trace / Remote command / Operation using RS-232C communication	



960 780 600 540

80% 65% 50% 45%

table at the left.

1200

Maximum speed for each stroke (mm/sec) Note 3

Speed setting