

SXYxC

2 axes



● Clean type ● Cable duct

Ordering method

SXYxC - D	[]	[]	[]	[]	RCX320-2	[]	[]	[]	[]	[]	
Model	Cable D: Cable duct	Combination T1 T3	X axis stroke 15 to 105cm	Y axis stroke 15 to 65cm	Cable length 3L: 3.5m 5L: 5m 10L: 10m	Controller / Number of controllable axes	Safety standard	Option A (O.P.A)	Option B (O.P.B)	Vision System	Absolute battery

Specify various controller setting items. RCX320 ▶ P.626

Basic specifications

	X axis	Y axis
Axis construction Note 1	C14H	C14
AC servo motor output (W)	200	100
Repeatability Note 2 (mm)	+/-0.01	+/-0.01
Drive system	Ball screw φ15	Ball screw φ15
Ball screw lead Note 3 (Deceleration ratio) (mm)	20	20
Maximum speed Note 4 (mm/sec)	1000	1000
Moving range (mm)	150 to 1050	150 to 650
Robot cable length (m)	Standard: 3.5 Option: 5, 10	
Degree of cleanliness	CLASS 10 Note 5	
Intake air (Nl/min)	60 Note 6	

Note 1. Use caution that the frame machining (installation holes, tap holes) differs from single-axis robots'.

Note 2. Positioning repeatability in one direction.

Note 3. Leads not listed in the catalog are also available. Contact us for details.

Note 4. When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

Note 5. Per 1cf (0.1μm base), when suction blower is used.

Note 6. The necessary intake amount varies depending on the use conditions and environment.

Maximum payload

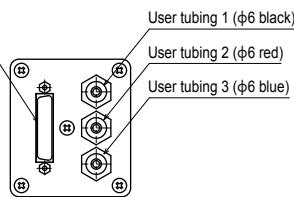
Y stroke (mm)	XY 2 axes
150	20
250	17
350	15
450	13
550	11
650	9

Controller

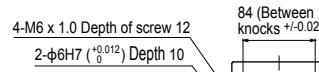
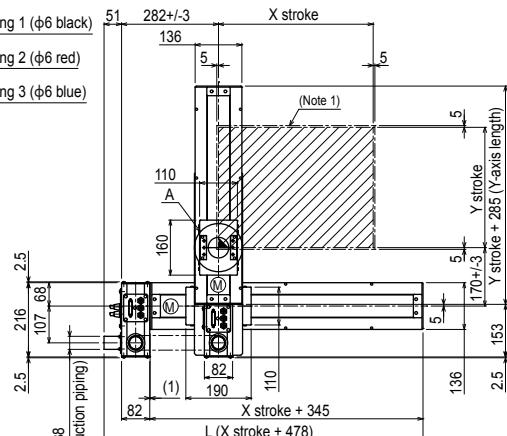
Controller	Operation method
RCX320	Programming / I/O point trace / Remote command / Operation using RS-232C communication

SXYxC 2 axes T1

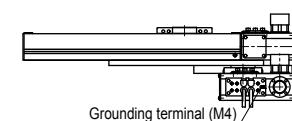
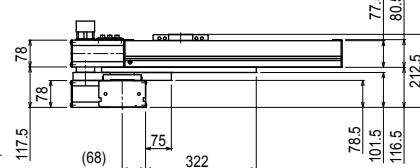
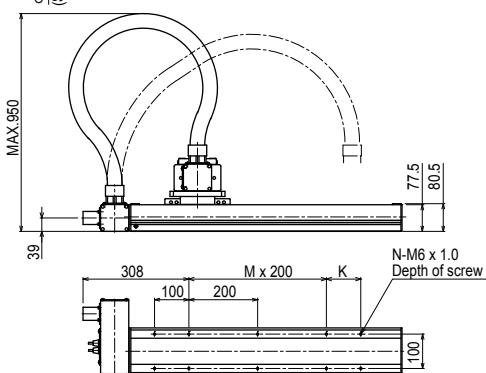
D-sub connector for user cables
(Adapted to #1 to 24)



Detail of user wiring/user tubing



Detail of section A



Grounding terminal (M4)

X stroke	150	250	350	450	550	650	750	850	950	1050
L	628	728	828	928	1028	1128	1228	1328	1428	1528
K	200	100	200	100	200	100	200	100	200	100
M	0	1	1	2	2	3	3	4	4	5
N	6	8	8	10	10	12	12	14	14	16

Y stroke

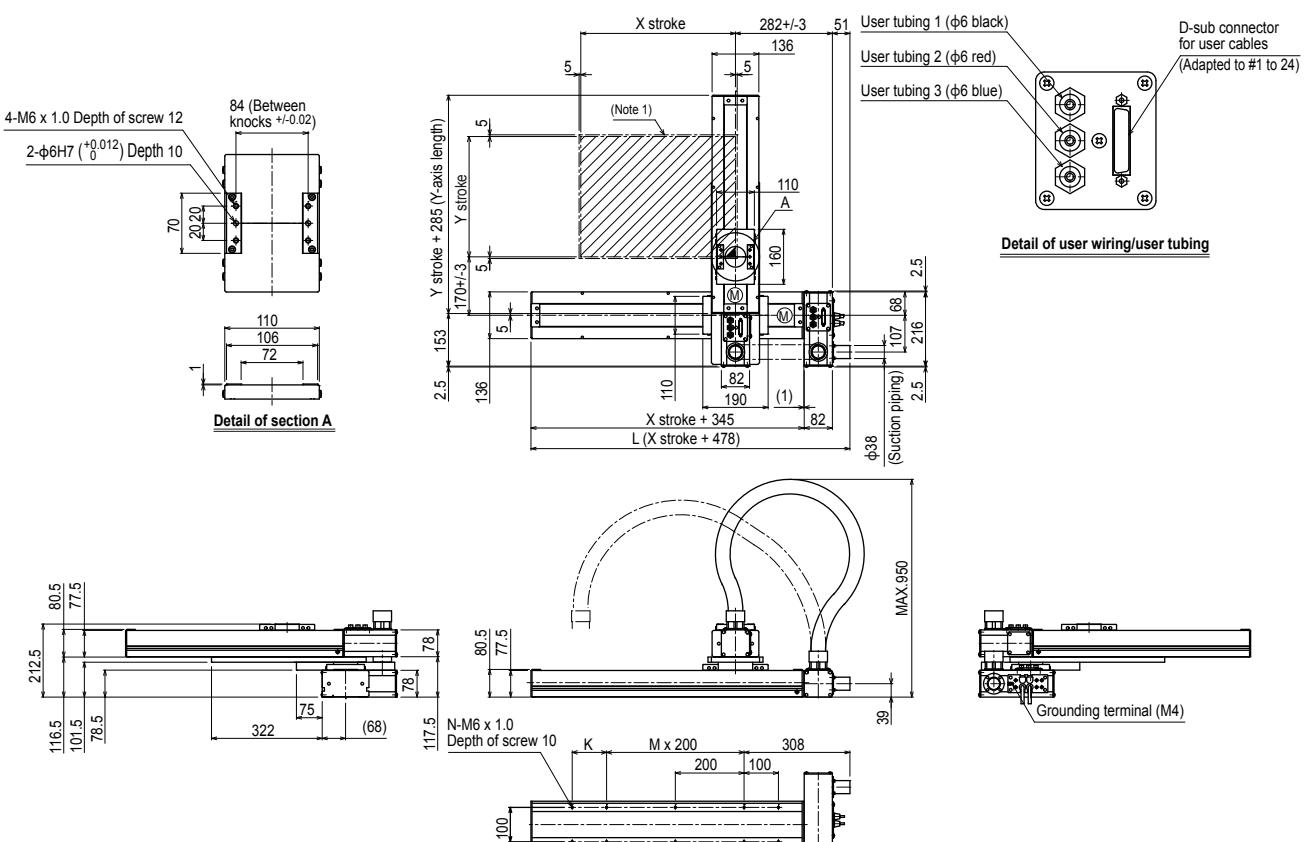
Y stroke	150	250	350	450	550	650
Maximum speed for each stroke (mm/sec) Note 2	1000					

Speed setting	-					
		80%	65%	55%		

Note 1. The moving range when returning to origin and the stop position when stopping by mechanical stopper.

Note 2. When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

SXYxC 2 axes (T3)



X stroke 150 250 350 450 550 650 750 850 950 1050 Note 1. The moving range when returning to origin and the stop position when stopping by mechanical stopper.

L 628 728 828 928 1028 1128 1228 1328 1428 1528

K 200 100 200 100 200 100 200 100 200 100

M 0 1 1 2 2 3 3 4 4 5

N 6 8 8 10 10 12 12 14 14 16

Y stroke 150 250 350 450 550 650

Maximum speed for each stroke (mm/sec) ^{Note 2}	X axis Speed setting	1000	800	650	550
		-	80%	65%	55%

Note 2. When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.