

SSC05

Slider type



- High lead: Lead 20
- CE compliance
- Origin on the non-motor side is selectable

Ordering method

Model	Lead	Type	Brake	Direction of air coupler installation	Origin position	Stroke	Cable length
SSC05	20: 20mm 12: 12mm 6: 6mm	S: Straight	N: With no brake B: With brake	RJ: Right (Standard) LJ: Left	N: Standard Z: Non-motor side	50 to 800 (50mm pitch)	1L: 1m 3L: 3m 5L: 5m 10L: 10m

S2	I/O
Robot positioner S2: TS-S2	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board
SH	Battery
Robot positioner SH: TS-SH	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board
SD	1
Robot driver SD: TS-SD	I/O cable 1: 1m

- Note 1. Only the model with a lead of 12mm or 6mm can select specifications with brake.
 Note 2. If changing from the origin position at the time of purchase, the machine reference amount must be reset. For details, refer to the manual.
 Note 3. The robot cable is flexible and resists bending.
 Note 4. See P.600 for DIN rail mounting bracket.
 Note 5. Select this selection when using the gateway function.

Basic specifications

Motor	42 □ Step motor
Repeatability (mm)	+/-0.02
Deceleration mechanism	Ball screw φ12
Maximum motor torque (N·m)	0.27
Ball screw lead (mm)	20 12 6
Maximum speed (mm/sec)	1000 600 300
Maximum payload (kg)	Horizontal 4 6 10 Vertical 1 2
Max. pressing force (N)	27 45 90
Stroke (mm)	50 to 800 (50mm pitch)
Overall length (mm)	Horizontal Stroke+230 Vertical Stroke+270
Maximum outside dimension of body cross-section (mm)	W55 × H56
Cable length (m)	Standard: 1 / Option: 3, 5, 10
Degree of cleanliness	CLASS 10
Intake air (Nl/min)	Lead 20 80 Lead 12 50 Lead 6 30

- Note 1. Positioning repeatability in one direction.
 Note 2. When the stroke is longer than 650mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
 Note 3. Per 1cf (0.1μm base), when suction blower is used.

Allowable overhang

Horizontal installation (Unit: mm)				Wall installation (Unit: mm)			
	A	B	C		A	B	C
Lead 20	2kg 413	139	218	Lead 20	2kg 192	123	372
Lead 12	4kg 334	67	120	Lead 12	4kg 92	51	265
Lead 6	4kg 347	72	139	Lead 6	4kg 109	57	300
	6kg 335	47	95		6kg 63	31	263
	4kg 503	78	165		4kg 134	63	496
	8kg 332	37	79		6kg 76	35	377
	10kg 344	29	62		8kg 47	22	355

Note. Distance from center of slider upper surface to conveyor center-of-gravity at a guide service life of 10,000 km (Service life is calculated for 600mm stroke models).

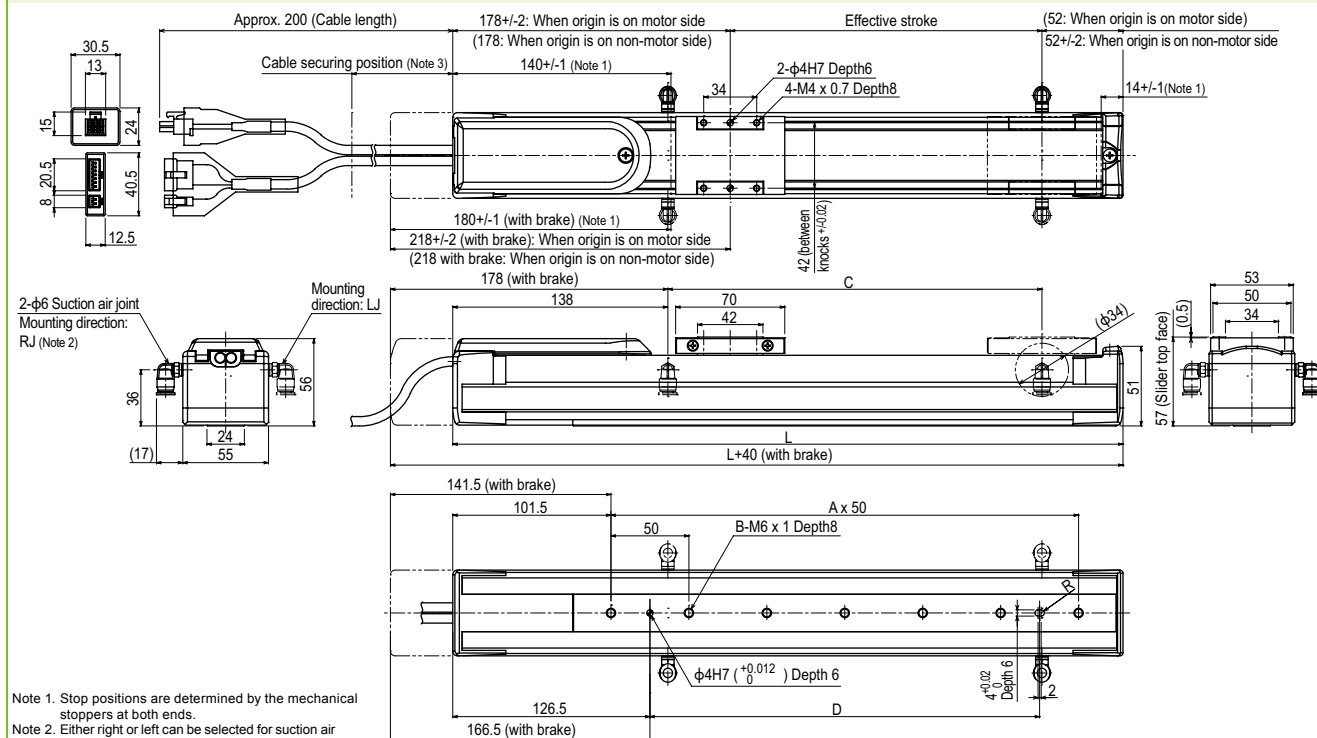
Static loading moment

MY	MP	MR
25	33	30

Controller

Controller	Operation method
TS-S2	I/O point trace / Remote command
TS-SH	Pulse train control
TS-SD	

SSC05



- Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. Either right or left can be selected for suction air joint mounting direction. This drawing shows the RJ (standard) direction.
 Note 3. Secure the cable with a tie-band 100mm or less from unit's end face to prevent the cable from being subjected to excessive loads.
 Note 4. The cable's minimum bend radius is R30.
 Note 5. These are the weights without a brake. The weights are 0.2kg heavier when equipped with a brake.
 Note 6. When the stroke is longer than 650mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
L	280	330	380	430	480	530	580	630	680	730	780	830	880	930	980	1030
A	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
B	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
C	100	150	200	250	300	350	400	450	500	500	500	500	500	500	500	500
Weight (kg)	2.1	2.3	2.5	2.7	2.8	3.0	3.2	3.4	3.6	3.8	4.0	4.2	4.4	4.6	4.8	5.0
Maximum speed for each stroke (mm/sec)	Lead 20 1000 Lead 12 600 Lead 6 300															