

# YP320X 2 axes



## Ordering method

### YP320X

Model

Cable length

- 3L: 3.5m
- 5L: 5m
- 10L: 10m

### RCX320-2

Controller /  
Number of controllable axes

Safety  
standard

Option A  
(OP.A)

Option B  
(OP.B)

Vision  
System

Absolute  
battery

Specify various controller setting items. RCX320 ▶ **P.660**

### RCX222

Controller

Usable for CE

I/O selection 1

I/O selection 2

Specify various controller setting items. RCX222 ▶ **P.670**

## Specifications

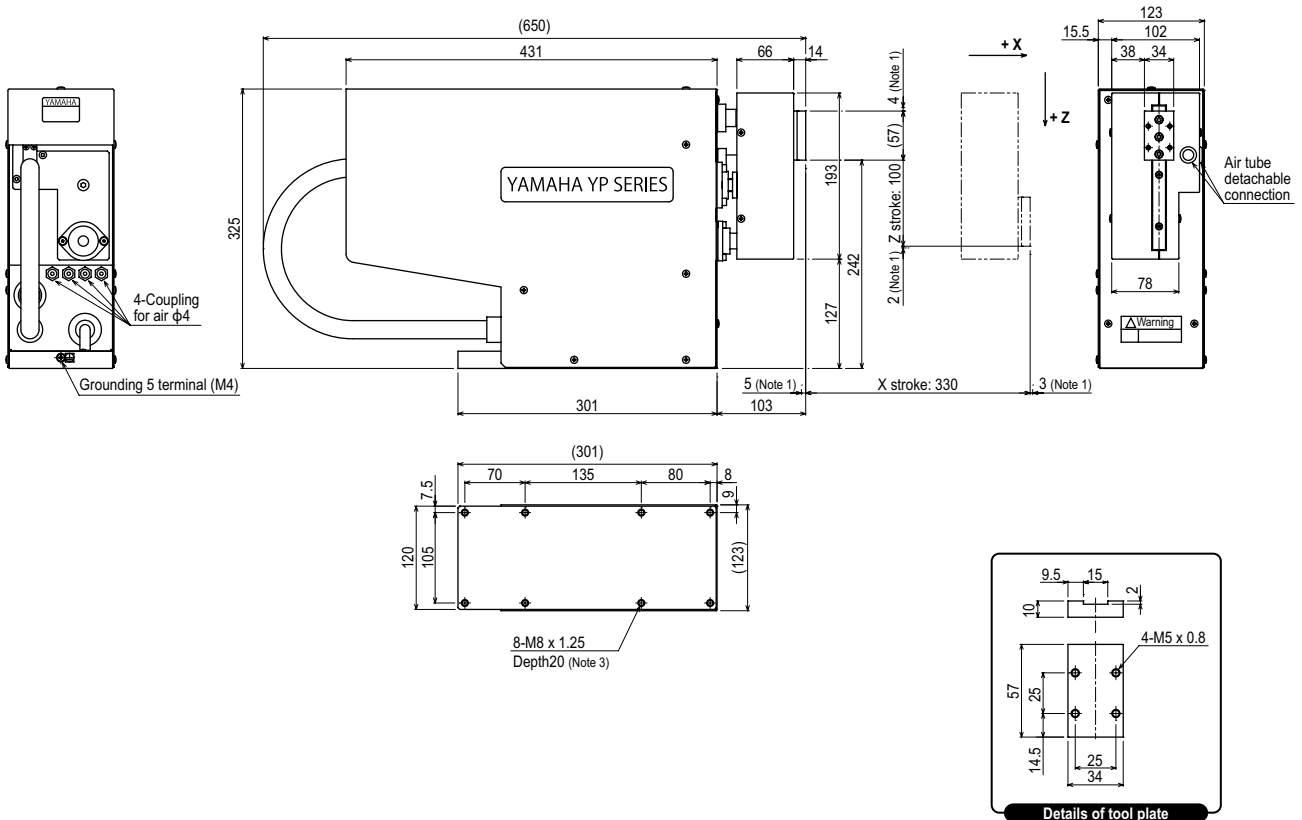
	X axis	Z axis
AC servo motor output (W)	200	200
Repeatability <sup>Note 1</sup> (mm)	+/-0.02	+/-0.05
Drive system	Ball screw φ15	Timing belt
Deceleration ratio (mm)	Equivalent to lead 20	Equivalent to lead 25
Maximum speed <sup>Note 2</sup> (mm/sec)	1500	1500
Moving range (mm)	330	100
Cycle time (sec)	0.57 <sup>Note 3</sup> , 0.78 <sup>Note 4</sup>	
Maximum payload (kg)	3	
Robot cable length (m)	Standard: 3.5 Option: 5,10	
Weight (kg)	21	

Note 1. Positioning repeatability precision in a single swing when residual vibration is stabilized (variable depending on the load and stroke).  
 Note 2. When the moving stroke is short, the maximum speed may not be reached.  
 Note 3. Reciprocating time in vertical direction (50mm) and longitudinal direction (150mm) with the arch amount of 50 (when executing rough-positioning arch motion with 1kg load).  
 Note 4. Reciprocating time in vertical direction (25mm) and longitudinal direction (300mm) with the arch amount of 25 (when executing rough-positioning arch motion with 1kg load).

## Controller

Controller	Power consumption (VA)	Operating method
RCX320 RCX222	500	Programming / I/O point trace / Remote command / Operation using RS-232C communication

## YP320X



Note 1. Distance to mechanical stopper.  
 Note 2. Return-to-origin on the YP320X is by absolute reset. So the origin position must be set the first time (making initial settings) but after that is not required.  
 Note 3. Do not use bolts longer than 20mm (robot bottom plate thickness).